

# Yinjie Lin

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/2667161/publications.pdf>

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#	ARTICLE	IF	CITATIONS
1	Decoupled Torque Control of Series Elastic Actuator With Adaptive Robust Compensation of Time-Varying Load-Side Dynamics. IEEE Transactions on Industrial Electronics, 2020, 67, 5604-5614.	7.9	33
2	Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. IEEE/ASME Transactions on Mechatronics, 2021, 26, 1905-1913.	5.8	24
3	Unified Method for Task-Space Motion/Force/Impedance Control of Manipulator With Unknown Contact Reaction Strategy. IEEE Robotics and Automation Letters, 2022, 7, 1478-1485.	5.1	10
4	Adaptive Robust Motion Control of Series Elastic Actuator with Unmatched Uncertainties. , 2021, , .		0