

Xian-min Zhang

List of Publications by Year in descending order

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284
papers

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all docs

291
docs citations

291
times ranked

2730
citing authors

#	ARTICLE	IF	CITATIONS
1	Intelligent fault diagnosis of rolling bearings based on normalized CNN considering data imbalance and variable working conditions. Knowledge-Based Systems, 2020, 199, 105971.	4.0	220
2	Design of compliant mechanisms using continuum topology optimization: A review. Mechanism and Machine Theory, 2020, 143, 103622.	2.7	218
3	Input coupling analysis and optimal design of a 3-DOF compliant micro-positioning stage. Mechanism and Machine Theory, 2008, 43, 400-410.	2.7	157
4	Active vibration control of a flexible beam using a non-collocated acceleration sensor and piezoelectric patch actuator. Journal of Sound and Vibration, 2009, 326, 438-455.	2.1	121
5	Deep multi-scale convolutional transfer learning network: A novel method for intelligent fault diagnosis of rolling bearings under variable working conditions and domains. Neurocomputing, 2020, 407, 24-38.	3.5	105
6	Design and Myoelectric Control of an Anthropomorphic Prosthetic Hand. Journal of Bionic Engineering, 2017, 14, 47-59.	2.7	95
7	Dynamic analysis of a 3-RRR parallel mechanism with multiple clearance joints. Mechanism and Machine Theory, 2014, 78, 105-115.	2.7	90
8	The Development of a New Piezoresistive Pressure Sensor for Low Pressures. IEEE Transactions on Industrial Electronics, 2018, 65, 6487-6496.	5.2	86
9	Optimal design of a planar parallel 3-DOF nanopositioner with multi-objective. Mechanism and Machine Theory, 2017, 112, 61-83.	2.7	82
10	A robust weld seam recognition method under heavy noise based on structured-light vision. Robotics and Computer-Integrated Manufacturing, 2020, 61, 101821.	6.1	80
11	Error modelling and motion reliability analysis of a planar parallel manipulator with multiple uncertainties. Mechanism and Machine Theory, 2018, 124, 55-72.	2.7	77
12	A review of nonlinear hysteresis modeling and control of piezoelectric actuators. AIP Advances, 2019, 9, .	0.6	74
13	Parameters Optimization and Experiment of A Planar Parallel 3-DOF Nanopositioning System. IEEE Transactions on Industrial Electronics, 2018, 65, 2388-2397.	5.2	72
14	A planar 3-DOF nanopositioning platform with large magnification. Precision Engineering, 2016, 46, 221-231.	1.8	66
15	Design and analysis of a multi-notched flexure hinge for compliant mechanisms. Precision Engineering, 2017, 48, 292-304.	1.8	66
16	A 213-line topology optimization code for geometrically nonlinear structures. Structural and Multidisciplinary Optimization, 2019, 59, 1863-1879.	1.7	62
17	A new topology optimization method for planar compliant parallel mechanisms. Mechanism and Machine Theory, 2016, 95, 42-58.	2.7	60
18	Deep multi-scale adversarial network with attention: A novel domain adaptation method for intelligent fault diagnosis. Journal of Manufacturing Systems, 2021, 59, 565-576.	7.6	60

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19	Classification of Solder Joint Using Feature Selection Based on Bayes and Support Vector Machine. IEEE Transactions on Components, Packaging and Manufacturing Technology, 2013, 3, 516-522.	1.4	59
20	Topology optimization of hinge-free compliant mechanisms with multiple outputs using level set method. Structural and Multidisciplinary Optimization, 2013, 47, 659-672.	1.7	58
21	Optimization of a 2-DOF micro-positioning stage using corrugated flexure units. Mechanism and Machine Theory, 2018, 121, 683-696.	2.7	57
22	Nonlinear analysis and optimal design of a novel piezoelectric-driven compliant microgripper. Mechanism and Machine Theory, 2017, 118, 32-52.	2.7	54
23	Hybrid flexure hinges. Review of Scientific Instruments, 2013, 84, 085004.	0.6	53
24	A new level set method for topology optimization of distributed compliant mechanisms. International Journal for Numerical Methods in Engineering, 2012, 91, 843-871.	1.5	51
25	Mechanical Structural Design of a Piezoresistive Pressure Sensor for Low-Pressure Measurement: A Computational Analysis by Increases in the Sensor Sensitivity. Sensors, 2018, 18, 2023.	2.1	51
26	Unified motion reliability analysis and comparison study of planar parallel manipulators with interval joint clearance variables. Mechanism and Machine Theory, 2019, 138, 58-75.	2.7	50
27	Design and analysis of a high-accuracy flexure hinge. Review of Scientific Instruments, 2016, 87, 055106.	0.6	49
28	A generalized Prandtl-Ishlinskii model for characterizing the rate-independent and rate-dependent hysteresis of piezoelectric actuators. Review of Scientific Instruments, 2016, 87, 035002.	0.6	47
29	Design of buckling-induced mechanical metamaterials for energy absorption using topology optimization. Structural and Multidisciplinary Optimization, 2018, 58, 1395-1410.	1.7	47
30	Structural topology and shape optimization using a level set method with distance-suppression scheme. Computer Methods in Applied Mechanics and Engineering, 2015, 283, 1214-1239.	3.4	45
31	Full closed-loop controls of micro/nano positioning system with nonlinear hysteresis using micro-vision system. Sensors and Actuators A: Physical, 2017, 257, 125-133.	2.0	44
32	Feature-Extraction-Based Inspection Algorithm for IC Solder Joints. IEEE Transactions on Components, Packaging and Manufacturing Technology, 2011, 1, 689-694.	1.4	43
33	A comparative study of planar 3-RRR and 4-RRR mechanisms with joint clearances. Robotics and Computer-Integrated Manufacturing, 2016, 40, 24-33.	6.1	42
34	Precision Alignment of Optical Fibers Based on Telecentric Stereo Microvision. IEEE/ASME Transactions on Mechatronics, 2016, 21, 1924-1934.	3.7	42
35	Design of single-axis flexure hinges using continuum topology optimization method. Science China Technological Sciences, 2014, 57, 560-567.	2.0	41
36	Topology optimization of a cable-driven soft robotic gripper. Structural and Multidisciplinary Optimization, 2020, 62, 2749-2763.	1.7	41

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37	Recent advances in non-contact force sensors used for micro/nano manipulation. <i>Sensors and Actuators A: Physical</i> , 2019, 296, 155-177.	2.0	38
38	Imposing minimum length scale in moving morphable component (MMC)-based topology optimization using an effective connection status (ECS) control method. <i>Computer Methods in Applied Mechanics and Engineering</i> , 2019, 351, 667-693.	3.4	37
39	Level Set-Based Topology Optimization of Hinge-Free Compliant Mechanisms Using a Two-Step Elastic Modeling Method. <i>Journal of Mechanical Design, Transactions of the ASME</i> , 2014, 136, .	1.7	36
40	The recognition of multi-finger prehensile postures using LDA. <i>Biomedical Signal Processing and Control</i> , 2013, 8, 706-712.	3.5	35
41	An enhanced Bouc-Wen model for characterizing rate-dependent hysteresis of piezoelectric actuators. <i>Review of Scientific Instruments</i> , 2018, 89, 115002.	0.6	35
42	Structural Topology Optimization Using a Moving Morphable Component-Based Method Considering Geometrical Nonlinearity. <i>Journal of Mechanical Design, Transactions of the ASME</i> , 2018, 140, .	1.7	35
43	Deep multi-scale separable convolutional network with triple attention mechanism: A novel multi-task domain adaptation method for intelligent fault diagnosis. <i>Expert Systems With Applications</i> , 2021, 182, 115087.	4.4	35
44	Realtime in-plane displacements tracking of the precision positioning stage based on computer micro-vision. <i>Mechanical Systems and Signal Processing</i> , 2019, 124, 111-123.	4.4	34
45	A multi-objective method of hinge-free compliant mechanism optimization. <i>Structural and Multidisciplinary Optimization</i> , 2014, 49, 431-440.	1.7	33
46	Pseudo-rigid-body model for corrugated cantilever beam used in compliant mechanisms. <i>Chinese Journal of Mechanical Engineering (English Edition)</i> , 2014, 27, 122-129.	1.9	31
47	Minimizing the influence of revolute joint clearance using the planar redundantly actuated mechanism. <i>Robotics and Computer-Integrated Manufacturing</i> , 2017, 46, 104-113.	6.1	31
48	Vibration control of a pneumatic driven piezoelectric flexible manipulator using self-organizing map based multiple models. <i>Mechanical Systems and Signal Processing</i> , 2016, 70-71, 345-372.	4.4	30
49	Line-based calibration of a micro-vision motion measurement system. <i>Optics and Lasers in Engineering</i> , 2017, 93, 40-46.	2.0	30
50	Adaptive positioning control of an ultrasonic linear motor system. <i>Robotics and Computer-Integrated Manufacturing</i> , 2017, 44, 156-173.	6.1	30
51	A CPRBM-based method for large-deflection analysis of contact-aided compliant mechanisms considering beam-to-beam contacts. <i>Mechanism and Machine Theory</i> , 2020, 145, 103700.	2.7	30
52	A novel microgripper hybrid driven by a piezoelectric stack actuator and piezoelectric cantilever actuators. <i>Review of Scientific Instruments</i> , 2016, 87, 115003.	0.6	28
53	Design of a rotary dielectric elastomer actuator using a topology optimization method based on pairs of curves. <i>Smart Materials and Structures</i> , 2018, 27, 055011.	1.8	28
54	Design of fully decoupled compliant mechanisms with multiple degrees of freedom using topology optimization. <i>Mechanism and Machine Theory</i> , 2018, 126, 413-428.	2.7	28

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55	Nonlinear Hysteresis Modeling of Piezoelectric Actuators Using a Generalized Bouc-Wen Model. <i>Micromachines</i> , 2019, 10, 183.	1.4	28
56	Compliant mechanisms design based on pairs of curves. <i>Science China Technological Sciences</i> , 2012, 55, 2099-2106.	2.0	27
57	Coupled dynamic modeling of piezo-actuated compliant mechanisms subjected to external loads. <i>Mechanism and Machine Theory</i> , 2021, 160, 104283.	2.7	27
58	Dynamic analysis of a 3-PRR parallel mechanism by considering joint clearances. <i>Nonlinear Dynamics</i> , 2017, 90, 405-423.	2.7	26
59	Design of flexure hinges based on stress-constrained topology optimization. <i>Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science</i> , 2017, 231, 4635-4645.	1.1	26
60	Topology Optimization of Compliant Mechanisms. , 2018, , .		26
61	The recognition of grasping force using LDA. <i>Biomedical Signal Processing and Control</i> , 2019, 47, 393-400.	3.5	26
62	TOPOLOGY OPTIMOZATION OF COMPLIANT MECHANISMS. <i>Jixie Gongcheng Xuebao/Chinese Journal of Mechanical Engineering</i> , 2003, 39, 47.	0.7	25
63	Peg-in-Hole Assembly Based on Two-phase Scheme and F/T Sensor for Dual-arm Robot. <i>Sensors</i> , 2017, 17, 2004.	2.1	24
64	Topology optimization of bistable mechanisms with maximized differences between switching forces in forward and backward direction. <i>Mechanism and Machine Theory</i> , 2019, 139, 131-143.	2.7	23
65	Effects of Temperature and Residual Stresses on the Output Characteristics of a Piezoresistive Pressure Sensor. <i>IEEE Access</i> , 2019, 7, 27668-27676.	2.6	23
66	An 89-line code for geometrically nonlinear topology optimization written in FreeFEM. <i>Structural and Multidisciplinary Optimization</i> , 2021, 63, 1015-1027.	1.7	23
67	A robust construction of normalized CNN for online intelligent condition monitoring of rolling bearings considering variable working conditions and sources. <i>Measurement: Journal of the International Measurement Confederation</i> , 2021, 174, 108973.	2.5	23
68	A monocular vision system for online pose measurement of a 3RRR planar parallel manipulator. <i>Journal of Intelligent and Robotic Systems: Theory and Applications</i> , 2018, 92, 3-17.	2.0	23
69	Displacement measurement system for inverters using computer micro-vision. <i>Optics and Lasers in Engineering</i> , 2016, 81, 113-118.	2.0	22
70	A vision-based vibration sensing and active control for a piezoelectric flexible cantilever plate. <i>JVC/Journal of Vibration and Control</i> , 2016, 22, 1320-1337.	1.5	22
71	A generalized pseudo-rigid-body PPRR model for both straight and circular beams in compliant mechanisms. <i>Mechanism and Machine Theory</i> , 2020, 154, 104054.	2.7	22
72	Pose Sensing and Servo Control of the Compliant Nanopositioners Based on Microscopic Vision. <i>IEEE Transactions on Industrial Electronics</i> , 2021, 68, 3324-3335.	5.2	22

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73	Dynamic responses of flexible linkage mechanisms with viscoelastic constrained layer damping treatment. <i>Computers and Structures</i> , 2001, 79, 1265-1274.	2.4	21
74	Dynamic analysis of flexible linkage mechanisms under uniform temperature change. <i>Journal of Sound and Vibration</i> , 2009, 319, 570-592.	2.1	20
75	Design, modeling and test of a novel compliant orthogonal displacement amplification mechanism for the compact micro-grasping system. <i>Microsystem Technologies</i> , 2017, 23, 2485-2498.	1.2	20
76	Design of diaphragm structure for piezoresistive pressure sensor using topology optimization. <i>Structural and Multidisciplinary Optimization</i> , 2017, 55, 317-329.	1.7	20
77	Online Precise Motion Measurement of 3-DOF Nanopositioners Based on Image Correlation. <i>IEEE Transactions on Instrumentation and Measurement</i> , 2019, 68, 782-790.	2.4	20
78	Nonlinear topology optimization of parallel-grasping microgripper. <i>Precision Engineering</i> , 2019, 60, 152-159.	1.8	20
79	Topology optimization of hinge-free compliant mechanisms using level set methods. <i>Engineering Optimization</i> , 2014, 46, 580-605.	1.5	19
80	Estimation of Handgrip Force from SEMG Based on Wavelet Scale Selection. <i>Sensors</i> , 2018, 18, 663.	2.1	19
81	Explicit structural topology optimization using moving wide Bezier components with constrained ends. <i>Structural and Multidisciplinary Optimization</i> , 2021, 64, 53-70.	1.7	19
82	Design of a compliant adjustable constant-force gripper based on circular beams. <i>Mechanism and Machine Theory</i> , 2022, 173, 104843.	2.7	19
83	A level set method for reliability-based topology optimization of compliant mechanisms. <i>Science in China Series D: Earth Sciences</i> , 2008, 51, 443-455.	0.9	18
84	Climbing gaits of a modular biped climbing robot. , 2009, , .		18
85	Realtime recognition of multi-finger prehensile gestures. <i>Biomedical Signal Processing and Control</i> , 2014, 13, 262-269.	3.5	18
86	Integrated Design of Actuation and Mechanism of Dielectric Elastomers Using Topology Optimization Based on Fat Bezier Curves. <i>Soft Robotics</i> , 2019, 6, 644-656.	4.6	18
87	Topology optimization of compliant mechanism considering actual output displacement using adaptive output spring stiffness. <i>Mechanism and Machine Theory</i> , 2020, 146, 103728.	2.7	18
88	Dynamic analysis of the precision compliant mechanisms considering thermal effect. <i>Precision Engineering</i> , 2010, 34, 592-606.	1.8	17
89	A novel flexural lamina emergent spatial joint. <i>Mechanism and Machine Theory</i> , 2019, 142, 103582.	2.7	17
90	Origami Kaleidocycle-Inspired Symmetric Multistable Compliant Mechanisms. <i>Journal of Mechanisms and Robotics</i> , 2019, 11, .	1.5	17

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91	Vibration control of two-connected piezoelectric flexible plate using nonlinear algorithm and T-S fuzzy controller. <i>Journal of Intelligent Material Systems and Structures</i> , 2015, 26, 219-243.	1.4	16
92	Jacobian-Based Topology Optimization Method Using an Improved Stiffness Evaluation. <i>Journal of Mechanical Design, Transactions of the ASME</i> , 2018, 140, .	1.7	16
93	Design and experimental evaluation of a compliant mechanism-based stepping-motion actuator with multi-mode. <i>Smart Materials and Structures</i> , 2018, 27, 105014.	1.8	16
94	Eye-to-Hand Robotic Visual Tracking Based on Template Matching on FPGAs. <i>IEEE Access</i> , 2019, 7, 88870-88880.	2.6	16
95	Design of Planar Large-Deflection Compliant Mechanisms With Decoupled Multi-Input-Output Using Topology Optimization. <i>Journal of Mechanisms and Robotics</i> , 2019, 11, .	1.5	16
96	Joint torque estimation for the human arm from sEMG using backpropagation neural networks and autoencoders. <i>Biomedical Signal Processing and Control</i> , 2020, 62, 102051.	3.5	16
97	Integrated optimal design of flexible mechanism and vibration control. <i>International Journal of Mechanical Sciences</i> , 2004, 46, 1607-1620.	3.6	15
98	W-Climbot: A modular biped wall-climbing robot. , 2010, , .		15
99	Preload characteristics identification of the piezoelectric-actuated 1-DOF compliant nanopositioning platform. <i>Frontiers of Mechanical Engineering</i> , 2015, 10, 20-36.	2.5	15
100	Topology optimization of distributed flexure hinges with desired performance. <i>Engineering Optimization</i> , 2020, 52, 405-425.	1.5	15
101	Extended Dynamic Stiffness Model for Analyzing Flexure-Hinge Mechanisms With Lumped Compliance. <i>Journal of Mechanical Design, Transactions of the ASME</i> , 2022, 144, .	1.7	15
102	Micro-motion detection of the 3-DOF precision positioning stage based on iterative optimized template matching. <i>Applied Optics</i> , 2017, 56, 9435.	0.9	15
103	Calibration method for hand-eye system with rotation and translation couplings. <i>Applied Optics</i> , 2019, 58, 5375.	0.9	15
104	Optimal Placement of Piezoelectric Sensors and Actuators for Controlled Flexible Linkage Mechanisms. <i>Journal of Vibration and Acoustics, Transactions of the ASME</i> , 2006, 128, 256-260.	1.0	14
105	Stiffness analysis of corrugated flexure beam used in compliant mechanisms. <i>Chinese Journal of Mechanical Engineering (English Edition)</i> , 2015, 28, 776-784.	1.9	14
106	Dynamic analysis of planar 3-RR flexible parallel robots under uniform temperature change. <i>JVC/Journal of Vibration and Control</i> , 2015, 21, 81-104.	1.5	14
107	Bi-directional evolutionary level set method for topology optimization. <i>Engineering Optimization</i> , 2015, 47, 390-406.	1.5	14
108	Damped leaf flexure hinge. <i>Review of Scientific Instruments</i> , 2015, 86, 055002.	0.6	14

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109	Displacement measurement of the compliant positioning stage based on a computer micro-vision method. <i>AIP Advances</i> , 2016, 6, .	0.6	14
110	High-precision displacement measurement method for three degrees of freedom-compliant mechanisms based on computer micro-vision. <i>Applied Optics</i> , 2016, 55, 2594.	2.1	14
111	Topological and Shape Optimization of Flexure Hinges for Designing Compliant Mechanisms Using the Level Set Method. <i>Chinese Journal of Mechanical Engineering (English Edition)</i> , 2019, 32, .	1.9	14
112	Design of dielectric elastomer grippers using Bezier curves. <i>Mechanism and Machine Theory</i> , 2021, 158, 104216.	2.7	14
113	Multiscale Graph-Guided Convolutional Network With Node Attention for Intelligent Health State Diagnosis of a 3-PRR Planar Parallel Manipulator. <i>IEEE Transactions on Industrial Electronics</i> , 2022, 69, 11733-11743.	5.2	14
114	Active noise control of flexible linkage mechanism with piezoelectric actuators. <i>Computers and Structures</i> , 2003, 81, 2045-2051.	2.4	13
115	Fatigue reliability based optimal design of planar compliant micropositioning stages. <i>Review of Scientific Instruments</i> , 2015, 86, 105117.	0.6	13
116	Tracking control of piezoelectric actuators using a polynomial-based hysteresis model. <i>AIP Advances</i> , 2016, 6, .	0.6	13
117	Modular crawling robots using soft pneumatic actuators. <i>Frontiers of Mechanical Engineering</i> , 2021, 16, 163-175.	2.5	13
118	Title is missing!. <i>Multibody System Dynamics</i> , 2002, 8, 51-70.	1.7	12
119	Optimize heat conduction problem using level set method with a weighting based velocity constructing scheme. <i>International Journal of Heat and Mass Transfer</i> , 2016, 99, 441-451.	2.5	12
120	A high accuracy algorithm of displacement measurement for a micro-positioning stage. <i>AIP Advances</i> , 2017, 7, .	0.6	12
121	Vision-based adaptive control of a 3-RRR parallel positioning system. <i>Science China Technological Sciences</i> , 2018, 61, 1253-1264.	2.0	12
122	Dynamic modeling and comparative analysis of a 3-PRR parallel robot with multiple lubricated joints. <i>International Journal of Mechanics and Materials in Design</i> , 2020, 16, 541-555.	1.7	12
123	Analysis and design of spatial compliant mechanisms using a 3-D dynamic stiffness model. <i>Mechanism and Machine Theory</i> , 2022, 168, 104581.	2.7	12
124	Finite dynamic element analysis for high-speed flexible linkage mechanisms. <i>Computers and Structures</i> , 1996, 60, 787-796.	2.4	11
125	1-DoF robotic joint modules and their applications in new robotic systems. , 2009, , .		11
126	Workspace Generation for Multifingered Manipulation. <i>Advanced Robotics</i> , 2011, 25, 2293-2317.	1.1	11

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127	Feature-Based Object Location of IC Pins by Using Fast Run Length Encoding BLOB Analysis. IEEE Transactions on Components, Packaging and Manufacturing Technology, 2014, 4, 1887-1898.	1.4	11
128	A robust rotation-invariance displacement measurement method for a micro-/nano-positioning system. Measurement Science and Technology, 2018, 29, 055402.	1.4	11
129	A Level Set Method With a Bounded Diffusion for Structural Topology Optimization. Journal of Mechanical Design, Transactions of the ASME, 2018, 140, .	1.7	11
130	Design and analysis of corrugated flexure-based lamina emergent spatial joints for symmetrical compliant kaleidocycles. Mechanism and Machine Theory, 2022, 167, 104525.	2.7	11
131	Dynamic Analysis of Planar 3-RRR Flexible Parallel Robots with Dynamic Stiffening. Shock and Vibration, 2014, 2014, 1-13.	0.3	10
132	A New Calibration Method for a Directly Driven 3PRR Positioning System. Journal of Intelligent and Robotic Systems: Theory and Applications, 2017, 85, 613-631.	2.0	10
133	Generating ultra-small droplets based on a double-orifice technique. Sensors and Actuators B: Chemical, 2018, 255, 2011-2017.	4.0	10
134	A magnification-continuous calibration method for SEM-based nanorobotic manipulation systems. Review of Scientific Instruments, 2019, 90, 053706.	0.6	10
135	Design and analysis of translational joints using corrugated flexural beams with conic curve segments. Mechanism and Machine Theory, 2019, 132, 223-235.	2.7	10
136	An Improved Template-Matching-Based Pose Tracking Method for Planar Nanopositioning Stages Using Enhanced Correlation Coefficient. IEEE Sensors Journal, 2020, 20, 6378-6387.	2.4	10
137	An Approach for Geometrically Nonlinear Topology Optimization Using Moving Wide-Bandwidth Components With Constrained Ends. Journal of Mechanical Design, Transactions of the ASME, 2022, 144, .	1.7	10
138	Enhancing Dynamic Bandwidth of Amplified Piezoelectric Actuators by a Hybrid Lever and Bridge-Type Compliant Mechanism. Actuators, 2022, 11, 134.	1.2	10
139	Topology optimization of compliant mechanisms with anisotropic composite materials. , 2010, , .		9
140	An intelligent environmental monitoring system based on autonomous mobile robot. , 2011, , .		9
141	A kind of soft pneumatic actuator based on multi-material 3D print technology. , 2017, , .		9
142	Peg-in-hole assembly based on hybrid vision/force guidance and dual-arm coordination. , 2017, , .		9
143	Natural Gesture Control of a Delta Robot Using Leap Motion. Journal of Physics: Conference Series, 2019, 1187, 032042.	0.3	9
144	A Simultaneous Optimization Method of Calibration and Measurement for a Typical Handâ€œEye Positioning System. IEEE Transactions on Instrumentation and Measurement, 2021, 70, 1-11.	2.4	9

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145	Topology optimization of multiple inputs and multiple outputs compliant mechanisms. Chinese Journal of Mechanical Engineering (English Edition), 2007, 20, 82.	1.9	9
146	TOPOLOGY OPTIMIZATION OF MULTIPLE INPUTS AND OUTPUTS COMPLIANT MECHANISM WITH COUPLING TERMS CONTROL. Jixie Gongcheng Xuebao/Chinese Journal of Mechanical Engineering, 2006, 42, 162.	0.7	9
147	A high speed AOI algorithm for chip component based on image difference. , 2009, , .		8
148	Topology optimization of thermo-mechanical continuum structure. , 2010, , .		8
149	A Design Method for LEDs Arrays Structure Illumination. Journal of Display Technology, 2016, 12, 1177-1184.	1.3	8
150	Error modeling and calibration of a 4á¹žRR redundant positioning system. AIP Advances, 2017, 7, 095009.	0.6	8
151	Exploration of Translational Joint Design Using Corrugated Flexure Units With BÃ©zier Curve Segments. Journal of Mechanical Design, Transactions of the ASME, 2019, 141, .	1.7	8
152	Development of a 3-PRR Precision Tracking System with Full Closed-Loop Measurement and Control. Sensors, 2019, 19, 1756.	2.1	8
153	Dynamic analysis of open-loop mechanisms with multiple spatial revolute clearance joints. Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering Science, 2019, 233, 593-610.	1.1	8
154	Design of dielectric elastomer actuators using topology optimization on electrodes. Smart Materials and Structures, 2020, 29, 075029.	1.8	8
155	Single-step printing of high-resolution, high-aspect ratio silver lines through laser-induced forward transfer. Optics and Laser Technology, 2021, 133, 106514.	2.2	8
156	Topology optimization of flexure hinges with a prescribed compliance matrix based on the adaptive spring model and stress constraint. Precision Engineering, 2021, 72, 397-408.	1.8	8
157	Hybrid explicitâ€“implicit topology optimization method for the integrated layout design of compliant mechanisms and actuators. Mechanism and Machine Theory, 2022, 171, 104750.	2.7	8
158	A Velocity Predictorâ€“Corrector Scheme in Level Set-Based Topology Optimization to Improve Computational Efficiency. Journal of Mechanical Design, Transactions of the ASME, 2014, 136, .	1.7	7
159	Study on Residual Vibration Suppress of a 3-DOF Flexible Parallel Robot Mechanism. Sensors, 2018, 18, 4145.	2.1	7
160	Design of dielectric elastomer actuator using topology optimization method based on genetic algorithm. Smart Materials and Structures, 2019, 28, 065013.	1.8	7
161	Development of an SEMG-Handgrip Force Model Based on Cross Model Selection. IEEE Sensors Journal, 2019, 19, 1829-1838.	2.4	7
162	A projective transformation-based topology optimization using moving morphable components. Computer Methods in Applied Mechanics and Engineering, 2021, 376, 113646.	3.4	7

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163	Spatial compliance modeling and optimization of a translational joint using corrugated flexure units. <i>Mechanism and Machine Theory</i> , 2022, 176, 104962.	2.7	7
164	An AOI algorithm for PCB based on feature extraction. , 2008, , .		6
165	Maximization of Values of Simple and Multiple Eigenfrequencies of Continuum Structures Using Topology Optimization. , 2009, , .		6
166	Experiments on resonant vibration suppression of a piezoelectric flexible clamped-clamped plate using filtered-U least mean square algorithm. <i>Journal of Intelligent Material Systems and Structures</i> , 2016, 27, 166-194.	1.4	6
167	A simplified focusing and astigmatism correction method for a scanning electron microscope. <i>AIP Advances</i> , 2018, 8, .	0.6	6
168	A novel compression-based compliant orthogonal displacement amplification mechanism for the typical actuators used in micro-grasping. <i>Sensors and Actuators A: Physical</i> , 2019, 297, 111463.	2.0	6
169	Multi-target tracking for automated RF on-wafer probing based on template matching. , 2019, , .		6
170	Laser direct printing of solder paste. <i>AIP Advances</i> , 2019, 9, 125306.	0.6	6
171	Fuzzy-PI double-layer stability control of an online vision-based tracking system. <i>Intelligent Service Robotics</i> , 2021, 14, 187-197.	1.6	6
172	Design of compliant mechanisms: An explicit topology optimization method using end-constrained spline curves with variable width. <i>Mechanism and Machine Theory</i> , 2022, 171, 104713.	2.7	6
173	A Novel Semi-Supervised Graph-Guided Approach for Intelligent Health State Diagnosis of a 3-PRR Planar Parallel Manipulator. <i>IEEE/ASME Transactions on Mechatronics</i> , 2022, 27, 4786-4797.	3.7	6
174	A novel mobile robot capable of changing its wheel distance and body configuration. , 2009, , .		5
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