

Mojtaba Ahmadiéh Khanesar

List of Publications by Year in descending order

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91
papers

1,626
citations

394286

19
h-index

360920

35
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all docs

94
docs citations

94
times ranked

1633
citing authors

#	ARTICLE	IF	CITATIONS
1	Robust Sliding Mode Fuzzy Control of Industrial Robots Using an Extended Kalman Filter Inverse Kinematic Solver. <i>Energies</i> , 2022, 15, 1876.	1.6	10
2	Rule-Based Sliding-Mode Fuzzy Logic Control. <i>Studies in Systems, Decision and Control</i> , 2021, , 89-102.	0.8	0
3	Adaptive Sliding-Mode Fuzzy Control Systems: Gradient Descent Method. <i>Studies in Systems, Decision and Control</i> , 2021, , 103-124.	0.8	0
4	Adaptive Sliding-Mode Fuzzy Control Systems: Lyapunov Approach. <i>Studies in Systems, Decision and Control</i> , 2021, , 125-178.	0.8	0
5	Prediction Interval Identification Using Interval Type-2 Fuzzy Logic Systems: Lake Water Level Prediction Using Remote Sensing Data. <i>IEEE Sensors Journal</i> , 2021, 21, 13815-13827.	2.4	7
6	Electrical Load Prediction Using Interval Type-2 Atanassov Intuitionist Fuzzy System: Gravitational Search Algorithm Tuning Approach. <i>Energies</i> , 2021, 14, 3591.	1.6	4
7	Unsupervised Learning for Product Use Activity Recognition: An Exploratory Study of a "Chatty Device". <i>Sensors</i> , 2021, 21, 4991.	2.1	7
8	Intelligent Optimization of Sliding-Mode Fuzzy Logic Controllers. <i>Studies in Systems, Decision and Control</i> , 2021, , 213-234.	0.8	0
9	Fuzzy Logic Systems. <i>Studies in Systems, Decision and Control</i> , 2021, , 57-87.	0.8	0
10	XOR Binary Gravitational Search Algorithm with Repository: Industry 4.0 Applications. <i>Applied Sciences (Switzerland)</i> , 2020, 10, 6451.	1.3	5
11	Recurrent Interval Type-2 Fuzzy Wavelet Neural Network with Stable Learning Algorithm: Application to Model-Based Predictive Control. <i>International Journal of Fuzzy Systems</i> , 2020, 22, 351-367.	2.3	7
12	Ensemble of Deep Belief Network and Bayesian Adaptive Aggregation for Regression. , 2019, , .		0
13	Optimal control of non-smooth fractional-order systems based on extended Caputo derivative. <i>Nonlinear Dynamics</i> , 2019, 96, 57-74.	2.7	6
14	Nonlinear System Identification Using Type-2 Fuzzy Recurrent Wavelet Neural Network. , 2019, , .		5
15	A Novel Non-Iterative Parameter Estimation Method for Interval Type-2 Fuzzy Neural Networks Based on a Dynamic Cost Function. , 2019, , .		2
16	Ant Colony Optimization Algorithm for Industrial Robot Programming in a Digital Twin. , 2019, , .		15
17	XOR Binary Gravitational Search Algorithm. , 2019, , .		2
18	Type-2 fuzzy elliptic membership functions for modeling uncertainty. <i>Engineering Applications of Artificial Intelligence</i> , 2018, 70, 170-183.	4.3	26

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19	Optimal parameters of an ELM-based interval type 2 fuzzy logic system: a hybrid learning algorithm. <i>Neural Computing and Applications</i> , 2018, 29, 1001-1014.	3.2	6
20	Modeling level change in Lake Urmia using hybrid artificial intelligence approaches. <i>Theoretical and Applied Climatology</i> , 2018, 133, 447-458.	1.3	4
21	Improving the quality of service in network-based control systems. <i>Transactions of the Institute of Measurement and Control</i> , 2018, 40, 2694-2702.	1.1	0
22	An aerial robot for rice farm quality inspection with type-2 fuzzy neural networks tuned by particle swarm optimization-sliding mode control hybrid algorithm. <i>Swarm and Evolutionary Computation</i> , 2018, 41, 1-8.	4.5	63
23	Optimal synchronization of non-smooth fractional order chaotic systems with uncertainty based on extension of a numerical approach in fractional optimal control problems. <i>Chaos, Solitons and Fractals</i> , 2018, 115, 325-340.	2.5	9
24	MOSCAP compensation of three-stage operational amplifiers: Sensitivity and robustness, modeling and analysis. <i>The Integration VLSI Journal</i> , 2018, 62, 34-49.	1.3	1
25	A New Maximum Power Point Tracking Based on Modified Firefly Algorithm for PV System Under Partial Shading Conditions. <i>Technology and Economics of Smart Grids and Sustainable Energy</i> , 2018, 3, 1.	1.8	27
26	Comparative analysis of three approaches of antecedent part generation for an IT2 TSK FLS. <i>Applied Soft Computing Journal</i> , 2017, 51, 130-144.	4.1	6
27	Guaranteed cost adaptive sliding mode fuzzy control systems. , 2017, , .		0
28	Novel Levenbergâ€“Marquardt based learning algorithm for unmanned aerial vehicles. <i>Information Sciences</i> , 2017, 417, 361-380.	4.0	39
29	Improving the Speed of Center of Sets Type Reduction in Interval Type-2 Fuzzy Systems by Eliminating the Need for Sorting. <i>IEEE Transactions on Fuzzy Systems</i> , 2017, 25, 1193-1206.	6.5	33
30	Multi objective optimal allocation of fault current limiters in power system. <i>International Journal of Electrical Power and Energy Systems</i> , 2017, 85, 1-11.	3.3	27
31	A novel complexity reduced Levenberge-Marquardt algorithm: Application to the training of interval type-2 fuzzy systems. , 2017, , .		1
32	Learning Control of Fixed-Wing Unmanned Aerial Vehicles Using Fuzzy Neural Networks. <i>International Journal of Aerospace Engineering</i> , 2017, 2017, 1-12.	0.5	22
33	Elliptic membership functions and the modeling uncertainty in type-2 fuzzy logic systems as applied to time series prediction. , 2017, , .		6
34	Type-2 Fuzzy Neural Networks. , 2016, , 37-43.		10
35	Gradient Descent Methods for Type-2 Fuzzy Neural Networks. , 2016, , 45-70.		1
36	Extended Kalman Filter Algorithm for the Tuning of Type-2 Fuzzy Neural Networks. , 2016, , 71-84.		0

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37	Sliding Mode Control Theory-Based Parameter Adaptation Rules for Fuzzy Neural Networks. , 2016, , 85-131.		3
38	Hybrid Training Method for Type-2 Fuzzy Neural Networks Using Particle Swarm Optimization. , 2016, , 133-160.		1
39	Noise Reduction Property of Type-2 Fuzzy Neural Networks. , 2016, , 161-172.		1
40	Model of car wing active control in order to increase stability of the car on corners of roads. , 2016, , .		1
41	A multi-objective genetic type-2 fuzzy extreme learning system for the identification of nonlinear dynamic systems. , 2016, , .		0
42	Sliding mode fuzzy rule base bilateral teleoperation control of 2-DOF SCARA system. , 2016, , .		9
43	Artificial bee colony optimization of interval type-2 fuzzy extreme learning system for chaotic data. , 2016, , .		2
44	COOA: Competitive optimization algorithm. Swarm and Evolutionary Computation, 2016, 30, 39-63.	4.5	29
45	Optimal design of adaptive type-2 neuro-fuzzy systems: A review. Applied Soft Computing Journal, 2016, 44, 134-143.	4.1	33
46	A Novel Direct Model Reference Fuzzy Control Approach Based on Observer and Its Applications. IFAC-PapersOnLine, 2016, 49, 318-323.	0.5	1
47	Adaptive direct fuzzy control of SISO nonlinear systems using a fuzzy reference model. , 2016, , .		1
48	Recurrent Interval Type-2 Fuzzy Control of 2-DOF Helicopter With Finite Time Training Algorithm. IFAC-PapersOnLine, 2016, 49, 293-299.	0.5	10
49	Maclaurin series expansion complexity-reduced center of sets type-reduction + defuzzification for interval type-2 fuzzy systems. , 2016, , .		8
50	Recurrent interval type-2 neuro-fuzzy control of an electro hydraulic servo system. , 2016, , .		4
51	Indirect Model Reference Fuzzy Control of SISO Fractional Order Nonlinear Chaotic Systems. Procedia Computer Science, 2016, 102, 309-316.	1.2	15
52	Fuzzy reference model for adaptive indirect Takagi-Sugeno model reference control. , 2016, , .		1
53	A systematic design of interval type-2 fuzzy logic system using extreme learning machine for electricity load demand forecasting. International Journal of Electrical Power and Energy Systems, 2016, 82, 1-10.	3.3	64
54	Model reference fractional order control using type-2 fuzzy neural networks structure: Implementation on a 2-DOF helicopter. Neurocomputing, 2016, 193, 268-279.	3.5	20

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55	Design of a hierarchical fuzzy model predictive controller. International Journal of Engineering and Technology(UAE), 2015, 4, 342.	0.2	1
56	Stabilization of type-2 fuzzy Takagi-Sugeno-Kang identifier using Lyapunov functions. , 2015, , .		0
57	Optimal sliding mode type-2 TSK fuzzy control of a 2-DOF helicopter. , 2015, , .		9
58	Levenberg-Marquardt training method for Type-2 fuzzy neural networks and its stability analysis. , 2015, , .		2
59	Direct Model Reference Adaptive Fuzzy Control of Networked SISO Nonlinear Systems. IEEE/ASME Transactions on Mechatronics, 2015, , 1-1.	3.7	19
60	Feedback Error Learning Control of Magnetic Satellites Using Type-2 Fuzzy Neural Networks With Elliptic Membership Functions. IEEE Transactions on Cybernetics, 2015, 45, 858-868.	6.2	47
61	Adaptive Indirect Fuzzy Sliding Mode Controller for Networked Control Systems Subject to Time-Varying Network-Induced Time Delay. IEEE Transactions on Fuzzy Systems, 2015, 23, 205-214.	6.5	128
62	Adaptive sliding-mode type-2 neuro-fuzzy control of an induction motor. Expert Systems With Applications, 2015, 42, 6635-6647.	4.4	64
63	Controlling the Pitch and Yaw Angles of a 2-DOF Helicopter Using Interval Type-2 Fuzzy Neural Networks. Studies in Systems, Decision and Control, 2015, , 349-370.	0.8	7
64	Identification of Nonlinear Dynamic Systems Using Type-2 Fuzzy Neural Networksâ€”A Novel Learning Algorithm and a Comparative Study. IEEE Transactions on Industrial Electronics, 2015, 62, 1716-1724.	5.2	84
65	Hybrid Model for the Training of Interval Type-2 Fuzzy Logic System. Lecture Notes in Computer Science, 2015, , 644-653.	1.0	1
66	Improved Karnik-Mendel algorithm: Eliminating the need for sorting. , 2014, , .		4
67	Neural Networks for Normative Knowledge Source of Cultural Algorithm. International Journal of Computational Intelligence Systems, 2014, 7, 979.	1.6	1
68	Discrete binary cat swarm optimization algorithm. , 2013, , .		63
69	Hierarchical Fuzzy identification using gradient descent and recursive least square method. , 2013, , .		1
70	Observer-based indirect model reference fuzzy control system with application to control of chaotic systems. Journal of the Franklin Institute, 2013, 350, 419-436.	1.9	10
71	Type-2 Fuzzy neural networks for sliding mode Fuzzy control of nonlinear dynamical systems with adaptive learning rate. , 2013, , .		1
72	Sliding mode type-2 fuzzy control of robotic arm using ellipsoidal membership functions. , 2013, , .		1

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73	Estimation of the parameters of wavelet neural networks using simultaneous use of genetic algorithm and recursive least square. , 2013, , .		0
74	Statistical results to show the superiority of type two fuzzy logic systems over type one counterparts under noisy conditions. , 2012, , .		3
75	Extended Kalman Filter Based Learning Algorithm for Type-2 Fuzzy Logic Systems and Its Experimental Evaluation. IEEE Transactions on Industrial Electronics, 2012, 59, 4443-4455.	5.2	124
76	Training fuzzy neural networks using sliding mode theory with adaptive learning rate. , 2012, , .		1
77	Control and synchronization of chaotic systems using a novel indirect model reference fuzzy controller. Soft Computing, 2012, 16, 1253-1265.	2.1	21
78	A novel training method based on variable structure systems theory for fuzzy neural networks. , 2011, , .		3
79	Levenberg marquardt algorithm for the training of type-2 fuzzy neuro systems with a novel type-2 fuzzy membership function. , 2011, , .		20
80	Analysis of the Noise Reduction Property of Type-2 Fuzzy Logic Systems Using a Novel Type-2 Membership Function. IEEE Transactions on Systems, Man, and Cybernetics, 2011, 41, 1395-1406.	5.5	81
81	Direct Model Reference Takagiâ€™Sugeno Fuzzy Control of SISO Nonlinear Systems. IEEE Transactions on Fuzzy Systems, 2011, 19, 914-924.	6.5	54
82	Identification of interval fuzzy models using recursive least square method. , 2010, , .		1
83	Subspace identification of dynamical neurofuzzy system using LOLIMOT. , 2010, , .		4
84	A novel type-2 fuzzy membership function: application to the prediction of noisy data. , 2010, , .		35
85	Identification using ANFIS with intelligent hybrid stable learning algorithm approaches and stability analysis of training methods. Applied Soft Computing Journal, 2009, 9, 833-850.	4.1	120
86	Incremental Locally Linear Fuzzy Classifier. Advances in Intelligent and Soft Computing, 2009, , 305-314.	0.2	0
87	Direct Stable Adaptive Fuzzy Neural Model Reference Control of a Class of Nonlinear Systems. , 2008, , .		5
88	Fuzzy Sliding Mode Control of Rotary Inverted Pendulum. , 2007, , .		18
89	Sliding mode control of Rotary Inverted Pendulum. , 2007, , .		10
90	A novel binary particle swarm optimization. , 2007, , .		113

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91	Hybrid Training of Recurrent Fuzzy Neural Network Model. , 2007, , .		16