

# Erik Schaffernicht

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/2780129/publications.pdf>

Version: 2024-02-01

17  
papers

212  
citations

1684188

5  
h-index

1872680

6  
g-index

18  
all docs

18  
docs citations

18  
times ranked

248  
citing authors

#	ARTICLE	IF	CITATIONS
1	Ensemble Learning-Based Approach for Gas Detection Using an Electronic Nose in Robotic Applications. <i>Frontiers in Chemistry</i> , 2022, 10, 863838.	3.6	5
2	Semi-supervised Gas Detection Using an Ensemble of One-class Classifiers. , 2019, , .		2
3	Towards Gas Discrimination and Mapping in Emergency Response Scenarios Using a Mobile Robot with an Electronic Nose. <i>Sensors</i> , 2019, 19, 685.	3.8	32
4	FireNose on Mobile Robot in Harsh Environments. <i>IEEE Sensors Journal</i> , 2019, 19, 12418-12431.	4.7	20
5	A cluster analysis approach based on exploiting density peaks for gas discrimination with electronic noses in open environments. <i>Sensors and Actuators B: Chemical</i> , 2018, 259, 183-203.	7.8	26
6	Exploration and localization of a gas source with MOX gas sensors on a mobile robot – A Gaussian regression based amplitude approach. , 2017, , .		11
7	Bayesian gas source localization and exploration with a multi-robot system using partial differential equation based modeling. , 2017, , .		6
8	Improving gas dispersal simulation for mobile robot olfaction: Using robot-created occupancy maps and remote gas sensors in the simulation loop. , 2017, , .		5
9	Mobile robot multi-sensor unit for unsupervised gas discrimination in uncontrolled environments. , 2017, , .		14
10	Improving gas tomography with mobile robots: An evaluation of sensing geometries in complex environments. , 2017, , .		3
11	The right direction to smell: Efficient sensor planning strategies for robot assisted gas tomography. , 2016, , .		7
12	Towards occupational health improvement in foundries through dense dust and pollution monitoring using a complementary approach with mobile and stationary sensing nodes. , 2016, , .		9
13	Unsupervised gas discrimination in uncontrolled environments by exploiting density peaks. , 2016, , .		2
14	Global Coverage Measurement Planning Strategies for Mobile Robots Equipped with a Remote Gas Sensor. <i>Sensors</i> , 2015, 15, 6845-6871.	3.8	13
15	Efficient measurement planning for remote gas sensing with mobile robots. , 2015, , .		10
16	Combining Non Selective Gas Sensors on a Mobile Robot for Identification and Mapping of Multiple Chemical Compounds. <i>Sensors</i> , 2014, 14, 17331-17352.	3.8	31
17	A novel approach for gas discrimination in natural environments with Open Sampling Systems. , 2014, , .		13