

# Xiuguang Song

## List of Publications by Year in descending order

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Version: 2024-02-01

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#	ARTICLE	IF	CITATIONS
1	Augmented Multiple Vehiclesâ€™ Trajectories Extraction Under Occlusions With Roadside LiDAR Data. IEEE Sensors Journal, 2021, 21, 21921-21930.	2.4	13
2	Road Surface Defects Detection Based on IMU Sensor. IEEE Sensors Journal, 2021, , 1-1.	2.4	7
3	Background Filtering and Object Detection With a Stationary LiDAR Using a Layer-Based Method. IEEE Access, 2020, 8, 184426-184436.	2.6	11
4	Automatic ground points filtering of roadside LiDAR data using a channel-based filtering algorithm. Optics and Laser Technology, 2019, 115, 374-383.	2.2	34