Long Wang

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/287361/publications.pdf Version: 2024-02-01



#	Article	IF	CITATIONS
1	A Survey on Visual Surveillance of Object Motion and Behaviors. IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews, 2004, 34, 334-352.	3.3	1,666
2	Finite-Time Consensus Problems for Networks of Dynamic Agents. IEEE Transactions on Automatic Control, 2010, 55, 950-955.	3.6	899
3	Finite-time formation control for multi-agent systems. Automatica, 2009, 45, 2605-2611.	3.0	774
4	Asynchronous Consensus in Continuous-Time Multi-Agent Systems With Switching Topology and Time-Varying Delays. IEEE Transactions on Automatic Control, 2008, 53, 1804-1816.	3.6	626
5	Recent Advances in Consensus of Multi-Agent Systems: A Brief Survey. IEEE Transactions on Industrial Electronics, 2017, 64, 4972-4983.	5.2	582
6	Reputation-based partner choice promotes cooperation in social networks. Physical Review E, 2008, 78, 026117.	0.8	517
7	Consensus control for a class of networks of dynamic agents. International Journal of Robust and Nonlinear Control, 2007, 17, 941-959.	2.1	466
8	Group consensus in multi-agent systems with switching topologies and communication delays. Systems and Control Letters, 2010, 59, 340-348.	1.3	421
9	Average consensus in networks of dynamic agents with switching topologies and multiple time-varying delays. Systems and Control Letters, 2008, 57, 175-183.	1.3	419
10	Necessary and sufficient conditions for containment control of networked multi-agent systems. Automatica, 2012, 48, 1415-1422.	3.0	370
11	Consensus of Multi-Agent Systems in Directed Networks With Nonuniform Time-Varying Delays. IEEE Transactions on Automatic Control, 2009, 54, 1607-1613.	3.6	344
12	State consensus for multi-agent systems with switching topologies and time-varying delays. International Journal of Control, 2006, 79, 1277-1284.	1.2	327
13	Imitation dynamics of vaccination behaviour on social networks. Proceedings of the Royal Society B: Biological Sciences, 2011, 278, 42-49.	1.2	326
14	Consensus of heterogeneous multi-agent systems. IET Control Theory and Applications, 2011, 5, 1881-1888.	1.2	311
15	Promotion of cooperation induced by appropriate payoff aspirations in a small-world networked game. Physical Review E, 2008, 77, 017103.	0.8	303
16	Consensus of Hybrid Multi-Agent Systems. IEEE Transactions on Neural Networks and Learning Systems, 2018, 29, 1359-1365.	7.2	299
17	The fundamental advantages of temporal networks. Science, 2017, 358, 1042-1046.	6.0	287
18	Controllability of a Leader–Follower Dynamic Network With Switching Topology. IEEE Transactions on Automatic Control, 2008, 53, 1009-1013.	3.6	262

#	Article	IF	CITATIONS
19	Sampled-Data Based Consensus of Continuous-Time Multi-Agent Systems With Time-Varying Topology. IEEE Transactions on Automatic Control, 2011, 56, 1226-1231.	3.6	255
20	Consensus protocols for discrete-time multi-agent systems with time-varying delays. Automatica, 2008, 44, 2577-2582.	3.0	247
21	Finite-time consensus of heterogeneous multi-agent systems with and without velocity measurements. Systems and Control Letters, 2012, 61, 871-878.	1.3	242
22	Controllability and stabilizability of switched linear-systems. Systems and Control Letters, 2003, 48, 135-155.	1.3	237
23	Leader-following formation control of multiple mobile vehicles. IET Control Theory and Applications, 2007, 1, 545-552.	1.2	219
24	Stability Analysis for Continuous-Time Positive Systems With Time-Varying Delays. IEEE Transactions on Automatic Control, 2010, 55, 1024-1028.	3.6	217
25	Consensus problems for high-dimensional multi-agent systems. IET Control Theory and Applications, 2007, 1, 830-837.	1.2	194
26	Partner switching stabilizes cooperation in coevolutionary prisoner's dilemma. Physical Review E, 2009, 79, 036101.	0.8	187
27	Workload-based multi-task scheduling in cloud manufacturing. Robotics and Computer-Integrated Manufacturing, 2017, 45, 3-20.	6.1	185
28	Containment control of heterogeneous multi-agent systems. International Journal of Control, 2014, 87, 1-8.	1.2	179
29	Containment control for second-order multi-agent systems with time-varying delays. Systems and Control Letters, 2014, 67, 24-31.	1.3	173
30	Robust fault detection with missing measurements. International Journal of Control, 2008, 81, 804-819.	1.2	171
31	Necessary and sufficient conditions for solving consensus problems of doubleâ€integrator dynamics via sampled control. International Journal of Robust and Nonlinear Control, 2010, 20, 1706-1722.	2.1	164
32	Stabilization of switched linear systems with time-delay in detection of switching signal. Journal of Mathematical Analysis and Applications, 2005, 305, 277-290.	0.5	160
33	Evolution of in-group favoritism. Scientific Reports, 2012, 2, 460.	1.6	160
34	Group consensus of multi-agent systems with directed information exchange. International Journal of Systems Science, 2012, 43, 334-348.	3.7	159
35	Evolutionary Prisoner's Dilemma on heterogeneous Newman-Watts small-world network. European Physical Journal B, 2007, 56, 367-372.	0.6	156
36	Evolution of Cooperation on Stochastic Dynamical Networks. PLoS ONE, 2010, 5, e11187.	1.1	155

#	Article	IF	CITATIONS
37	Virtual leader approach to coordinated control of multiple mobile agents with asymmetric interactions. Physica D: Nonlinear Phenomena, 2006, 213, 51-65.	1.3	154
38	Universality of weak selection. Physical Review E, 2010, 82, 046106.	0.8	154
39	Stability Analysis of Positive Systems With Bounded Time-Varying Delays. IEEE Transactions on Circuits and Systems II: Express Briefs, 2009, 56, 600-604.	2.2	150
40	Consensus for multi-agent systems with inherent nonlinear dynamics under directed topologies. Systems and Control Letters, 2013, 62, 152-162.	1.3	148
41	Finite-time information consensus for multi-agent systems with fixed and switching topologies. Physica D: Nonlinear Phenomena, 2009, 238, 1550-1560.	1.3	140
42	Containment of linear multi-agent systems under general interaction topologies. Systems and Control Letters, 2012, 61, 528-534.	1.3	138
43	Consensus of linear multi-agent systems via event-triggered control. International Journal of Control, 2014, 87, 1243-1251.	1.2	138
44	Event-Based Second-Order Consensus Control for Multi-Agent Systems via Synchronous Periodic Event Detection. IEEE Transactions on Automatic Control, 2015, 60, 2452-2457.	3.6	134
45	Leader-Following Consensus for Linear and Lipschitz Nonlinear Multiagent Systems With Quantized Communication. IEEE Transactions on Cybernetics, 2017, 47, 1970-1982.	6.2	128
46	Necessary and Sufficient Conditions for Controllability and Observability of Switched Impulsive Control Systems. IEEE Transactions on Automatic Control, 2004, 49, 960-966.	3.6	127
47	Empirical analysis of online social networks in the age of Web 2.0. Physica A: Statistical Mechanics and Its Applications, 2008, 387, 675-684.	1.2	127
48	Social dilemmas in an online social network: The structure and evolution of cooperation. Physics Letters, Section A: General, Atomic and Solid State Physics, 2007, 371, 58-64.	0.9	124
49	Consensus of heterogeneous multi-agent systems without velocity measurements. International Journal of Control, 2012, 85, 906-914.	1.2	123
50	Second-order consensus of hybrid multi-agent systems. Systems and Control Letters, 2019, 125, 51-58.	1.3	123
51	Consensus of Switched Multiagent Systems. IEEE Transactions on Circuits and Systems II: Express Briefs, 2016, 63, 314-318.	2.2	121
52	Consensus of multi-agent systems based on sampled-data control. International Journal of Control, 2009, 82, 2193-2205.	1.2	120
53	Consensus in networked multi-agent systems via sampled control: Fixed topology case. , 2009, , .		120
54	LMI approach to L2-gain analysis and control synthesis of uncertain switched systems. IET Control Theory and Applications, 2004, 151, 21-28.	1.7	119

#	Article	IF	CITATIONS
55	Stabilization of Networked Control Systems with Data Packet Dropout and Transmission Delays: Continuous-Time Case. European Journal of Control, 2005, 11, 40-49.	1.6	118
56	Distributed consensus of heterogeneous multi-agent systems with fixed and switching topologies. International Journal of Control, 2012, 85, 1967-1976.	1.2	117
57	Controllability of switched linear systems. IEEE Transactions on Automatic Control, 2002, 47, 1401-1405.	3.6	115
58	Consensus seeking of high-order dynamic multi-agent systems with fixed and switching topologies. International Journal of Control, 2010, 83, 404-420.	1.2	111
59	Aspiration dynamics of multi-player games in finite populations. Journal of the Royal Society Interface, 2014, 11, 20140077.	1.5	110
60	Consensus problems in networks of agents with double-integrator dynamics and time-varying delays. International Journal of Control, 2009, 82, 1937-1945.	1.2	109
61	Interaction stochasticity supports cooperation in spatial Prisoner's dilemma. Physical Review E, 2008, 78, 051120.	0.8	108
62	Delay-dependent robust stability and Hâ^ž control for uncertain discrete-time switched systems with mode-dependent time delays. Applied Mathematics and Computation, 2007, 187, 1228-1237.	1.4	102
63	Evolution of Cooperation Driven by Reputation-Based Migration. PLoS ONE, 2012, 7, e35776.	1.1	101
64	Emergence of social cooperation in threshold public goods games with collective risk. Physical Review E, 2009, 80, 016101.	0.8	99
65	Stabilization of networked control systems with data packet dropout and network delays via switching system approach. , 2004, , .		96
66	Complex emergent dynamics of anisotropic swarms: Convergence vs oscillation. Chaos, Solitons and Fractals, 2006, 30, 875-885.	2.5	93
67	Delay-dependent robust stability and control for jump linear systems with delays. Systems and Control Letters, 2006, 55, 939-948.	1.3	92
68	On Controllability of Switched Linear Systems. IEEE Transactions on Automatic Control, 2008, 53, 796-801.	3.6	92
69	Social exclusion in finite populations. Physical Review E, 2015, 91, 042810.	0.8	92
70	Distributed Algorithms for Searching Generalized Nash Equilibrium of Noncooperative Games. IEEE Transactions on Cybernetics, 2019, 49, 2362-2371.	6.2	92
71	Consensus for heterogeneous multi-agent systems under fixed and switching topologies. Journal of the Franklin Institute, 2015, 352, 3670-3683.	1.9	91
72	Evolutionary dynamics on graphs: Efficient method for weak selection. Physical Review E, 2009, 79, 046707.	0.8	89

#	Article	IF	CITATIONS
73	Delay-dependent robust stability and stabilization for discrete-time switched systems with mode-dependent time-varying delays. Applied Mathematics and Computation, 2006, 180, 428-435.	1.4	88
74	How small are small mutation rates?. Journal of Mathematical Biology, 2012, 64, 803-827.	0.8	86
75	Sampled-data stabilisation of networked control systems with nonlinearity. IET Control Theory and Applications, 2005, 152, 609-614.	1.7	84
76	An LMI approach to networked control systems with data packet dropout and transmission delays. , 2004, , .		83
77	LQRâ€based optimal topology of leaderâ€following consensus. International Journal of Robust and Nonlinear Control, 2015, 25, 3404-3421.	2.1	83
78	Reachability realization and stabilizability of switched linear discrete-time systems. Journal of Mathematical Analysis and Applications, 2003, 280, 209-220.	0.5	81
79	Moving formation convergence of a group of mobile robots via decentralised information feedback. International Journal of Systems Science, 2009, 40, 1019-1027.	3.7	81
80	A new approach to consensus problems in discrete-time multiagent systems with time-delays. Science in China Series F: Information Sciences, 2007, 50, 625-635.	1.1	80
81	On stability of a class of switched nonlinear systems. Automatica, 2013, 49, 305-307.	3.0	80
82	Coordinated collective motion in a motile particle group with a leader. Physica A: Statistical Mechanics and Its Applications, 2005, 351, 211-226.	1.2	79
83	Vision-Based Target Tracking and Collision Avoidance for Two Autonomous Robotic Fish. IEEE Transactions on Industrial Electronics, 2009, 56, 1401-1410.	5.2	78
84	Evolutionary dynamics with game transitions. Proceedings of the National Academy of Sciences of the United States of America, 2019, 116, 25398-25404.	3.3	78
85	Evolution of cooperation on temporal networks. Nature Communications, 2020, 11, 2259.	5.8	78
86	Imperfect Vaccine Aggravates the Long-Standing Dilemma of Voluntary Vaccination. PLoS ONE, 2011, 6, e20577.	1.1	78
87	Leader–Follower Flocking of Multiple Robotic Fish. IEEE/ASME Transactions on Mechatronics, 2015, 20, 1372-1383.	3.7	77
88	Fuzzy-Logic-Based Terrain Identification with Multisensor Fusion for Transtibial Amputees. IEEE/ASME Transactions on Mechatronics, 2015, 20, 618-630.	3.7	77
89	On the Design of a Powered Transtibial Prosthesis With Stiffness Adaptable Ankle and Toe Joints. IEEE Transactions on Industrial Electronics, 2014, 61, 4797-4807.	5.2	76
90	Constrained Control of Positive Discrete-Time Systems With Delays. IEEE Transactions on Circuits and Systems II: Express Briefs, 2008, 55, 193-197.	2.2	75

#	Article	IF	CITATIONS
91	Locomotion Mode Classification Using a Wearable Capacitive Sensing System. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2013, 21, 744-755.	2.7	74
92	Self-organized motion in anisotropic swarms. Journal of Control Theory and Applications, 2003, 1, 77-81.	0.8	73
93	Coevolutionary dynamics of opinions and networks: From diversity to uniformity. Physical Review E, 2008, 78, 016104.	0.8	73
94	Effects of heterogeneous wealth distribution on public cooperation with collective risk. Physical Review E, 2010, 82, 016102.	0.8	73
95	Walk the Walk: A Lightweight Active Transtibial Prosthesis. IEEE Robotics and Automation Magazine, 2015, 22, 80-89.	2.2	73
96	A Noncontact Capacitive Sensing System for Recognizing Locomotion Modes of Transtibial Amputees. IEEE Transactions on Biomedical Engineering, 2014, 61, 2911-2920.	2.5	72
97	On Synchronization of Dynamical Systems Over Directed Switching Topologies: An Algebraic and Geometric Perspective. IEEE Transactions on Automatic Control, 2020, 65, 5083-5098.	3.6	72
98	Linear matrix inequality approach to quadratic stabilisation of switched systems. IET Control Theory and Applications, 2004, 151, 289-294.	1.7	70
99	Controllability of multi-agent systems based on agreement protocols. Science in China Series F: Information Sciences, 2009, 52, 2074-2088.	1.1	70
100	Finite-Time Consensus in Networks of Integrator-Like Dynamic Agents With Directional Link Failure. IEEE Transactions on Automatic Control, 2014, 59, 756-762.	3.6	68
101	Swarming behavior of multi-agent systems. Journal of Control Theory and Applications, 2004, 2, 313-318.	0.8	67
102	Consensus of multiple doubleâ€integrator agents with intermittent measurement. International Journal of Robust and Nonlinear Control, 2010, 20, 1140-1155.	2.1	67
103	Probabilistic interconnection between interdependent networks promotes cooperation in the public goods game. Journal of Statistical Mechanics: Theory and Experiment, 2012, 2012, P11017.	0.9	67
104	Prisoner's Dilemma on community networks. Physica A: Statistical Mechanics and Its Applications, 2007, 378, 512-518.	1.2	66
105	Win-Stay-Lose-Learn Promotes Cooperation in the Spatial Prisoner's Dilemma Game. PLoS ONE, 2012, 7, e30689.	1.1	65
106	Adaptive task assignment for multiple mobile robots via swarm intelligence approach. Robotics and Autonomous Systems, 2007, 55, 572-588.	3.0	64
107	Social tolerance allows cooperation to prevail in an adaptive environment. Physical Review E, 2009, 80, 051104.	0.8	64
108	Controllability of switching networks of multiâ€agent systems. International Journal of Robust and Nonlinear Control, 2012, 22, 630-644.	2.1	63

#	Article	IF	CITATIONS
109	Decentralized stabilizability of multi-agent systems under fixed and switching topologies. Systems and Control Letters, 2013, 62, 438-446.	1.3	63
110	Interactive diversity promotes the evolution of cooperation in structured populations. New Journal of Physics, 2016, 18, 103007.	1.2	63
111	Aspiration-based learning promotes cooperation in spatial prisoner's dilemma games. Europhysics Letters, 2011, 94, 60002.	0.7	62
112	Quadratic stabilization of switched systems. International Journal of Systems Science, 2005, 36, 395-404.	3.7	61
113	Geometric Optimization of Relative Link Lengths for Biomimetic Robotic Fish. , 2007, 23, 382-386.		61
114	Promotion of cooperation induced by the interplay between structure and game dynamics. Physica A: Statistical Mechanics and Its Applications, 2007, 383, 651-659.	1.2	61
115	Partner selections in public goods games with constant group size. Physical Review E, 2009, 80, 026121.	0.8	60
116	Controllability of multiâ€agent systems under directed topology. International Journal of Robust and Nonlinear Control, 2017, 27, 4333-4347.	2.1	60
117	Opinion dynamics in social networks with stubborn agents: An issue-based perspective. Automatica, 2018, 96, 213-223.	3.0	60
118	Expectation-driven migration promotes cooperation by group interactions. Physical Review E, 2012, 85, 066104.	0.8	59
119	Consensus of Multiagent Systems With Distance-Dependent Communication Networks. IEEE Transactions on Neural Networks and Learning Systems, 2017, 28, 2712-2726.	7.2	59
120	Controllability and observability of a class of linear impulsive systems. Journal of Mathematical Analysis and Applications, 2005, 304, 336-355.	0.5	58
121	Consensus of high-order dynamic multi-agent systems with switching topology and time-varying delays. Journal of Control Theory and Applications, 2010, 8, 52-60.	0.8	58
122	Evolutionary dynamics of general group interactions in structured populations. Physical Review E, 2016, 93, 022407.	0.8	57
123	Consensus problems in discrete-time multiagent systems with fixed topology. Journal of Mathematical Analysis and Applications, 2006, 322, 587-598.	0.5	56
124	Turning Control of a Multilink Biomimetic Robotic Fish. , 2008, 24, 201-206.		56
125	Finite-time weighted average consensus with respect to a monotonic function and its application. Systems and Control Letters, 2011, 60, 718-725.	1.3	56
126	Controllability of heterogeneous multi-agent systems under directed and weighted topology. International Journal of Control, 2016, 89, 1009-1024.	1.2	56

#	Article	IF	CITATIONS
127	Development of an artificial fish-like robot and its application in cooperative transportation. Control Engineering Practice, 2008, 16, 569-584.	3.2	55
128	Connectivity preservation for multi-agent rendezvous with link failure. Automatica, 2012, 48, 25-35.	3.0	55
129	Stabilization of networked control systems with time-varying network-induced delay. , 2004, , .		54
130	Asynchronous Periodic Edge-Event Triggered Control for Double-Integrator Networks With Communication Time Delays. IEEE Transactions on Cybernetics, 2018, 48, 675-688.	6.2	54
131	Consensus in networked multi-agent systems via sampled control: Switching topology case. , 2009, , .		53
132	Finite-time consensus for stochastic multi-agent systems. International Journal of Control, 2011, 84, 1644-1652.	1.2	53
133	Consensus of multiple dynamic agents with sampled information. IET Control Theory and Applications, 2010, 4, 945-956.	1.2	52
134	Passive dynamic walking with flat feet and ankle compliance. Robotica, 2010, 28, 413-425.	1.3	52
135	Impact of generalized benefit functions on the evolution of cooperation in spatial public goods games with continuous strategies. Physical Review E, 2012, 85, 066133.	0.8	52
136	Evolutionary dynamics of N-person snowdrift game. Physics Letters, Section A: General, Atomic and Solid State Physics, 2015, 379, 2922-2934.	0.9	52
137	Angle-based shape determination theory of planar graphs with application to formation stabilization. Automatica, 2019, 105, 117-129.	3.0	52
138	Flocking of multi-agent systems with a dynamic virtual leader. International Journal of Control, 2009, 82, 43-58.	1.2	51
139	A novel group consensus protocol for heterogeneous multi-agent systems. International Journal of Control, 2015, 88, 2347-2353.	1.2	51
140	Asynchronous consensus of continuous-time multi-agent systems with intermittent measurements. International Journal of Control, 2010, 83, 552-562.	1.2	50
141	Aspiration dynamics in structured population acts as if in a well-mixed one. Scientific Reports, 2015, 5, 8014.	1.6	50
142	Periodic Event-Triggered Consensus With Quantization. IEEE Transactions on Circuits and Systems II: Express Briefs, 2016, 63, 406-410.	2.2	50
143	Controllability of multi-agent systems with directed and weighted signed networks. Systems and Control Letters, 2018, 116, 47-55.	1.3	50
144	Mechanical design and motion control of a biomimetic robotic dolphin. Advanced Robotics, 2007, 21, 499-513.	1.1	49

#	Article	IF	CITATIONS
145	Dolphin-like propulsive mechanism based on an adjustable Scotch yoke. Mechanism and Machine Theory, 2009, 44, 603-614.	2.7	49
146	Diversity of contribution promotes cooperation in public goods games. Physica A: Statistical Mechanics and Its Applications, 2010, 389, 3166-3171.	1.2	49
147	Social influence promotes cooperation in the public goods game. Physica A: Statistical Mechanics and Its Applications, 2014, 413, 86-93.	1.2	48
148	Adaptive Slope Walking With a Robotic Transtibial Prosthesis Based on Volitional EMG Control. IEEE/ASME Transactions on Mechatronics, 2015, 20, 2146-2157.	3.7	48
149	Robust Hâ^ž Control and Stabilization of Uncertain Switched Linear Systems: A Multiple Lyapunov Functions Approach. Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME, 2006, 128, 696-700.	0.9	47
150	Design of switching sequences for controllability realization of switched linear systems. Automatica, 2007, 43, 662-668.	3.0	47
151	Promoting cooperation by local contribution under stochastic win-stay-lose-shift mechanism. Physica A: Statistical Mechanics and Its Applications, 2008, 387, 5609-5615.	1.2	47
152	Finite-time consensus of multiple second-order dynamic agents without velocity measurements. International Journal of Systems Science, 2014, 45, 579-588.	3.7	47
153	Adaptive role switching promotes fairness in networked ultimatum game. Scientific Reports, 2013, 3, 1550.	1.6	46
154	Spatial reciprocity in the evolution of cooperation. Proceedings of the Royal Society B: Biological Sciences, 2019, 286, 20190041.	1.2	46
155	Dynamic behavior of discrete-time multiagent systems with general communication structures. Physica A: Statistical Mechanics and Its Applications, 2006, 370, 364-380.	1.2	45
156	Individual's expulsion to nasty environment promotes cooperation in public goods games. Europhysics Letters, 2009, 88, 30011.	0.7	45
157	Reputation-based mutual selection rule promotes cooperation in spatial threshold public goods games. Chaos, Solitons and Fractals, 2013, 56, 181-187.	2.5	45
158	Periodic stabilizability of switched linear control systems. Automatica, 2009, 45, 2141-2148.	3.0	44
159	Cooperation enhanced by moderate tolerance ranges in myopically selective interactions. Physical Review E, 2009, 80, 046109.	0.8	43
160	Heterogeneity of allocation promotes cooperation in public goods games. Physica A: Statistical Mechanics and Its Applications, 2010, 389, 4708-4714.	1.2	43
161	A distributed algorithm for efficiently solving linear equations and its applications (Special Issue) Tj ETQq1 1	0.784314 rgB1 1.3	ſ∕Qverlock
162	Salient Object Detection via Two-Stage Graphs. IEEE Transactions on Circuits and Systems for Video Technology, 2019, 29, 1023-1037.	5.6	43

#	Article	IF	CITATIONS
163	Consensus for multiâ€agent systems under double integrator dynamics with timeâ€varying communication delays. International Journal of Robust and Nonlinear Control, 2012, 22, 1881-1898.	2.1	42
164	Influence of different initial distributions on robust cooperation in scale-free networks: A comparative study. Physics Letters, Section A: General, Atomic and Solid State Physics, 2008, 372, 1161-1167.	0.9	41
165	The coevolutionary ultimatum game. Europhysics Letters, 2011, 93, 48003.	0.7	41
166	Evolutionary dynamics of cooperation on interdependent networks with the Prisoner's Dilemma and Snowdrift Game. Europhysics Letters, 2014, 107, 58006.	0.7	41
167	Memory-based prisoner's dilemma on square lattices. Physica A: Statistical Mechanics and Its Applications, 2010, 389, 2390-2396.	1.2	40
168	Distributed event-triggered consensus for multi-agent systems with quantisation. International Journal of Control, 2015, 88, 1112-1122.	1.2	40
169	Multiagent Flocking With Angle-Based Formation Shape Control. IEEE Transactions on Automatic Control, 2020, 65, 817-823.	3.6	40
170	Moving Away from Nasty Encounters Enhances Cooperation in Ecological Prisoner's Dilemma Game. PLoS ONE, 2011, 6, e27669.	1.1	39
171	Cooperation with both synergistic and local interactions can be worse than each alone. Scientific Reports, 2014, 4, 5536.	1.6	39
172	Structural controllability of multi-agent systems with absolute protocol under fixed and switching topologies. Science China Information Sciences, 2017, 60, 1.	2.7	39
173	Leader-Following Formation Control of Multiple Mobile Robots. , 0, , .		38
174	Evolution of cooperation in multilevel public goods games with community structures. Europhysics Letters, 2011, 93, 58001.	0.7	38
175	A tale of two contribution mechanisms for nonlinear public goods. Scientific Reports, 2013, 3, 2021.	1.6	38
176	Coevolutionary dynamics of aspiration and strategy in spatial repeated public goods games. New Journal of Physics, 2018, 20, 063007.	1.2	38
177	Note on asymptotic stability of a class of neutral differential equations. Applied Mathematics Letters, 2006, 19, 949-953.	1.5	37
178	Partial state consensus for networks of second-order dynamic agents. Systems and Control Letters, 2010, 59, 775-781.	1.3	37
179	The coevolution of overconfidence and bluffing in the resource competition game. Scientific Reports, 2016, 6, 21104.	1.6	37
180	Equilibrium topology of multi-agent systems with two leaders: A zero-sum game perspective. Automatica, 2016, 73, 200-206.	3.0	37

#	Article	IF	CITATIONS
181	Distributed fixedâ€ŧime eventâ€ŧriggered consensus of linear multiâ€øgent systems with input delay. International Journal of Robust and Nonlinear Control, 2021, 31, 2526-2545.	2.1	37
182	Aggregation of Foraging Swarms. Lecture Notes in Computer Science, 2004, , 766-777.	1.0	37
183	Robust stability analysis and control synthesis for discrete-time uncertain switched systems. , 0, , .		36
184	Development of Multi-mode Biomimetic Robotic Fish Based on Central Pattern Generator. , 2006, , .		36
185	Design and CPG-based control of biomimetic robotic fish. IET Control Theory and Applications, 2009, 3, 281-293.	1.2	36
186	Effects of cost threshold and noise in spatial snowdrift games with fixed multi-person interactions. Europhysics Letters, 2010, 90, 38003.	0.7	36
187	Cooperation in group-structured populations with two layers of interactions. Scientific Reports, 2015, 5, 17446.	1.6	36
188	Some applications of small gain theorem to interconnected systems. Systems and Control Letters, 2004, 52, 263-273.	1.3	35
189	Consensus in leaderless networks of high-order-integrator agents. , 2009, , .		35
190	Evolutionary dynamics under interactive diversity. New Journal of Physics, 2017, 19, 103023.	1.2	35
191	Parameter Optimization of Simplified Propulsive Model for Biomimetic Robot Fish. , 0, , .		34
192	Stabilization of Switched Linear Systems with Time-Varying Delay in Switching Occurrence Detection. Circuits, Systems, and Signal Processing, 2007, 26, 361-377.	1.2	34
193	Similarity-based multimodality image fusion with shiftable complex directional pyramid. Pattern Recognition Letters, 2011, 32, 1544-1553.	2.6	34
194	consensus of second-order multi-agent systems with asymmetric delays. Systems and Control Letters, 2012, 61, 857-862.	1.3	34
195	Flocking of multi-agent systems with multiple groups. International Journal of Control, 2014, 87, 2573-2582.	1.2	34
196	Aspiration dynamics and the sustainability of resources in the public goods dilemma. Physics Letters, Section A: General, Atomic and Solid State Physics, 2016, 380, 1432-1436.	0.9	34
197	Observability of Multi-Agent Systems With Switching Topology. IEEE Transactions on Circuits and Systems II: Express Briefs, 2017, 64, 1317-1321.	2.2	34
198	Necessary and sufficient conditions for controllability of switched linear systems. , 2002, , .		33

#	Article	IF	CITATIONS
199	A framework for biomimetic robot fish's design and its realization. , 0, , .		33
200	Evolution of Interactions and Cooperation in the Spatial Prisoner's Dilemma Game. PLoS ONE, 2011, 6, e26724.	1.1	33
201	Necessary and sufficient asymptotic stability criterion for 2-D positive systems with time-varying state delays described by Roesser model. IET Control Theory and Applications, 2011, 5, 663-668.	1.2	33
202	Evolutionary dynamics on stochastic evolving networks for multiple-strategy games. Physical Review E, 2011, 84, 046111.	0.8	33
203	Adaptive and Bounded Investment Returns Promote Cooperation in Spatial Public Goods Games. PLoS ONE, 2012, 7, e36895.	1.1	33
204	Tolerance-based punishment in continuous public goods game. Physica A: Statistical Mechanics and Its Applications, 2012, 391, 4111-4120.	1.2	33
205	Online Distributed Optimization With Strongly Pseudoconvex-Sum Cost Functions. IEEE Transactions on Automatic Control, 2020, 65, 426-433.	3.6	33
206	Output feedback stabilisation of networked control systems via switched system approach. International Journal of Control, 2009, 82, 1665-1677.	1.2	32
207	Modelling and control of networked systems via jump system approach. IET Control Theory and Applications, 2008, 2, 535-541.	1.2	31
208	Containment control of switched multi-agent systems. International Journal of Control, 2015, 88, 2570-2577.	1.2	31
209	Coordinated Transport by Multiple Biomimetic Robotic Fish in Underwater Environment. IEEE Transactions on Control Systems Technology, 2007, 15, 658-671.	3.2	30
210	Switched system approach to stabilization of networked control systems. International Journal of Robust and Nonlinear Control, 2011, 21, 1925-1946.	2.1	30
211	Beyond pairwise strategy updating in the prisoner's dilemma game. Scientific Reports, 2012, 2, 740.	1.6	30
212	One step memory of group reputation is optimal to promote cooperation in public goods games. Europhysics Letters, 2013, 103, 30007.	0.7	30
213	Random allocation of pies promotes the evolution of fairness in the Ultimatum Game. Scientific Reports, 2014, 4, 4534.	1.6	30
214	Controllability of discrete-time multi-agent systems with directed topology and input delay. International Journal of Control, 2016, 89, 179-192.	1.2	30
215	Spatial structure favors cooperative behavior in the snowdrift game with multiple interactive dynamics. Physica A: Statistical Mechanics and Its Applications, 2017, 468, 299-306.	1.2	30
216	Evolution of cooperation with interactive identity and diversity. Journal of Theoretical Biology, 2018, 442, 149-157.	0.8	30

#	Article	IF	CITATIONS
217	Simple property of heterogeneous aspiration dynamics: Beyond weak selection. Physical Review E, 2018, 98, .	0.8	30
218	Controllability analysis of multi-agent systems with switching topology over finite fields. Science China Information Sciences, 2019, 62, 1.	2.7	30
219	Average Consensus in Directed Networks of Dynamic Agents with Time-Varying Communication Delays. , 2006, , .		29
220	Collective motion of a class of social foraging swarms. Chaos, Solitons and Fractals, 2008, 38, 277-292.	2.5	29
221	Development and target following of vision-based autonomous robotic fish. Robotica, 2009, 27, 1075-1089.	1.3	29
222	Cooperative box-pushing with multiple autonomous robotic fish in underwater environment. IET Control Theory and Applications, 2011, 5, 2015-2022.	1.2	29
223	Evolutionary multiplayer games on graphs with edge diversity. PLoS Computational Biology, 2019, 15, e1006947.	1.5	29
224	Coevolving agent strategies and network topology for the public goods games. European Physical Journal B, 2011, 80, 217-222.	0.6	28
225	Nash Equilibrium Topology of Multi-Agent Systems With Competitive Groups. IEEE Transactions on Industrial Electronics, 2017, 64, 4956-4966.	5.2	28
226	Cooperation guided by the coexistence of imitation dynamics and aspiration dynamics in structured populations. Europhysics Letters, 2017, 117, 48002.	0.7	28
227	Periodical stabilization of switched linear systems. Journal of Computational and Applied Mathematics, 2005, 181, 176-187.	1.1	27
228	Improved Overshoot Estimation in Pole Placements and Its Application in Observer-Based Stabilization for Switched Systems. IEEE Transactions on Automatic Control, 2006, 51, 1962-1966.	3.6	27
229	Exponential stability of switched systems with interval time-varying delay. IET Control Theory and Applications, 2009, 3, 1033-1040.	1.2	27
230	Evolution of global cooperation driven by risks. Physical Review E, 2012, 85, 056117.	0.8	27
231	Second-order leader-following consensus based on time and event hybrid-driven control. Systems and Control Letters, 2014, 74, 90-97.	1.3	27
232	Registration of images with affine geometric distortion based on Maximally Stable Extremal Regions and phase congruency. Image and Vision Computing, 2015, 36, 23-39.	2.7	27
233	Consensus of switched multi-agent systems with random networks. International Journal of Control, 2017, 90, 1113-1122.	1.2	27
234	Time scales in evolutionary game on adaptive networks. Physics Letters, Section A: General, Atomic and Solid State Physics, 2014, 378, 950-955.	0.9	26

#	Article	IF	CITATIONS
235	Energy-Efficient Braking Torque Control of Robotic Transtibial Prosthesis. IEEE/ASME Transactions on Mechatronics, 2017, 22, 149-160.	3.7	26
236	Conditional punishment is a double-edged sword in promoting cooperation. Scientific Reports, 2018, 8, 528.	1.6	26
237	Online Distributed Algorithms for Seeking Generalized Nash Equilibria in Dynamic Environments. IEEE Transactions on Automatic Control, 2021, 66, 2289-2296.	3.6	26
238	Output feedback control of networked systems. International Journal of Automation and Computing, 2004, 1, 26-34.	4.5	25
239	EFFECTS OF LEARNING ACTIVITY ON COOPERATION IN EVOLUTIONARY PRISONER'S DILEMMA GAME. International Journal of Modern Physics C, 2008, 19, 1377-1387.	0.8	25
240	PANTOE 1: Biomechanical design of powered ankle-foot prosthesis with compliant joints and segmented foot. , 2010, , .		25
241	Inertia in strategy switching transforms the strategy evolution. Physical Review E, 2011, 84, 066103.	0.8	25
242	Interpretations arising from Wrightian and Malthusian fitness under strong frequency dependent selection. Ecology and Evolution, 2013, 3, 1276-1280.	0.8	25
243	A new strategy for parameter optimization to improve phase-dependent locomotion mode recognition. Neurocomputing, 2015, 149, 585-593.	3.5	25
244	Multisensor video fusion based on higher order singular value decomposition. Information Fusion, 2015, 24, 54-71.	11.7	25
245	Understanding spatial public goods games on three-layer networks. New Journal of Physics, 2018, 20, 103030.	1.2	25
246	Coevolution of aspirations and cooperation in spatial prisoner's dilemma game. Journal of Statistical Mechanics: Theory and Experiment, 2015, 2015, P01032.	0.9	24
247	Evolutionary dynamics of N-person Hawk-Dove games. Scientific Reports, 2017, 7, 4800.	1.6	24
248	Distributed integralâ€ŧype eventâ€ŧriggered synchronization of multiagent systems. International Journal of Robust and Nonlinear Control, 2018, 28, 4175-4187.	2.1	24
249	Target controllability of multiagent systems under fixed and switching topologies. International Journal of Robust and Nonlinear Control, 2019, 29, 2725-2741.	2.1	24
250	Reputation-Based Conditional Interaction Supports Cooperation in Well-Mixed Prisoner's Dilemmas. PLoS ONE, 2012, 7, e36260.	1.1	24
251	On the controllability of multiple dynamic agents with fixed topology. , 2009, , .		23
252	Construction and Central Pattern Generator-Based Control of a Flipper-Actuated Turtle-Like Underwater Robot. Advanced Robotics, 2009, 23, 19-43.	1.1	23

#	Article	IF	CITATIONS
253	Evolutionary dynamics of public goods games with diverse contributions in finite populations. Physical Review E, 2010, 81, 056103.	0.8	23
254	Selective investment promotes cooperation in public goods game. Physica A: Statistical Mechanics and Its Applications, 2012, 391, 3924-3929.	1.2	23
255	Mixed strategy under generalized public goods games. Journal of Theoretical Biology, 2013, 334, 52-60.	0.8	23
256	Sampled-data consensus for multi-agent systems with quantised communication. International Journal of Control, 2015, 88, 413-428.	1.2	23
257	Evolutionary dynamics of fairness on graphs with migration. Journal of Theoretical Biology, 2015, 380, 103-114.	0.8	23
258	Voluntary vaccination dilemma with evolving psychological perceptions. Journal of Theoretical Biology, 2018, 439, 65-75.	0.8	23
259	Easily testable necessary and sufficient algebraic criteria for delay-independent stability of a class of neutral differential systems. Systems and Control Letters, 2008, 57, 165-174.	1.3	22
260	Consensus of multiple second-order agents without velocity measurements. , 2009, , .		22
261	A novel video fusion framework using surfacelet transform. Optics Communications, 2012, 285, 3032-3041.	1.0	22
262	Second-order consensus in time-delayed networks based on periodic edge-event driven control. Systems and Control Letters, 2016, 96, 37-44.	1.3	22
263	Friendship-based partner switching promotes cooperation in heterogeneous populations. Physica A: Statistical Mechanics and Its Applications, 2016, 443, 192-199.	1.2	22
264	Aspiration dynamics generate robust predictions in heterogeneous populations. Nature Communications, 2021, 12, 3250.	5.8	22
265	Complete characterization of strictly positive real regions and robust strictly positive real synthesis method. Science in China Series D: Earth Sciences, 2000, 43, 97-112.	0.9	21
266	Quadratic Stabilization of Uncertain Discrete-Time Switched Systems via Output Feedback. Circuits, Systems, and Signal Processing, 2005, 24, 733-751.	1.2	21
267	Evolutionary dynamics of synergistic and discounted group interactions in structured populations. Journal of Theoretical Biology, 2015, 377, 57-65.	0.8	21
268	Weak Rigidity Theory and Its Application to Formation Stabilization. SIAM Journal on Control and Optimization, 2018, 56, 2248-2273.	1.1	21
269	Stability of switched systems with time-varying delays: delay-dependent common Lyapunov functional approach. , 2006, , .		20
270	Controllability of Interconnected Systems via Switching Networks with a Leader. , 2006, , .		20

#	Article	IF	CITATIONS
271	Control and Coordination of Multiple Biomimetic Robotic Fish. IEEE Transactions on Control Systems Technology, 2007, 15, 176-183.	3.2	20
272	Group consensus in multi-agent systems with switching topologies. , 2009, , .		20
273	Effects of adaptive dynamical linking in networked games. Physical Review E, 2013, 88, 042128.	0.8	20
274	Average consensus of continuousâ€time multiâ€agent systems with quantized communication. International Journal of Robust and Nonlinear Control, 2014, 24, 3345-3371.	2.1	20
275	Controllability improvement for multi-agent systems: leader selection and weight adjustment. International Journal of Control, 2016, 89, 2008-2018.	1.2	20
276	Individual mobility promotes punishment in evolutionary public goods games. Scientific Reports, 2017, 7, 14015.	1.6	20
277	Controllability and observability of switched multi-agent systems. International Journal of Control, 2019, 92, 1742-1752.	1.2	20
278	An improved model-based control scheme for networked systems. , 0, , .		19
279	A new approach to consensus problems for discrete-time multiagent systems with time-delays. , 2006, ,		19
280	Elimination mechanism promotes cooperation in coevolutionary prisoner's dilemma games. Physica A: Statistical Mechanics and Its Applications, 2010, 389, 4081-4086.	1.2	19
281	Adaptive tag switching reinforces the coevolution of contingent cooperation and tag diversity. Journal of Theoretical Biology, 2013, 330, 45-55.	0.8	19
282	Effects of payoff-related velocity in the co-evolutionary snowdrift game. Physica A: Statistical Mechanics and Its Applications, 2014, 393, 304-311.	1.2	19
283	Coevolutionary dynamics of phenotypic diversity and contingent cooperation. PLoS Computational Biology, 2017, 13, e1005363.	1.5	19
284	Evolution of cooperation in a hierarchical society with corruption control. Journal of Theoretical Biology, 2018, 449, 60-72.	0.8	19
285	Robust stability of a class of polynomial families under nonlinearly correlated perturbations. Systems and Control Letters, 1997, 30, 25-30.	1.3	18
286	A switched system approach to stabilization of networked control systems. Journal of Control Theory and Applications, 2006, 4, 86-95.	0.8	18
287	Fast information sharing in networks of autonomous agents. , 2008, , .		18
288	Aspiration-Based Partner Switching Boosts Cooperation in Social Dilemmas. PLoS ONE, 2014, 9, e97866.	1.1	18

#	Article	IF	CITATIONS
289	Quadratic stabilisability of multi-agent systems under switching topologies. International Journal of Control, 2014, 87, 2657-2668.	1.2	18
290	Experimental implementation of distributed flocking algorithm for multiple robotic fish. Control Engineering Practice, 2014, 30, 1-11.	3.2	18
291	Evolution of cooperation on complex networks with synergistic and discounted group interactions. Europhysics Letters, 2015, 110, 60006.	0.7	18
292	Resource service sharing in cloud manufacturing based on the Gale–Shapley algorithm: advantages and challenge. International Journal of Computer Integrated Manufacturing, 0, , 1-13.	2.9	18
293	Cooperation induced by random sequential exclusion. Europhysics Letters, 2016, 114, 58001.	0.7	18
294	Distributed Algorithm for Solving Convex Inequalities. IEEE Transactions on Automatic Control, 2018, 63, 2670-2677.	3.6	18
295	A Wearable Plantar Pressure Measurement System: Design Specifications and First Experiments with an Amputee. Advances in Intelligent Systems and Computing, 2013, , 273-281.	0.5	18
296	Controllability of switched time-delay systems under constrained switching. Journal of Mathematical Analysis and Applications, 2003, 286, 397-421.	0.5	17
297	STABILITY ANALYSIS OF NETWORKED SYSTEMS WITH PACKET DROPOUT AND TRANSMISSION DELAYS: DISCRETE-TIME CASE. Asian Journal of Control, 2008, 7, 433-439.	1.9	17
298	Cooperative control for trajectory tracking of robotic fish. , 2009, , .		17
299	Modeling and gait selection of passivity-based seven-link bipeds with dynamic series of walking phases. Robotica, 2012, 30, 39-51.	1.3	17
300	Multisensor video fusion based on spatial–temporal salience detection. Signal Processing, 2013, 93, 2485-2499.	2.1	17
301	Climate collective risk dilemma with feedback of real-time temperatures. Europhysics Letters, 2014, 107, 60005.	0.7	17
302	Effects of toe stiffness on ankle kinetics in a robotic transtibial prosthesis during level-ground walking. Mechatronics, 2014, 24, 1254-1261.	2.0	17
303	Effects of partner choice and role assignation in the spatial ultimatum game. Europhysics Letters, 2015, 109, 40013.	0.7	17
304	Opinion Propagation Over Signed Networks: Models and Convergence Analysis. IEEE Transactions on Automatic Control, 2019, 64, 3431-3438.	3.6	17
305	Anderson's claim on fourth-order SPR synthesis is true. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 2001, 48, 506-509.	0.1	16
306	Persistent bounded disturbance rejection for impulsive systems. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 2003, 50, 785-788.	0.1	16

#	Article	IF	CITATIONS
307	Consensus Control for Networks of Dynamic Agents via Active Switching Topology. Lecture Notes in Computer Science, 2005, , 424-433.	1.0	16
308	Stabilization of NCSs: asynchronous partial transfer approach. , 0, , .		16
309	Stability and Oscillation of Swarm With Interaction Time Delays. Proceedings of the American Control Conference, 2007, , .	0.0	16
310	Bluffing promotes overconfidence on social networks. Scientific Reports, 2014, 4, 5491.	1.6	16
311	Topology selection for multi-agent systems with opposite leaders. Systems and Control Letters, 2016, 93, 43-49.	1.3	16
312	Energy cost for controlling complex networks with linear dynamics. Physical Review E, 2019, 99, 052305.	0.8	16
313	Evolution of fairness in the mixture of the Ultimatum Game and the Dictator Game. Physica A: Statistical Mechanics and Its Applications, 2019, 519, 319-325.	1.2	16
314	Social Power Evolution in Influence Networks With Stubborn Individuals. IEEE Transactions on Automatic Control, 2022, 67, 574-588.	3.6	16
315	Different Reactions to Adverse Neighborhoods in Games of Cooperation. PLoS ONE, 2012, 7, e35183.	1.1	16
316	On Hurwitz stable polynomials and strictly positive real transfer functions. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 2001, 48, 127-128.	0.1	15
317	Quadratic stability and stabilization of discrete-time switched systems with state delay. , 2004, , .		15
318	Consensus control for a class of networks of dynamic agents: switching topology. , 2006, , .		15
319	A Distributed Multi-Robot Cooperative Hunting Algorithm Based on Limit-cycle. , 2009, , .		15
320	Role of recommendation in spatial public goods games. Physica A: Statistical Mechanics and Its Applications, 2013, 392, 2038-2045.	1.2	15
321	Structural Controllability of Directed Signed Networks. IEEE Transactions on Control of Network Systems, 2021, 8, 1189-1200.	2.4	15
322	A tracking controller for motion coordination of multiple mobile robots. , 2005, , .		14
323	Coordinated Control of Multiple Interactive Dynamical Agents with Asymmetric Coupling Pattern and Switching Topology. , 2006, , .		14
324	Self-Organization of General Multi-Agent Systems with Complex Interactions. , 2006, , .		14

#	Article	IF	CITATIONS
325	Consensus of population systems with community structures. Physical Review E, 2008, 78, 051923.	0.8	14
326	Underwater target following with a vision-based autonomous robotic fish. , 2009, , .		14
327	Cooperative Multi-Robot Monocular-SLAM Using Salient Landmarks. , 2009, , .		14
328	Energetic efficiency and stability of dynamic bipedal walking gaits with different step lengths. , 2010, , .		14
329	EFFECTS OF FOOT SHAPE ON ENERGETIC EFFICIENCY AND DYNAMIC STABILITY OF PASSIVE DYNAMIC BIPED WITH UPPER BODY. International Journal of Humanoid Robotics, 2010, 07, 295-313.	0.6	14
330	Heterogenous allocation of chips promotes fairness in the Ultimatum Game. Europhysics Letters, 2015, 109, 68006.	0.7	14
331	Randomly biased investments and the evolution of public goods on interdependent networks. Physica A: Statistical Mechanics and Its Applications, 2017, 479, 542-550.	1.2	14
332	Controllability of Switching Signed Networks. IEEE Transactions on Circuits and Systems II: Express Briefs, 2020, 67, 1059-1063.	2.2	14
333	Multiplier design for extended strict positive realness and its applications. International Journal of Control, 2004, 77, 1493-1502.	1.2	13
334	Optimal design and motion control of biomimetic robotic fish. Science in China Series F: Information Sciences, 2008, 51, 535-549.	1.1	13
335	Geometric topology based cooperation for multiple robots in adversarial environments. Control Engineering Practice, 2008, 16, 1092-1100.	3.2	13
336	Does migration cost influence cooperation among success-driven individuals?. Chaos, Solitons and Fractals, 2012, 45, 1301-1308.	2.5	13
337	Multimodality image fusion by using both phase and magnitude information. Pattern Recognition Letters, 2013, 34, 185-193.	2.6	13
338	Cooperation induced by wise incentive allocation in spontaneous institution. Europhysics Letters, 2016, 115, 38002.	0.7	13
339	Evolution of cooperation in synergistically evolving dynamic interdependent networks: fundamental advantages of coordinated network evolution. New Journal of Physics, 2019, 21, 073057.	1.2	13
340	Integral-based event-triggered control for multi-agent systems with general linear dynamics. International Journal of Control, 2020, 93, 1005-1014.	1.2	13
341	Online Distributed Optimization With Nonconvex Objective Functions: Sublinearity of First-Order Optimality Condition-Based Regret. IEEE Transactions on Automatic Control, 2022, 67, 3029-3035.	3.6	13
342	Consensus Control for a class of Networks of Dynamic Agents: Fixed Topology. , 0,		12

342 Consensus Control for a class of Networks of Dynamic Agents: Fixed Topology. , 0, , .

#	Article	IF	CITATIONS
343	An adjustable scotch yoke mechanism for robotic dolphin. , 2007, , .		12
344	Flocking of Multi-Agent Systems with a Virtual Leader. , 2007, , .		12
345	Stabilization of planar discrete-time switched systems: Switched Lyapunov functional approach. Nonlinear Analysis: Hybrid Systems, 2008, 2, 1062-1068.	2.1	12
346	Stabilizability of networked control systems via packet-loss dependent output feedback controllers. , 2008, , .		12
347	Disturbance rejection of switched systems subject to actuator saturation. Transactions of the Institute of Measurement and Control, 2010, 32, 603-634.	1.1	12
348	Cautious strategy update promotes cooperation in spatial prisoner's dilemma game. Physica A: Statistical Mechanics and Its Applications, 2013, 392, 3640-3647.	1.2	12
349	Hunting for wealthy encounters promotes cooperation in spatial Prisoner's Dilemma games. European Physical Journal B, 2013, 86, 1.	0.6	12
350	Degree-based assignation of roles in ultimatum games on scale-free networks. Physica A: Statistical Mechanics and Its Applications, 2013, 392, 1885-1893.	1.2	12
351	Evolution of cooperation in lattice population with adaptive interaction intensity. Physica A: Statistical Mechanics and Its Applications, 2013, 392, 2046-2051.	1.2	12
352	The Increased Risk of Joint Venture Promotes Social Cooperation. PLoS ONE, 2013, 8, e63801.	1.1	12
353	Promote or hinder? The role of punishment in the emergence of cooperation. Journal of Theoretical Biology, 2015, 386, 69-77.	0.8	12
354	Quantised consensus of multi-agent systems with nonlinear dynamics. International Journal of Systems Science, 2015, 46, 2061-2071.	3.7	12
355	Rationality alters the rank between peer punishment and social exclusion. Europhysics Letters, 2018, 121, 38003.	0.7	12
356	Coevolution of nonlinear group interactions and strategies in well-mixed and structured populations. Journal of Theoretical Biology, 2018, 440, 32-41.	0.8	12
357	Evolution of global cooperation and ethnocentrism in group-structured populations. Physics Letters, Section A: General, Atomic and Solid State Physics, 2018, 382, 2027-2043.	0.9	12
358	Distributed adaptive Nash equilibrium seeking and disturbance rejection for noncooperative games of highâ€order nonlinear systems with input saturation and input delay. International Journal of Robust and Nonlinear Control, 2021, 31, 2827-2846.	2.1	12
359	Reachability and Controllability of Positive Linear Discrete-time Systems with Time-delays. Lecture Notes in Control and Information Sciences, 0, , 377-384.	0.6	11
360	Necessary and Sufficient Conditions for Controllability of Switched Impulsive Control Systems With Time Delay. , 2006, , .		11

#	Article	IF	CITATIONS
361	Packet-loss dependent controller design for networked control systems via switched system approach. , 2008, , .		11
362	Chaotic attractor generation and critical value analysis via switching approach. Chaos, Solitons and Fractals, 2009, 40, 2160-2169.	2.5	11
363	Emergence of parochial altruism in well-mixed populations. Physics Letters, Section A: General, Atomic and Solid State Physics, 2015, 379, 333-341.	0.9	11
364	Competitive diffusion in signed social networks: A game-theoretic perspective. Automatica, 2020, 112, 108656.	3.0	11
365	Self-organized motion in a class of anisotropic swarms: convergence vs oscillation. , 0, , .		10
366	Development and depth control of biomimetic robotic fish. , 2007, , .		10
367	The χâ€consensus problem of highâ€order multiâ€agent systems with fixed and switching topologies. Asian Journal of Control, 2008, 10, 246-253.	1.9	10
368	Formation Control of Heterogeneous Multi-Robot Systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2008, 41, 6596-6601.	0.4	10
369	Diversity of game strategies promotes the evolution of cooperation in public goods games. Europhysics Letters, 2010, 90, 68005.	0.7	10
370	Adding compliant joints and segmented foot to bio-inspired below-knee exoskeleton. , 2011, , .		10
371	Video fusion performance evaluation based on structural similarity and human visual perception. Signal Processing, 2012, 92, 912-925.	2.1	10
372	A realtime locomotion mode recognition method for an active pelvis orthosis. , 2015, , .		10
373	Quantised consensus of heterogeneous multiâ€agent systems. IET Control Theory and Applications, 2015, 9, 2553-2560.	1.2	10
374	Adaptive play stabilizes cooperation in continuous public goods games. Physica A: Statistical Mechanics and Its Applications, 2018, 495, 427-435.	1.2	10
375	Controllability of multi-agent systems with periodically switching topologies and switching leaders. International Journal of Control, 2018, 91, 1023-1033.	1.2	10
376	A distributed algorithm for solving mixed equilibrium problems. Automatica, 2019, 105, 246-253.	3.0	10
377	ENERGY COST FOR TARGET CONTROL OF COMPLEX NETWORKS. International Journal of Modeling, Simulation, and Scientific Computing, 2019, 22, 1950022.	0.9	10
378	Hybrid event- and time-triggered control for double-integrator heterogeneous networks. Science China Information Sciences, 2019, 62, 1.	2.7	10

#	Article	IF	CITATIONS
379	Evolution of cooperation in a conformity-driven evolving dynamic social network. Applied Mathematics and Computation, 2020, 379, 125251.	1.4	10
380	Evolution of state-dependent strategies in stochastic games. Journal of Theoretical Biology, 2021, 527, 110818.	0.8	10
381	Obstacle Avoidance and Path Planning Based on Flow Field for Biomimetic Robotic Fish. Lecture Notes in Computer Science, 2005, , 857-860.	1.0	10
382	Vertex results for uncertain systems. International Journal of Systems Science, 1994, 25, 541-549.	3.7	9
383	An LMI approach to persistent bounded disturbance rejection for uncertain impulsive systems. , 0, , .		9
384	Controllability of linear descriptor systems. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 2003, 50, 455-460.	0.1	9
385	Stabilizing discrete-time switched systems via observer-based static output feedback. , 0, , .		9
386	Flexible Formation Control for Obstacle Avoidance Based on Numerical Flow Field. , 2006, , .		9
387	Tracking Control for Groups of Mobile Agents. Proceedings of the American Control Conference, 2007, , .	0.0	9
388	Development of multiple robotic fish cooperation platform. International Journal of Systems Science, 2007, 38, 257-268.	3.7	9
389	CONTROLLABILITY OF A CLASS OF SINGULAR SYSTEMS. Asian Journal of Control, 2006, 8, 424-432.	1.9	9
390	Asynchronous Rendezvous Analysis via Set-valued Consensus Theory. SIAM Journal on Control and Optimization, 2012, 50, 196-221.	1.1	9
391	A fuzzy logic based terrain identification approach to prosthesis control using multi-sensor fusion. , 2013, , .		9
392	Do not aim too high nor too low: Moderate expectation-based group formation promotes public cooperation on networks. Physica A: Statistical Mechanics and Its Applications, 2014, 410, 259-267.	1.2	9
393	Speed of evolution on graphs. Physical Review E, 2015, 92, 062124.	0.8	9
394	A novel hybrid decision-making model for team building in cloud service environment. International Journal of Computer Integrated Manufacturing, 2019, 32, 1134-1153.	2.9	9
395	Finite-Time Coordination Under State-Dependent Communication Graphs With Inherent Links. IEEE Transactions on Circuits and Systems II: Express Briefs, 2019, 66, 968-972.	2.2	9
396	Robust strong stabilizability of interval plants: It suffices to check two vertices. Systems and Control Letters, 1995, 26, 133-136.	1.3	8

#	Article	IF	CITATIONS
397	Stability and stabilization of switched descriptor systems under arbitrary switching. , 0, , .		8
398	New results on quadratic stabilization of switched linear systems with polytopic uncertainties. IMA Journal of Mathematical Control and Information, 2005, 22, 441-452.	1.1	8
399	Flocking Control of Groups of Mobile Autonomous Agents Via Local Feedback. , 0, , .		8
400	Commuting and stable feedback design for switched linear systems. Nonlinear Analysis: Theory, Methods & Applications, 2006, 64, 197-216.	0.6	8
401	Modular design and motion control of reconfigurable robotic fish. , 2007, , .		8
402	Robust Stabilization of Discrete-time Switched Uncertain Systems Subject to Actuator Saturation. Proceedings of the American Control Conference, 2007, , .	0.0	8
403	General distributed protocols for finite-time consensus of multi-agent systems. , 2009, , .		8
404	Adding segmented feet to passive dynamic walkers. , 2010, , .		8
405	Non-contact capacitance sensing for continuous locomotion mode recognition: Design specifications and experiments with an amputee. , 2013, 2013, 6650410.		8
406	Evolution of stinginess and generosity in finite populations. Journal of Theoretical Biology, 2017, 421, 71-80.	0.8	8
407	Three-Dimensional Leaderless Flocking Control of Large-Scale Small Unmanned Aerial Vehicles. IFAC-PapersOnLine, 2017, 50, 6208-6213.	0.5	8
408	Controllability and observability of multi-agent systems with heterogeneous and switching topologies. International Journal of Control, 2020, 93, 437-448.	1.2	8
409	The Study on Credit Risk Warning of Regional Listed Companies in China Based on Logistic Model. Discrete Dynamics in Nature and Society, 2021, 2021, 1-8.	0.5	8
410	Stability of polytopic polynomial matrices. , 2001, , .		7
411	Robust SPR synthesis for low-order polynomial segments and interval polynomials. , 2001, , .		7
412	Exponential convergence estimates for neural networks with multiple delays. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 2002, 49, 1829-1832.	0.1	7
413	Output controllability of switched linear systems. , 2003, , .		7
414	An Adaptive Task Assignment Method for Multiple Mobile Robots via Swarm Intelligence Approach. , 0, ,		7

#	Article	IF	CITATIONS
415	Consensus behavior of agents in networked systems under general communication topologies. , 2006, , .		7
416	Consensus Behavior of Agents in Networked Systems under General Communication Topologies. , 2006, , .		7
417	Necessary and sufficient conditions for stabilization of discrete-time planar switched systems. Nonlinear Analysis: Theory, Methods & Applications, 2006, 65, 1039-1049.	0.6	7
418	Dynamics and Control of Turning Maneuver for Biomimetic Robotic Fish. , 2006, , .		7
419	Formation Control of Multiple Biomimetic Robotic Fish. , 2006, , .		7
420	Development of vision-based autonomous robotic fish and its application in water-polo-attacking task. , 2008, , .		7
421	Dynamic Analysis and Control Synthesis of a Link-Based Dolphin-Like Robot Capable of Three-Dimensional Movements. Advanced Robotics, 2009, 23, 1299-1313.	1.1	7
422	Effects of migration on the evolutionary game dynamics in finite populations with community structures. Physica A: Statistical Mechanics and Its Applications, 2010, 389, 67-78.	1.2	7
423	Coevolution with weights of names in structured language games. Physica A: Statistical Mechanics and Its Applications, 2010, 389, 5628-5634.	1.2	7
424	Robustness of Cooperation on Highly Clustered Scale-Free Networks. Chinese Physics Letters, 2010, 27, 030203.	1.3	7
425	Modeling and stability analysis of human normal walking with implications for the evolution of the foot. , 2010, , .		7
426	Controllability of discreteâ€ŧime multiagent systems with switching topology. International Journal of Robust and Nonlinear Control, 2018, 28, 2560-2573.	2.1	7
427	Evolution of cooperation driven by majority-pressure based interdependence. New Journal of Physics, 2018, 20, 083047.	1.2	7
428	Collective Behavior Analysis of a Class of Social Foraging Swarms. Lecture Notes in Computer Science, 2005, , 584-593.	1.0	7
429	Flocking Control of Multiple Interactive Dynamical Agents with Switching Topology via Local Feedback. Lecture Notes in Computer Science, 2005, , 604-613.	1.0	7
430	Dynamic Walking on Uneven Terrains with Passivity-Based Bipedal Robots. Lecture Notes in Electrical Engineering, 2011, , 187-199.	0.3	7
431	Learning enables adaptation in cooperation for multi-player stochastic games. Journal of the Royal Society Interface, 2020, 17, 20200639.	1.5	7
432	Evolutionary dynamics of zero-determinant strategies in repeated multiplayer games. Journal of Theoretical Biology, 2022, 549, 111209.	0.8	7

#	Article	IF	CITATIONS
433	Unified Approach to Robust Performance of a Class of Transfer Functions with Multilinearly Correlated Perturbations. Journal of Optimization Theory and Applications, 1998, 96, 709-721.	0.8	6
434	On strict positive realness of multilinearly parametrized interval systems. Science in China Series D: Earth Sciences, 1998, 41, 552-560.	0.9	6
435	Robustly stabilizing PID controllers for car steering systems. , 1998, , .		6
436	Robustness analysis and synthesis of SISO systems under both plant and controller perturbations. Systems and Control Letters, 2001, 42, 201-216.	1.3	6
437	Kharitonov-like theorems for robust performance of interval systems. Journal of Mathematical Analysis and Applications, 2003, 279, 430-441.	0.5	6
438	New results on the quadratic stabilization of switched linear systems. , 0, , .		6
439	Stabilization of networked control systems with transmission delays. , 0, , .		6
440	Controllability Implies Stabilizability for Discrete-Time Switched Linear Systems. Lecture Notes in Computer Science, 2005, , 667-682.	1.0	6
441	Robust stabilization of nonlinear sampled-data systems. , 0, , .		6
442	Optimized design and implementation of biomimetic robotic dolphin. , 2005, , .		6
443	Coordination of Multiple Dynamic Agents with Asymmetric Interactions. , 0, , .		6
444	Flocking of Multi-Vehicle Systems With A Leader. , 2006, , .		6
445	Consensus Problems of Multiagent Systems under Discrete Communication Structure. , 2006, , .		6
446	Controllability of a class of multi-agent systems with a leader. , 2006, , .		6
447	Learning from Human Cognition: Collaborative Localization for Vision-based Autonomous Robots. , 2006, , .		6
448	Dynamic Modeling of Three-Dimensional Swimming for Biomimetic Robotic Fish. , 2006, , .		6
449	STABILIZATION OF A COLLECTION OF LINEAR SYSTEMS WITH LIMITED INFORMATION. Asian Journal of Control, 2007, 9, 80-86.	1.9	6
450	Controllability of a Leader-Follower Dynamic Network with Interaction Time Delays. , 2008, , .		6

#	Article	IF	CITATIONS
451	Optimal mass distribution for a passive dynamic biped with upper body considering speed, efficiency and stability. , 2008, , .		6
452	Collective motion in non-reciprocal swarms. Journal of Control Theory and Applications, 2009, 7, 105-111.	0.8	6
453	Group penalty on the evolution of cooperation in spatial public goods games. Journal of Statistical Mechanics: Theory and Experiment, 2010, 2010, P12004.	0.9	6
454	Circle formation for anonymous mobile robots with order preservation. , 2012, , .		6
455	Evolutionary game dynamics of multi-agent cooperation driven by self-learning. , 2013, , .		6
456	Development and Implementation of Cloud Manufacturing: An Evolutionary Perspective. , 2013, , .		6
457	Promise of using surface EMG signals to volitionally control ankle joint position for powered transtibial prostheses. , 2014, 2014, 2545-8.		6
458	Finite-state control of a robotic transtibial prosthesis with motor-driven nonlinear damping behaviors for level ground walking. , 2014, , .		6
459	Non-fragility of multi-agent controllability. Science China Information Sciences, 2018, 61, 1.	2.7	6
460	Information Propagation Over Networks With Antagonistic Interactions: The Equilibrium Analysis. IEEE Transactions on Control of Network Systems, 2020, 7, 592-602.	2.4	6
461	Evolution of egalitarian social norm by resource management. PLoS ONE, 2020, 15, e0227902.	1.1	6
462	Coordinating Dual-Mode Biomimetic Robotic Fish in Box-Pushing Task. Lecture Notes in Computer Science, 2005, , 815-824.	1.0	6
463	Autonomous Evolution of High-Speed Quadruped Gaits Using Particle Swarm Optimization. Lecture Notes in Computer Science, 2009, , 259-270.	1.0	6
464	Controllability of switched linear discrete-time systems with time delay. , 0, , .		5
465	Algebraic Characterizations of Consensus Problems for Networked Dynamic Systems. , 0, , .		5
466	Development of a flipper propelled turtle-like underwater robot and its CPG-based control algorithm. , 2008, , .		5
467	Could feedback-based self-learning help solve networked Prisoner's Dilemma?. , 2009, , .		5
468	Social selection of game organizers promotes cooperation in spatial public goods games. Europhysics Letters, 2013, 102, 50006.	0.7	5

#	Article	IF	CITATIONS
469	A Hierarchical Control Scheme for Smooth Transitions between Level Ground and Ramps with a Robotic Transtibial Prosthesis. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 3527-3532.	0.4	5
470	Emergence of parochial altruism in well-mixed populations of multiple groups. Physics Letters, Section A: General, Atomic and Solid State Physics, 2015, 379, 2311-2318.	0.9	5
471	Stochastic evolutionary dynamics in minimum-effort coordination games. Physics Letters, Section A: General, Atomic and Solid State Physics, 2016, 380, 2595-2602.	0.9	5
472	Multiple tolerances dilute the second order cooperative dilemma. Physics Letters, Section A: General, Atomic and Solid State Physics, 2017, 381, 3785-3797.	0.9	5
473	Controllability of heterogeneous multiagent systems. International Journal of Robust and Nonlinear Control, 2020, 30, 512-525.	2.1	5
474	On Necessary and Sufficient Conditions for Exponential Consensus in Dynamic Networks via Uniform Complete Observability Theory. IEEE Transactions on Automatic Control, 2021, 66, 4975-4981.	3.6	5
475	Guaranteed absolute stability and robustness of a class of delay systems with local sector nonlinearities via piecewise linear Lyapunov function. , 2001, , .		4
476	A new geometric algorithm with order reduction for robust strictly positive real synthesis. , 0, , .		4
477	New results on stabilizability of switched linear systems. , 0, , .		4
478	Null controllability of planar piecewise linear systems. , 0, , .		4
479	Controllability of periodically switched linear systems with saturating actuators. , 0, , .		4
480	Disturbance attenuation of uncertain switched linear systems. , 2004, , .		4
481	Impulsive control of networked systems with communication delays. , 0, , .		4
482	Construction and control of biomimetic robotic dolphin. , 0, , .		4
483	Collision-free motion planning for a biomimetic robotic fish based on numerical flow field. , 2006, , .		4
484	Stability and stabilization of switched impulsive systems. , 2006, , .		4
485	Coordinated control of two biomimetic robotic fish in pushing-object task. IET Control Theory and Applications, 2007, 1, 1200-1207.	1.2	4
486	Solution to the Generalized Champagne Problem on simultaneous stabilization of linear systems. Science in China Series F: Information Sciences, 2007, 50, 719-731.	1.1	4

3

#	Article	IF	CITATIONS
487	State feedback control of networked systems with uncertain plant. International Journal of Systems Science, 2008, 39, 383-393.	3.7	4
488	Leader-following formation control of multiple vision-based autonomous robotic fish. , 2009, , .		4
489	Three-dimensional quasi-passive dynamic bipedal walking with flat feet and compliant ankles. , 2009, , .		4
490	Fast convergence in language games induced by majority rule. Physica A: Statistical Mechanics and Its Applications, 2010, 389, 4046-4051.	1.2	4
491	Development and gait analysis of five-bar mechanism implemented quadruped amphibious robot. , 2010, ,		4
492	A new approach to controller design for networked control systems with multiple-packet transmissions. International Journal of Systems, Control and Communications, 2011, 3, 158.	0.2	4
493	The effect of recommended role models in prisoner's dilemma game. Physica A: Statistical Mechanics and Its Applications, 2011, 390, 811-816.	1.2	4
494	Simulating energy efficient wireless sensor networks using cellular automata. , 2011, , .		4
495	A wearable capacitive sensing system with phase-dependent classifier for locomotion mode recognition. , 2012, , .		4
496	A Bayesian Approach to Uncertainty-Based Depth Map Super Resolution. Lecture Notes in Computer Science, 2013, , 205-216.	1.0	4
497	Minimal positive realizations of a class of third-order systems. , 2004, , .		4
498	Payoff Control in Repeated Games. , 2021, , .		4
499	Interval-polynomial stability theory and its applications in testing the strict positive realness of interval transfer functions. IMA Journal of Mathematical Control and Information, 1996, 13, 19-40.	1.1	3
500	Composite Interval Control Systems: Some Strong Kharitonov-Like Properties. Reliable Computing, 2000, 6, 231-246.	0.8	3
501	A new viewpoint of H â^ž control in frequency domain. International Journal of Control, 2002, 75, 627-636.	1.2	3
502	Determinative Vertices of Interval Family with ΩÎ, Stability. Journal of Mathematical Analysis and Applications, 2002, 266, 321-332.	0.5	3
503	Reachability of switched discrete-time systems under constrained switching. , 0, , .		3

504 Improved results on robust stability of multivariable interval control systems. , 0, , .

#	Article	IF	CITATIONS
505	Robust strictly positive real synthesis for convex combination of the sixth-order polynomials. , 0, , .		3
506	Robust Stability and Performance of Uncertain Lurie Systems with State Delays. Circuits, Systems, and Signal Processing, 2004, 23, 299.	1.2	3
507	Complete characterization of quadratic Lyapunov functions for planar discrete systems. Communications in Nonlinear Science and Numerical Simulation, 2004, 9, 405-416.	1.7	3
508	State feedback control of networked systems via periodical switching. , 0, , .		3
509	A coordination method for multiple biomimetic robotic fish box-pushing. , 0, , .		3
510	Design Framework and Motion Control for Biomimetic Robot Fish. , 0, , .		3
511	A Solvable Lie Algebra Condition for Stability of Linear Multidimensional Systems. IEEE Transactions on Automatic Control, 2006, 51, 320-324.	3.6	3
512	Robotic fish motion planning under inherent kinematic constraints. , 2006, , .		3
513	Cooperation of Multiple Fish-like Microrobots Based on Reinforcement Learning. , 2007, , .		3
514	Coordinated control of multiple mobile robots in pursuit-evasion games. , 2009, , .		3
515	Essential stability in games with endogenous sharing rules. Journal of Mathematical Economics, 2009, 45, 233-240.	0.4	3
516	Consensus of multi-agent systems with time-varying delay. , 2010, , .		3
517	Effects of encounter in a population of spatial prisoner's dilemma players. Theoretical Population Biology, 2011, 80, 226-231.	0.5	3
518	CPG-based locomotion control of a quadruped amphibious robot. , 2012, , .		3
519	Segmented Foot with Compliant Actuators and Its Applications to Lower-Limb Prostheses and Exoskeletons. , 2012, , .		3
520	Changes of Achilles tendon properties via 12-week PNF based robotic rehabilitation of ankle joints with spasticity and/or contracture. , 2014, 2014, 1214-7.		3
521	Motion control of a robotic transtibial prosthesis during transitions between level ground and stairs. , 2014, , .		3
522	Structural controllability of multi-agent systems with general linear dynamics over finite fields. , 2016, , .		3

#	Article	IF	CITATIONS
523	Some Open Problems on Simultaneous Stabilization of Linear Systems. Journal of Systems Science and Complexity, 2016, 29, 289-299.	1.6	3
524	An energy-efficient torque controller based on passive dynamics of human locomotion for a robotic transtibial prosthesis. , 2016, , .		3
525	Evolutionary dynamics of networked multi-person games: mixing opponent-aware and opponent-independent strategy decisions. New Journal of Physics, 2019, 21, 063013.	1.2	3
526	Phenotype affinity mediated interactions can facilitate the evolution of cooperation. Journal of Theoretical Biology, 2019, 462, 361-369.	0.8	3
527	Interaction stochasticity may hinder cooperation in the spatial public goods game. Physics Letters, Section A: General, Atomic and Solid State Physics, 2020, 384, 126121.	0.9	3
528	Bridging the Gap between Opinion Dynamics and Evolutionary Game Theory: Some Equivalence Results. , 2020, , .		3
529	Design of Robust Strictly Positive Real Transfer Functions. , 2008, , 293-341.		3
530	Robust stability of diamond families of polynomials with complex coefficients. International Journal of Systems Science, 1992, 23, 1371-1378.	3.7	2
531	Inherent robust stability of driver support systems. Science in China Series D: Earth Sciences, 1999, 42, 437-448.	0.9	2
532	ROBUST STRICTLY POSITIVE REAL SYNTHESIS BASED ON GENETIC ALGORITHM. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2002, 35, 349-354.	0.4	2
533	Equivalence of some controllability notions for linear switched systems and their geometric criteria. , 0, , .		2
534	Edge Theorem for MIMO systems. IEEE Transactions on Circuits and Systems Part 1: Regular Papers, 2003, 50, 1577-1580.	0.1	2
535	Stability of networked control systems with limited communication. , 0, , .		2
536	Quadratic stabilization of uncertain discrete-time switched linear systems. , 0, , .		2
537	Coordinated Box-pushing of Multiple Biomimetic Robotic Fish. , 0, , .		2
538	Performance optimization and coordinated control of multiple biomimetic robotic fish. , 2005, , .		2
539	Robust stabilization of discrete-time systems with time-varying delays. , 0, , .		2
540	Virtual Leader Approach to Coordinated Control of Multiple Mobile Agents with Asymmetric		2

Interactions., 0, , .

#	Article	IF	CITATIONS
541	On Reachability and Controllability of Positive Discrete-time Switched Linear Systems. , 2006, , .		2
542	Ground Contact Angle in Bipedal Locomotion towards Passive Dynamic Walking and Running. Proceedings of the American Control Conference, 2007, , .	0.0	2
543	Collective Dynamic Behavior of Anisotropic Foraging Swarms. Proceedings of the American Control Conference, 2007, , .	0.0	2
544	Target topology based task assignment for multiple mobile robots in adversarial environments. , 2007, , .		2
545	FPGA-based gait control system for passive bipedal robot. , 2007, , .		2
546	Development and control of dolphin-like underwater vehicle. , 2008, , .		2
547	Neural-based control of modular robotic fish with multiple propulsors. , 2008, , .		2
548	Velocity-consensus control for networks of multiple double-integrators. , 2009, , .		2
549	Asynchronous consensus of agents with double-integrator dynamics. , 2009, , .		2
550	Finite-time consensus for multi-agent systems with application to sensor fusion. , 2009, , .		2
551	Towards development of link-based robotic dolphin: Experiences and lessons. , 2009, , .		2
552	Mechanism of synchronization in switched nonlinear coupled dynamic networks. Europhysics Letters, 2010, 91, 48005.	0.7	2
553	Effect of community structure on coevolutionary dynamics with dynamical linking. Physica A: Statistical Mechanics and Its Applications, 2011, 390, 43-49.	1.2	2
554	A Game-Theoretical Approach to Image Segmentation. Lecture Notes in Computer Science, 2012, , 33-42.	1.0	2
555	Consensus for second-order multi-agent systems with inherent nonlinear dynamics under directed topologies. , 2012, , .		2
556	Group flocking of multiple mobile agents. , 2014, , .		2
557	Decentralized Leader-Follower Flocking of Multiple Non-Holonomic Agents. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 6668-6673.	0.4	2
558	Fuzzy-logic-based hybrid locomotion mode classification for an active pelvis orthosis: Preliminary results. , 2015, 2015, 3893-6.		2

#	Article	IF	CITATIONS
559	Opinion containment in social networks over issue sequences. , 2017, , .		2
560	The Equivalence Induced by Unifying Fitness Mappings in Frequency-Dependent Moran Process. , 2018, , .		2
561	Role of the effective payoff function in evolutionary game dynamics. Europhysics Letters, 2018, 124, 40002.	0.7	2
562	Distributed algorithms for solving the convex feasibility problems. Science China Information Sciences, 2020, 63, 1.	2.7	2
563	Coevolution of fairness and spite on stochastic dynamics networks. Physics Letters, Section A: General, Atomic and Solid State Physics, 2021, 405, 127423.	0.9	2
564	Evolution of cooperation with joint liability. Journal of the Royal Society Interface, 2022, 19, 20220082.	1.5	2
565	Achieving consensus in spite of stubbornness: time-varying concatenated Friedkin-Johnsen models. , 2021, , .		2
566	Controllability implies stabilizability for switched linear systems under arbitrary switching. , 2003, , .		1
567	Reachability of switched linear impulsive systems. , 0, , .		1
568	Reachability and controllability of switched linear systems with state jumps. , 0, , .		1
569	Hâ^ž performance of interval systems. , 2003, , .		1
570	Persistent bounded disturbance rejection for impulsive systems with polytopic uncertainties. , 2003, , .		1
571	An LMI approach to L/sub 2/ gain analysis and control synthesis of switched systems. , 0, , .		1
572	On controllability and reachability of switched systems with digraph-directed switchings. , 0, , .		1
573	Flocking coordination of multiple mobile autonomous agents with asymmetric interactions and switching topology. , 2005, , .		1
574	Control and coordination of biomimetic robotic fish. , 2005, , .		1
575	A New Criterion on Exponential Stability of a Class of Discrete Cellular Neural Networks with Time Delay. Lecture Notes in Computer Science, 2005, , 769-772.	1.0	1
576	Motion Planning of Cooperative Disk-Pushing for Multiple Biomimetic Robotic Fish. , 0, , .		1

#	Article	IF	CITATIONS
577	Cooperative control of multiple robotic fish in a disk-pushing task. , 2006, , .		1
578	Flocking Coordination of Multiple Interactive Dynamical Agents with Switching Topology. , 2006, , .		1
579	Comment: Controllability of periodic systems: continuous and discrete. IET Control Theory and Applications, 2006, 153, 627-627.	1.7	1
580	Underwater transportation of multiple fish-like robots using situation based action selection. , 0, , .		1
581	Minimal Positive Realizations for Transfer Functions with Negative Poles. , 2006, , .		1
582	A Coordination Method for Multiple Biomimetic Robotic Fish in Underwater Transport Task. Proceedings of the American Control Conference, 2007, , .	0.0	1
583	Online and Offline Stabilization of Switched Linear Systems. , 2007, , .		1
584	Robust controller design for networked control systems with nonlinear uncertainties. , 2009, , .		1
585	Underwater box-pushing with multiple vision-based autonomous robotic fish. , 2010, , .		1
586	Path planning for robot fish in water-polo game: Tangent circle method. , 2011, , .		1
587	Complexity analysis of network-based dynamical systems. Journal of Systems Science and Complexity, 2011, 24, 413-432.	1.6	1
588	A new proof of existence of equilibria in infinite normal form games. Applied Mathematics Letters, 2011, 24, 253-256.	1.5	1
589	Decentralized formation flocking for multiple non-holonomic agents. , 2013, , .		1
590	A Joint Learning-Based Method for Multi-view Depth Map Super Resolution. , 2013, , .		1
591	Evolution of joint cooperation under phenotypic variations. Scientific Reports, 2018, 8, 4137.	1.6	1
592	Dynamic analysis and decision-making in disease-behavior systems with perceptions. , 2019, , .		1
593	Robust strictly positive real synthesis for polynomial families of arbitrary order. Science in China Series F: Information Sciences, 2004, 47, 475.	1.1	1
594	Modeling and Control of a Link-Based Dolphin-Like Robot Capable of 3D Movements. Lecture Notes in Computer Science, 2008, , 982-991.	1.0	1

#	Article	IF	CITATIONS
595	Some characterizations of interval systems: further extensions and applications. , 0, , .		0
596	Robust stability of polynomial families and robust strict positive realness of rational function families. International Journal of Systems Science, 1992, 23, 235-247.	3.7	0
597	Diamond and simplex stability regions. International Journal of Systems Science, 1993, 24, 757-767.	3.7	0
598	Robust  -stability of the interval polynomial set and robust  stabilization of the interval rational function set. International Journal of Systems Science, 1994, 25, 551-570.	3.7	0
599	Robust Stabilization of Car Steering Dynamics. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 1999, 32, 3283-3288.	0.4	0
600	Performance Evaluation of Composite Interval Systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 1999, 32, 3219-3224.	0.4	0
601	Genetic algorithm for simultaneous stabilization based on stability preserving maps. , 2002, , .		0
602	Controllability and stabilizability of a class of hybrid dynamic systems. , 0, , .		0
603	Some characterizations of interval systems: pointwise frequency properties. , 0, , .		0
604	ESPR analysis and synthesis of discrete-time systems with polytopic uncertainty. , 0, , .		0
605	Complete characterization of quadratic Lyapunov functions for planar systems in LMI regions. , 0, , .		0
606	Reachability of a class of hybrid systems. , 0, , .		0
607	Robust strictly positive real synthesis of polynomial segments for discrete time systems. , 0, , .		0
608	Robust peak gain problem for uncertain systems via LMI approach. , 0, , .		0
609	Controllability and stabilization of discrete-time switched linear systems. , 0, , .		0
610	Online-type state feedback design for switched systems with time-delay in detection of switching signal. , 0, , .		0
611	Stabilization of a collection of linear systems with communication constraints. , 0, , .		0

612 On reachability of switched linear discrete-time systems with time-delay in state. , 0, , .

#	Article	lF	CITATIONS
613	Commuting and stable state feedback design for switched linear systems. , 0, , .		Ο
614	Commuting and Stable Feedback Design for Switched Linear Discrete-time Systems. , 0, , .		0
615	A hierarchical framework for cooperative control of multiple bio-mimetic robotic fish. , 2005, , .		0
616	Stabilization of NCSs with Time-Varying Transmission Period. , 0, , .		0
617	Coordination of a group of agents with a leader-part I: general case. , 0, , .		0
618	Robust Stabilization of Time-Varying Uncertain Switched Linear Systems. , 0, , .		0
619	Disturbance attenuation of discrete-time switched linear systems. , 2006, , .		0
620	Preliminary results on null controllable region of discrete-time switched linear systems with input saturation. , 2006, , .		0
621	Robust stabilization of nonlinear switched systems via switched output feedback. , 2006, , .		0
622	Frequency domain criteria for robust D-stability of mimo systems based on LMI method. Applied Mathematics and Mechanics (English Edition), 2006, 27, 207-213.	1.9	0
623	Hopf Bifurcation Analysis of a Class of Delay Differential Systems. , 2006, , .		0
624	Integrated Heterogeneous Multi-Robot System for Collaborative Navigation. , 2007, , .		0
625	Information propagation in hierarchical networks. , 2007, , .		0
626	A Note on Minimal Positive Realizations of Continuous-Time Linear Systems. , 2007, , .		0
627	Fuzzy logic based body state estimation in a bipedal robot with passive dynamic gaits. , 2007, , .		0
628	ROBUST <i>H</i> _{â^ž} CONTROL AND QUADRATIC STABILIZATION OF DISCRETEâ€TIME SWITCHED SYSTEMS WITH NORMâ€BOUNDED TIMEâ€VARYING UNCERTAINTIES. Asian Journal of Control, 2007, 9, 352-361	1.9	0
629	Output agreement in high-dimensional multi-agent systems. , 2009, , .		0

630 Self-learning PD game with imperfect information on networks. , 2009, , .

0

#	Article	IF	CITATIONS
631	Evolutionary intelligence and complexity management in social economic systems. , 2009, , .		0
632	Evolutionary game dynamics in finite populations with migration. , 2009, , .		0
633	Coevolution of strategy and structure on social networks. , 2010, , .		0
634	Effects of ankle stiffness on gait selection of dynamic bipedal walking with flat feet. , 2011, 2011, 5975446.		0
635	Three-dimensional swimming robotic fish with slide-block structure: design and realization. Robotica, 2014, 32, 823-834.	1.3	0
636	Optimal control of first-order multi-agent systems with leaders. , 2014, , .		0
637	Effects of migration in the spatial ultimatum game. , 2015, , .		0
638	Optimal topology selection for leader-following multi-agent systems with opposite leaders. , 2015, , .		0
639	Game theoretic approach to global climate control. , 2015, , .		0
640	Controllability of heterogeneous multi-agent systems. , 2015, , .		0
641	Coevolutionary dynamics of initial investment and reciprocation rate in continuous public goods games. , 2016, , .		0
642	Asynchronous periodic edge-event triggered control for double-integrator networks. , 2016, , .		0
643	Evolutionary Game Gynamics Driven by Heterogeneous Self-learning Rules. , 2018, , .		0
644	Upper bound of the minimum energy cost for controlling complex networks. , 2019, , .		0
645	Controllability and observability of multi-agent systems with general linear dynamics under switching topologies. International Journal of Control, 2021, 94, 1355-1367.	1.2	0
646	Controllability and reachability criteria for linear piecewise constant impulsive systems. , 2003, , .		0
647	Analysis of persistent bounded disturbance rejection for Lurie systems of the neutral type. , 2004, , .		0

648 Controllability of piecewise linear descriptor systems. , 2004, , .

#	Article	IF	CITATIONS
649	Disturbance rejection of switched systems. , 2004, , .		Ο
650	Stability and Stabilization of Impulsive Hybrid Dynamical Systems. Lecture Notes in Computer Science, 2005, , 645-654.	1.0	0
651	Development of the Multiple Robot Fish Cooperation System. Lecture Notes in Computer Science, 2006, , 34-43.	1.0	0
652	Collaborative Localization Based Formation Control of Multiple Quadruped Robots. Lecture Notes in Computer Science, 2009, , 649-659.	1.0	0
653	Information Dynamics and Intelligent Cooperation in Networked Societies. Lecture Notes in Computer Science, 2009, , 94-103.	1.0	0
654	DEVELOPMENT OF BIOMIMETIC POWERED ANKLE-FOOT PROSTHESIS WITH COMPLIANT JOINTS AND SEGMENTED FOOT. , 2010, , .		0
655	Topological essentiality in infinite games. Journal of Industrial and Management Optimization, 2012, 8, 179-187.	0.8	Ο