

Bailu Si

List of Publications by Year in descending order

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| # | ARTICLE | IF | CITATIONS |
|----|--|-----|-----------|
| 1 | Abnormal Reactivity of Brain Oscillations to Visual Search Target in Children With Attention-Deficit/Hyperactivity Disorder. <i>Biological Psychiatry: Cognitive Neuroscience and Neuroimaging</i> , 2023, 8, 522-530. | 1.1 | 2 |
| 2 | Learning Cognitive Map Representations for Navigation by Sensory-Motor Integration. <i>IEEE Transactions on Cybernetics</i> , 2022, 52, 508-521. | 6.2 | 5 |
| 3 | A theory of geometry representations for spatial navigation. <i>Progress in Neurobiology</i> , 2022, 211, 102228. | 2.8 | 3 |
| 4 | Entorhinal-hippocampal interactions lead to globally coherent representations of space. <i>Current Research in Neurobiology</i> , 2022, 3, 100035. | 1.1 | 0 |
| 5 | A brain-inspired compact cognitive mapping system. <i>Cognitive Neurodynamics</i> , 2021, 15, 91-101. | 2.3 | 13 |
| 6 | Learning allocentric representations of space for navigation. <i>Neurocomputing</i> , 2021, 453, 579-589. | 3.5 | 3 |
| 7 | Probabilistic learning vector quantization on manifold of symmetric positive definite matrices. <i>Neural Networks</i> , 2021, 142, 105-118. | 3.3 | 6 |
| 8 | Characterization of exploratory patterns and hippocampal-prefrontal network oscillations during the emergence of free exploration. <i>Science Bulletin</i> , 2021, 66, 2238-2250. | 4.3 | 7 |
| 9 | The DIAMOND Model: Deep Recurrent Neural Networks for Self-Organizing Robot Control. <i>Frontiers in Neurorobotics</i> , 2020, 14, 62. | 1.6 | 2 |
| 10 | NeuroBayesSLAM: Neurobiologically inspired Bayesian integration of multisensory information for robot navigation. <i>Neural Networks</i> , 2020, 126, 21-35. | 3.3 | 23 |
| 11 | Video data for the cognitive mapping process of NeuroBayesSLAM system. <i>Data in Brief</i> , 2020, 30, 105637. | 0.5 | 0 |
| 12 | A sampling-based multi-tree fusion algorithm for frontier detection. <i>International Journal of Advanced Robotic Systems</i> , 2019, 16, 172988141986542. | 1.3 | 7 |
| 13 | Unsupervised Feature Learning for Visual Place Recognition in Changing Environments. , 2019, , . | | 3 |
| 14 | Mobile Robot Exploration Based on Rapidly-exploring Random Trees and Dynamic Window Approach. , 2019, , . | | 10 |
| 15 | Learning joint space-time-frequency features for EEG decoding on small labeled data. <i>Neural Networks</i> , 2019, 114, 67-77. | 3.3 | 74 |
| 16 | A Reinforcement Learning Neural Network for Robotic Manipulator Control. <i>Neural Computation</i> , 2018, 30, 1983-2004. | 1.3 | 26 |
| 17 | Sample-Based Frontier Detection for Autonomous Robot Exploration. , 2018, , . | | 8 |
| 18 | Combined optimisation of waveform and quantisation thresholds for multistatic radar systems. <i>IET Signal Processing</i> , 2018, 12, 559-565. | 0.9 | 4 |

| # | ARTICLE | IF | CITATIONS |
|----|--|-----|-----------|
| 19 | Group feature selection with multiclass support vector machine. <i>Neurocomputing</i> , 2018, 317, 42-49. | 3.5 | 25 |
| 20 | A novel pyramidal cell type promotes sharp-wave synchronization in the hippocampus. <i>Nature Neuroscience</i> , 2018, 21, 985-995. | 7.1 | 65 |
| 21 | Self-organization of modular activity of grid cells. <i>Hippocampus</i> , 2017, 27, 1204-1213. | 0.9 | 32 |
| 22 | Two-dimensional forward-looking sonar image registration by maximization of peripheral mutual information. <i>International Journal of Advanced Robotic Systems</i> , 2017, 14, 172988141774627. | 1.3 | 18 |
| 23 | A prey-predator model for efficient robot tracking. , 2017, , . | | 1 |
| 24 | Model learning based on grid cell representations. , 2017, , . | | 1 |
| 25 | Cognitive Mapping Based on Conjunctive Representations of Space and Movement. <i>Frontiers in Neurorobotics</i> , 2017, 11, 61. | 1.6 | 20 |
| 26 | Local Autoencoding for Parameter Estimation in a Hidden Potts-Markov Random Field. <i>IEEE Transactions on Image Processing</i> , 2016, 25, 2324-2336. | 6.0 | 9 |
| 27 | Label field initialization for MRF-based sonar image segmentation by selective autoencoding. , 2016, , . | | 4 |
| 28 | Prior parameter estimation for Ising-MRF-based sonar image segmentation by local center-encoding. , 2015, , . | | 6 |
| 29 | Self-organization of hippocampal representations in large environments. , 2015, , . | | 0 |
| 30 | Continuous Attractor Network Model for Conjunctive Position-by-Velocity Tuning of Grid Cells. <i>PLoS Computational Biology</i> , 2014, 10, e1003558. | 1.5 | 23 |
| 31 | A model for the differentiation between grid and conjunctive units in medial entorhinal cortex. <i>Hippocampus</i> , 2013, 23, 1410-1424. | 0.9 | 77 |
| 32 | Grid cells on the ball. <i>Journal of Statistical Mechanics: Theory and Experiment</i> , 2013, 2013, P03013. | 0.9 | 18 |
| 33 | Grid maps for spaceflight, anyone? They are for free!. <i>Behavioral and Brain Sciences</i> , 2013, 36, 566-567. | 0.4 | 7 |
| 34 | Grid alignment in entorhinal cortex. <i>Biological Cybernetics</i> , 2012, 106, 483-506. | 0.6 | 85 |
| 35 | Self-organization of multiple spatial and context memories in the hippocampus. <i>Neuroscience and Biobehavioral Reviews</i> , 2012, 36, 1609-1625. | 2.9 | 40 |
| 36 | The role of competitive learning in the generation of DG fields from EC inputs. <i>Cognitive Neurodynamics</i> , 2009, 3, 177-187. | 2.3 | 59 |

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|----|--|----|-----------|
| 37 | Gain-based Exploration: From Multi-armed Bandits to Partially Observable Environments. , 2007, , . | | 5 |
| 38 | Robot Exploration by Subjectively Maximizing Objective Information Gain. , 0, , . | | 0 |
| 39 | Grid Cells Lose Coherence in Realistic Environments. , 0, , . | | 0 |