

Ba-Phuc Huynh

List of Publications by Year in descending order

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#	ARTICLE	IF	CITATIONS
1	Force/Position Hybrid Control for a Hexa Robot Using Gradient Descent Iterative Learning Control Algorithm. IEEE Access, 2019, 7, 72329-72342.	4.2	22
2	Dynamic Filtered Path Tracking Control for a 3RRR Robot Using Optimal Recursive Path Planning and Vision-Based Pose Estimation. IEEE Access, 2020, 8, 174736-174750.	4.2	8
3	Optimal Fuzzy Impedance Control for a Robot Gripper Using Gradient Descent Iterative Learning Control in Fuzzy Rule Base Design. Applied Sciences (Switzerland), 2020, 10, 3821.	2.5	5
4	Vision/Position Hybrid Control for a Hexa Robot Using Bacterial Foraging Optimization in Real-time Pose Adjustment. Symmetry, 2020, 12, 564.	2.2	5
5	Dynamic Hybrid Filter for Vision-Based Pose Estimation of a Hexa Parallel Robot. Journal of Sensors, 2021, 2021, 1-16.	1.1	3