

# Wenyang Gan

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/2341401/publications.pdf>

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2258059

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92  
citing authors

#	ARTICLE	IF	CITATIONS
1	QPSO-model predictive control-based approach to dynamic trajectory tracking control for unmanned underwater vehicles. Ocean Engineering, 2018, 158, 208-220.	4.3	71
2	Model Predictive Adaptive Constraint Tracking Control for Underwater Vehicles. IEEE Transactions on Industrial Electronics, 2020, 67, 7829-7840.	7.9	53
3	A Hybrid Control Strategy of 7000 m-Human Occupied Vehicle Tracking Control. IEEE Transactions on Intelligent Vehicles, 2020, 5, 251-264.	12.7	10
4	A Model Predictive Adaptive Control Algorithm for Human Occupied Vehicle. , 2019, , .		2