Andre Coelho

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/2834333/publications.pdf

Version: 2024-02-01

1937685 2272923 12 122 4 4 citations h-index g-index papers 12 12 12 78 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Visual-Inertial Telepresence for Aerial Manipulation. , 2020, , .		26
2	Smoother Position-Drift Compensation for Time Domain Passivity Approach Based Teleoperation. , 2018, , .		19
3	Whole-Body Bilateral Teleoperation of a Redundant Aerial Manipulator. , 2020, , .		14
4	Energy-Based Cooperative Control for Landing Fixed-Wing UAVs on Mobile Platforms Under Communication Delays. IEEE Robotics and Automation Letters, 2020, 5, 5081-5088.	5.1	14
5	Optimal Oscillation Damping Control of cable-Suspended Aerial Manipulator with a Single IMU Sensor. , 2020, , .		12
6	Whole-Body Teleoperation and Shared Control of Redundant Robots with Applications to Aerial Manipulation. Journal of Intelligent and Robotic Systems: Theory and Applications, 2021, 102, 1.	3.4	12
7	Multi-DoF Time Domain Passivity Approach Based Drift Compensation for Telemanipulation. , 2019, , .		9
8	Proxy-Based Approach for Position Synchronization of Delayed Robot Coupling Without Sacrificing Performance. IEEE Robotics and Automation Letters, 2020, 5, 6599-6606.	5.1	6
9	Model-Augmented Haptic Telemanipulation: Concept, Retrospective Overview, and Current Use Cases. Frontiers in Robotics and Al, 2021, 8, 611251.	3.2	5
10	Compliance Control of a Cable-Suspended Aerial Manipulator using Hierarchical Control Framework. , 2020, , .		4
11	Hierarchical Control of Redundant Aerial Manipulators with Enhanced Field of View., 2021,,.		1
12	High-Fidelity Modeling and Control Design for a Cooperative High Altitude Long Endurance Aircraft Landing System. , $2021, $, .		0