

Daniel Sanchez Aranguren

List of Publications by Year in descending order

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#	ARTICLE	IF	CITATIONS
1	Tethered Tool Manipulation Planning With Cable Maneuvering. IEEE Robotics and Automation Letters, 2020, 5, 2777-2784.	5.1	13
2	Teaching a robot to use electric tools with regrasp planning. CAAI Transactions on Intelligence Technology, 2019, 4, 54-63.	8.1	11
3	Towards Tethered Tool Manipulation Planning with the Help of a Tool Balancer. Robotics, 2020, 9, 11.	3.5	5
4	Regrasp Planning Considering Bipedal Stability Constraints. , 2018, , .		3
5	Re-posing Objects Considering Bipedal Stability Constraints: An Approach for Stability Preservation During Humanoid Manipulation. International Journal of Humanoid Robotics, 2020, 17, 2050005.	1.1	2