

# Guillermo Puriel-Gil

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/2708764/publications.pdf>

Version: 2024-02-01

1  
papers

10  
citations

3310631

1  
h-index

3475103

1  
g-index

1  
all docs

1  
docs citations

1  
times ranked

9  
citing authors

#	ARTICLE	IF	CITATIONS
1	Reinforcement Learning Compensation based PD Control for a Double Inverted Pendulum. IEEE Latin America Transactions, 2019, 17, 323-329.	1.2	10