

Yuhan Chen

List of Publications by Year in descending order

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2258059

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2272923

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4
times ranked

49
citing authors

#	ARTICLE	IF	CITATIONS
1	Collision-Free Path Planning Method for Robots Based on an Improved Rapidly-Exploring Random Tree Algorithm. Applied Sciences (Switzerland), 2020, 10, 1381.	2.5	45
2	Model Predictive Control With Integral Compensation for Motion Control of Robot Manipulator in Joint and Task Spaces. IEEE Access, 2020, 8, 107063-107075.	4.2	17
3	A General Approach Based on Newton's Method and Cyclic Coordinate Descent Method for Solving the Inverse Kinematics. Applied Sciences (Switzerland), 2019, 9, 5461.	2.5	5
4	Closed-form camera pose and plane parameters estimation for moments-based visual servoing of planar objects. International Journal of Advanced Robotic Systems, 2022, 19, 172988062210997.	2.1	1