

# Valentin Peretroukhin

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/2729275/publications.pdf>

Version: 2024-02-01

11

papers

205

citations

1684188

5

h-index

1872680

6

g-index

11

all docs

11

docs citations

11

times ranked

200

citing authors

#	ARTICLE	IF	CITATIONS
1	Robust Data-Driven Zero-Velocity Detection for Foot-Mounted Inertial Navigation. <i>IEEE Sensors Journal</i> , 2020, 20, 957-967.	4.7	51
2	Improving foot-mounted inertial navigation through real-time motion classification. , 2017, , .		44
3	DPC-Net: Deep Pose Correction for Visual Localization. <i>IEEE Robotics and Automation Letters</i> , 2018, 3, 2424-2431.	5.1	31
4	Certifiably Globally Optimal Extrinsic Calibration From Per-Sensor Egomotion. <i>IEEE Robotics and Automation Letters</i> , 2019, 4, 367-374.	5.1	18
5	Reducing drift in visual odometry by inferring sun direction using a Bayesian Convolutional Neural Network. , 2017, , .		16
6	PROBE-GK: Predictive robust estimation using generalized kernels. , 2016, , .		13
7	Self-Supervised Deep Pose Corrections for Robust Visual Odometry. , 2020, , .		11
8	Convex Iteration for Distance-Geometric Inverse Kinematics. <i>IEEE Robotics and Automation Letters</i> , 2022, 7, 1952-1959.	5.1	8
9	On the Coupling of Depth and Egomotion Networks for Self-Supervised Structure from Motion. <i>IEEE Robotics and Automation Letters</i> , 2022, 7, 6766-6773.	5.1	7
10	Inferring sun direction to improve visual odometry: A deep learning approach. <i>International Journal of Robotics Research</i> , 2018, 37, 996-1016.	8.5	5
11	Toward Robust and Efficient Online Adaptation for Deep Stereo Depth Estimation. , 2021, , .		1