Tor Arne Johansen

List of Publications by Citations

291 papers	5,424 citations	35 h-index	63 g-index
310 ext. papers	7,048 ext. citations	3.3 avg, IF	6.51 L-index

#	Paper	IF	Citations
291	Control allocation—A survey. *Automatica*, **2013**, 49, 1087-1103	5.7	560
290	An algorithm for multi-parametric quadratic programming and explicit MPC solutions. *Automatica*, **2003**, 39, 489-497	5.7	384
289	Approximate explicit receding horizon control of constrained nonlinear systems. *Automatica*, **2004**, 40, 293-300	5.7	176
288	Stabilization of Automotive Vehicles Using Active Steering and Adaptive Brake Control Allocation. *IEEE Transactions on Control Systems Technology*, **2010**, 18, 545-558	4.8	153
287	Ship Collision Avoidance and COLREGS Compliance Using Simulation-Based Control Behavior Selection With Predictive Hazard Assessment. *IEEE Transactions on Intelligent Transportation Systems*, **2016**, 17, 3407-3422	6.1	115
286	Fault tolerant control allocation using unknown input observers. *Automatica*, **2014**, 50, 1891-1897	5.7	111
285	Adaptive control allocation. *Automatica*, **2008**, 44, 2754-2765	5.7	106
284	A Survey of Control Allocation Methods for Ships and Underwater Vehicles **2006**,		90
283	On Tikhonov regularization, bias and variance in nonlinear system identification. *Automatica*, **1997**, 33, 441-446	5.7	84
282	Optimization of Wireless Sensor Network and UAV Data Acquisition. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2015**, 78, 159-179	2.9	77
281	Dynamic Positioning With Model Predictive Control. *IEEE Transactions on Control Systems Technology*, **2016**, 24, 1340-1353	4.8	74
280	Computation of Lyapunov functions for smooth nonlinear systems using convex optimization. *Automatica*, **2000**, 36, 1617-1626	5.7	73
279	Identification of non-linear systems using empirical data and prior knowledge—an optimization approach. *Automatica*, **1996**, 32, 337-356	5.7	72
278	Optimal constrained control allocation in marine surface vessels with rudders. *Control Engineering Practice*, **2008**, 16, 457-464	3.9	71
277	Efficient Optimal Constrained Control Allocation via Multiparametric Programming. *Journal of Guidance, Control, and Dynamics*, **2005**, 28, 506-515	2.1	70
276	Globally exponentially stable attitude and gyro bias estimation with application to GNSS/INS integration. *Automatica*, **2015**, 51, 158-166	5.7	68
275	Hardware Synthesis of Explicit Model Predictive Controllers. *IEEE Transactions on Control Systems Technology*, **2007**, 15, 191-197	4.8	67

274	Path Planning for UAVs Under Communication Constraints Using SPLAT! and MILP. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2012**, 65, 265-282	2.9	65
273	Explicit sub-optimal linear quadratic regulation with state and input constraints. *Automatica*, **2002**, 38, 1099-1111	5.7	64
272	Using hash tables to manage the time-storage complexity in a point location problem: Application to explicit model predictive control. *Automatica*, **2011**, 47, 571-577	5.7	63
271	On the facet-to-facet property of solutions to convex parametric quadratic programs. *Automatica*, **2006**, 42, 2209-2214	5.7	61
270	**2015**,		56
269	Explicit stochastic predictive control of combustion plants based on Gaussian process models. *Automatica*, **2008**, 44, 1621-1631	5.7	55
268	Energy-based control of a distributed solar collector field. *Automatica*, **2002**, 38, 1191-1199	5.7	55
267	Explicit Nonlinear Model Predictive Control. *Lecture Notes in Control and Information Sciences*, **2012**,	0.5	53
266	On estimation of wind velocity, angle-of-attack and sideslip angle of small UAVs using standard sensors **2015**,		51
265	Neural network augmented identification of underwater vehicle models. *Control Engineering Practice*, **2007**, 15, 715-725	3.9	50
264	Do it yourself hyperspectral imager for handheld to airborne operations. *Optics Express*, **2018**, 26, 6021-6035	3.3	41
263	Flexible Piecewise Function Evaluation Methods Based on Truncated Binary Search Trees and Lattice Representation in Explicit MPC. *IEEE Transactions on Control Systems Technology*, **2012**, 20, 632-640	4.8	41
262	Gain-scheduled control of a solar power plant. *Control Engineering Practice*, **2000**, 8, 1011-1022	3.9	39
261	Toward Dependable Embedded Model Predictive Control. *IEEE Systems Journal*, **2017**, 11, 1208-1219	4.3	38
260	. *IEEE Access*, **2015**, 3, 2065-2079	3.5	37
259	Computation, approximation and stability of explicit feedback min□max nonlinear model predictive control. *Automatica*, **2009**, 45, 1134-1143	5.7	37
258	Nonlinear observer for GNSS-aided inertial navigation with quaternion-based attitude estimation **2013**,		36
257	A Four-Quadrant Thrust Estimation Scheme for Marine Propellers: Theory and Experiments. *IEEE Transactions on Control Systems Technology*, **2009**, 17, 215-226	4.8	36

256	Nonlinear Control with Swing Damping of a Multirotor UAV with Suspended Load. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2017**, 88, 379-394	2.9	35
255	Observers for interconnected nonlinear and linear systems. *Automatica*, **2012**, 48, 1339-1346	5.7	35
254	Battery Power Smoothing Control in a Marine Electric Power Plant Using Nonlinear Model Predictive Control. *IEEE Transactions on Control Systems Technology*, **2017**, 25, 1449-1456	4.8	34
253	UAVs Trajectory Planning by Distributed MPC under Radio Communication Path Loss Constraints. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2015**, 79, 115-134	2.9	34
252	Linear Moving Horizon Estimation With Pre-Estimating Observer. *IEEE Transactions on Automatic Control*, **2010**, 55, 2363-2368	5.9	32
251	Model predictive control for a multi-body slung-load system. *Robotics and Autonomous Systems*, **2017**, 92, 1-11	3.5	31
250	An improved algorithm for combinatorial multi-parametric quadratic programming. *Automatica*, **2013**, 49, 1370-1376	5.7	31
249	Design and Comparison of Explicit Model Predictive Controllers for an Electropneumatic Clutch Actuator Using On/Off Valves. *IEEE/ASME Transactions on Mechatronics*, **2011**, 16, 665-673	5.5	31
248	COMPLEXITY REDUCTION IN EXPLICIT LINEAR MODEL PREDICTIVE CONTROL. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2002**, 35, 189-194		31
247	Dynamic Positioning System as Dynamic Energy Storage on Diesel-Electric Ships. *IEEE Transactions on Power Systems*, **2014**, 29, 3086-3091	7	30
246	Integrated Multimodel Control of Nonlinear Systems Based on Gap Metric and Stability Margin. *Industrial & Engineering Chemistry Research*, **2014**, 53, 10206-10215	3.9	30
245	Lyapunov-Based Integrator Resetting With Application to Marine Thruster Control. *IEEE Transactions on Control Systems Technology*, **2008**, 16, 908-917	4.8	30
244	Linear MPC with optimal prioritized infeasibility handling: application, computational issues and stability. *Automatica*, **2001**, 37, 1835-1843	5.7	30
243	Survey on Communication and Networks for Autonomous Marine Systems. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2019**, 95, 789-813	2.9	30
242	Nonlinear Observers for Integrated INS/GNSS Navigation: Implementation Aspects. *IEEE Control Systems*, **2017**, 37, 59-86	2.9	28
241	Cooperative Control for Multirotors Transporting an Unknown Suspended Load Under Environmental Disturbances. *IEEE Transactions on Control Systems Technology*, **2020**, 28, 653-660	4.8	28
240	Unmanned aerial vehicle as communication relay for autonomous underwater vehicle Field tests **2014**,		27
239	An Efficient Real-Time FPGA Implementation of the CCSDS-123 Compression Standard for Hyperspectral Images. *IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing*, **2018**, 11, 3841-3852	4.7	27

238	The eXogenous Kalman Filter (XKF). *International Journal of Control*, **2017**, 90, 161-167	1.5	26
237	Computational Aspects of Approximate Explicit Nonlinear Model Predictive Control **2007**, 181-192		26
236	A Parallel FPGA Implementation of the CCSDS-123 Compression Algorithm. *Remote Sensing*, **2019**, 11, 673	5	24
235	Coordinating UAVs and AUVs for oceanographic field experiments: Challenges and lessons learned **2014**,		24
234	Nonlinear control of a multirotor UAV with suspended load **2015**,		23
233	Attitude estimation by multiplicative exogenous Kalman filter. *Automatica*, **2018**, 95, 347-355	5.7	22
232	Autonomous Unmanned Aerial Vehicles in Search and Rescue Missions Using Real-Time Cooperative Model Predictive Control. *Sensors*, **2019**, 19,	3.8	21
231	Integrated Multilinear Model Predictive Control of Nonlinear Systems Based on Gap Metric. *Industrial & Engineering Chemistry Research*, **2015**, 54, 6002-6011	3.9	21
230	Autonomous visual navigation of Unmanned Aerial Vehicle for wind turbine inspection **2015**,		21
229	Combining model-free and model-based angle of attack estimation for small fixed-wing UAVs using a standard sensor suite **2016**,		20
228	Linear constrained moving horizon estimator with pre-estimating observer. *Systems and Control Letters*, **2014**, 67, 40-45	2.4	20
227	Dual-Mode Switched Control of an Electropneumatic Clutch Actuator. *IEEE/ASME Transactions on Mechatronics*, **2010**,	5.5	20
226	System-Wide Harmonic Mitigation in a Diesel-Electric Ship by Model Predictive Control. *IEEE Transactions on Industrial Electronics*, **2016**, 63, 4008-4019	8.9	19
225	Explicit output-feedback nonlinear predictive control based on black-box models. *Engineering Applications of Artificial Intelligence*, **2011**, 24, 388-397	7.2	19
224	Performance evaluation of cooperative relay and Particle Swarm Optimization path planning for UAV and wireless sensor network **2013**,		18
223	Icing detection and identification for unmanned aerial vehicles: Multiple model adaptive estimation **2015**,		17
222	Cluster-based communication topology selection and UAV path planning in wireless sensor networks **2013**,		17
221	Estimation of states and parameters for linear systems with nonlinearly parameterized perturbations. *Systems and Control Letters*, **2011**, 60, 771-777	2.4	17

220	Explicit model predictive control of gas–liquid separation plant via orthogonal search tree partitioning. *Computers and Chemical Engineering*, **2004**, 28, 2481-2491	4	17
219	Integrated Monitoring of Mola mola Behaviour in Space and Time. *PLoS ONE*, **2016**, 11, e0160404	3.7	17
218	Nonlinear observer design for GNSS-aided inertial navigation systems with time-delayed GNSS measurements. *Control Engineering Practice*, **2017**, 60, 39-50	3.9	16
217	Unmanned aerial surveillance system for hazard collision avoidance in autonomous shipping **2016**,		16
216	Asymptotic Stability of Perturbation-Based Extremum-Seeking Control for Nonlinear Plants. *IEEE Transactions on Automatic Control*, **2017**, 62, 2302-2317	5.9	16
215	Unmanned aerial system architecture for maritime missions. design & hardware description **2015**,		15
214	Model-Based Actuator Fault Diagnosis in Multirotor UAVs* **2018**,		15
213	Real-time georeferencing of thermal images using small fixed-wing UAVs in maritime environments. *ISPRS Journal of Photogrammetry and Remote Sensing*, **2019**, 154, 84-97	11.8	14
212	Unmanned Aerial Vehicles as Data Mules: An Experimental Assessment. *IEEE Access*, **2017**, 5, 24716-24726	3.5	14
211	Nonlinear observer with time-varying gains for inertial navigation aided by satellite reference systems in dynamic positioning **2014**,		14
210	Moving horizon observer with regularisation for detectable systems without persistence of excitation. *International Journal of Control*, **2011**, 84, 1041-1054	1.5	14
209	Identification of underwater vehicle hydrodynamic coefficients using free decay tests. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2004**, 37, 363-368		14
208	A METHOD FOR OBTAINING CONTINUOUS SOLUTIONS TO MULTIPARAMETRIC LINEAR PROGRAMS. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2005**, 38, 253-258		14
207	Nonlinear Observer for Tightly Integrated Inertial Navigation Aided by Pseudo-Range Measurements. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2017**, 139,	1.6	13
206	Combinatorial Approach Toward Multiparametric Quadratic Programming Based on Characterizing Adjacent Critical Regions. *IEEE Transactions on Automatic Control*, **2018**, 63, 3221-3231	5.9	13
205	Nonlinear Observers for GNSS- and Camera-Aided Inertial Navigation of a Fixed-Wing UAV. *IEEE Transactions on Control Systems Technology*, **2018**, 26, 1884-1891	4.8	13
204	Cooperative path-following for multirotor UAVs with a suspended payload **2015**,		13
203	Optimizing adaptive control allocation with actuator dynamics **2007**,		13

202	Explicit stochastic Nonlinear Predictive Control based on Gaussian process models **2007**,		13
201	Redundant MEMS-Based Inertial Navigation Using Nonlinear Observers. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2018**, 140,	1.6	12
200	Diagnosis of Icing and Actuator Faults in UAVs Using LPV Unknown Input Observers. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2018**, 91, 651-665	2.9	12
199	. *IEEE Transactions on Aerospace and Electronic Systems*, **2016**, 52, 1631-1643	3.7	12
198	A communication bridge between underwater sensors and unmanned vehicles using a surface wireless sensor network - design and validation **2016**,		12
197	Experiences with coastal and maritime UAS BLOS operation with phased-array antenna digital payload data link **2014**,		12
196	A ligth-weight thermal camera payload with georeferencing capabilities for small fixed-wing UAVs **2015**,		12
195	Path- and data transmission planning for cooperating UAVs in delay tolerant network **2012**,		12
194	Estimation of road inclination and bank angle in automotive vehicles **2009**,		12
193	On the Usage of Low-Cost MEMS Sensors, Strapdown Inertial Navigation, and Nonlinear Estimation Techniques in Dynamic Positioning. *IEEE Journal of Oceanic Engineering*, **2021**, 46, 24-39	3.3	12
192	**2018**,		12
191	Experimental validation of a uniformly semi-globally exponentially stable non-linear observer for GNSS- and camera-aided inertial navigation for fixed-wing UAVs **2015**,		11
190	Autonomous recovery of a fixed-wing UAV using a net suspended by two multirotor UAVs. *Journal of Field Robotics*, **2018**, 35, 717-731	6.7	11
189	Nonlinear Observer for Tightly Coupled Integration of Pseudorange and Inertial Measurements. *IEEE Transactions on Control Systems Technology*, **2016**, 24, 2199-2206	4.8	11
188	Icing detection in unmanned aerial vehicles with longitudinal motion using an LPV unknown input observer **2015**,		11
187	Thrust allocation with power management functionality on dynamically positioned vessels **2012**,		11
186	Nonlinear filtering with exogenous Kalman filter and double Kalman filter **2016**,		11
185	Robust fault and icing diagnosis in unmanned aerial vehicles using LPV interval observers. *International Journal of Robust and Nonlinear Control*, **2019**, 29, 5456-5480	3.6	11

184	Estimation of Flow Rate and Viscosity in a Well with an Electric Submersible Pump using Moving Horizon Estimation**This work is funded by the Research Council of Norway and Statoil through the PETROMAKS project No. 215684: Enabling High-Performance Safety-Critical Offshore and Subsea Automatic Control Systems Using Embedded Optimization (emOpt). *IFAC-PapersOnLine*, **2015**, 48, 140-146	0.7	10
183	User-Configurable Timing and Navigation for UAVs. *Sensors*, **2018**, 18,	3.8	10
182	Multi-Resolution Explicit Model Predictive Control: Delta-Model Formulation and Approximation. *IEEE Transactions on Automatic Control*, **2013**, 58, 2979-2984	5.9	10
181	SyncBoard - A high accuracy sensor timing board for UAV payloads **2017**,		10
180	Estimation of wind velocities and aerodynamic coefficients for UAVs using standard autopilot sensors and a Moving Horizon Estimator **2017**,		10
179	Nonlinear observer for inertial navigation aided by pseudo-range and range-rate measurements **2015**,		10
178	Non-linear model predictive control for guidance of a fixed-wing UAV in precision deep stall landing **2015**,		10
177	Task assignment for cooperating UAVs under radio propagation path loss constraints **2012**,		10
176	A Nonlinear Model-Based Wind Velocity Observer for Unmanned Aerial Vehicles. *IFAC-PapersOnLine*, **2016**, 49, 276-283	0.7	10
175	Advancing multi-vehicle deployments in oceanographic field experiments. *Autonomous Robots*, **2019**, 43, 1555-1574	3	10
174	Fault tolerant control of uncertain dynamical systems using interval virtual actuators. *International Journal of Robust and Nonlinear Control*, **2018**, 28, 611-624	3.6	10
173	Autonomous search and tracking of objects using model predictive control of unmanned aerial vehicle and gimbal: Hardware-in-the-loop simulation of payload and avionics **2015**,		9
172	Analysis and design of quadratic parameter varying (QPV) control systems with polytopic attractive region. *Journal of the Franklin Institute*, **2018**, 355, 3488-3507	4	9
171	A virtual vertical reference concept for aided inertial navigation at the sea surface. *Control Engineering Practice*, **2018**, 70, 1-14	3.9	9
170	Regularized Nonlinear Moving-Horizon Observer With Robustness to Delayed and Lost Data. *IEEE Transactions on Control Systems Technology*, **2013**, 21, 2114-2128	4.8	9
169	An unknown input observer approach to icing detection for unmanned aerial vehicles with linearized longitudinal motion **2015**,		9
168	A uniformly semiglobally exponentially stable nonlinear observer for GNSS- and camera-aided inertial navigation **2014**,		9
167	Suspended load motion control using multicopters **2014**,		9

166	Observer and IMU-based detection and isolation of faults in position reference systems and gyrocompasses with dual redundancy in dynamic positioning **2014**,		9
165	Reducing Power Load Fluctuations on Ships Using Power Redistribution Control **2008**, 45, 162-174		9
164	Autonomous ballistic airdrop of objects from a small fixed-wing unmanned aerial vehicle. *Autonomous Robots*, **2020**, 44, 859-875	3	9
163	Design of inertial navigation systems for marine craft with adaptive wave filtering aided by triple-redundant sensor packages. *International Journal of Adaptive Control and Signal Processing*, **2017**, 31, 522-544	2.8	8
162	Improved predictions from measured disturbances in linear model predictive control. *Journal of Process Control*, **2019**, 75, 86-106	3.9	8
161	Tracking of Ocean Surface Objects from Unmanned Aerial Vehicles with a Pan/Tilt Unit using a Thermal Camera. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2018**, 91, 775-793	2.9	8
160	MEMS-based Inertial Navigation on Dynamically Positioned Ships: Dead Reckoning. *IFAC-PapersOnLine*, **2016**, 49, 139-146	0.7	8
159	Guaranteed feasible control allocation using model predictive control. *Control Theory and Technology*, **2019**, 17, 252-264	1	8
158	A Virtual Vertical Reference Concept for GNSS/INS Applications at the Sea Surface. *IFAC-PapersOnLine*, **2015**, 48, 127-133	0.7	8
157	A UAV ice tracking framework for autonomous sea ice management **2017**,		8
156	Redesign and analysis of globally asymptotically stable bearing only SLAM **2017**,		8
155	. *IEEE Transactions on Aerospace and Electronic Systems*, **2020**, 56, 2101-2121	3.7	8
154	Coordinated control concept for recovery of a fixed-wing UAV on a ship using a net carried by multirotor UAVs **2016**,		8
153	Multi-agent informed path planning using the probability hypothesis density. *Autonomous Robots*, **2020**, 44, 913-925	3	7
152	Attitude and Heave Estimation for Ships using MEMS-based Inertial Measurements. *IFAC-PapersOnLine*, **2016**, 49, 568-575	0.7	7
151	Icing detection and identification for unmanned aerial vehicles using adaptive nested multiple models. *International Journal of Adaptive Control and Signal Processing*, **2017**, 31, 1584-1607	2.8	7
150	Approach Methods for Autonomous Precision Aerial Drop from a Small Unmanned Aerial Vehicle. *IFAC-PapersOnLine*, **2017**, 50, 3566-3573	0.7	7
149	Moving horizon estimation for tire-road friction during braking **2010**,		7

148	Explicit Model Predictive Control of an electropneumatic clutch actuator using on/off valves and pulse-width modulation **2009**,		7
147	Transient power control in dynamic positioning - governor feedforward and dynamic thrust allocation. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2012**, 45, 158-163		7
146	Improved Transient Performance by Lyapunov-based Integrator Reset of PI Thruster Control in Extreme Seas **2006**,		7
145	Wheel slip control using gain-scheduled LQ LPV/LMI analysis and experimental results **2003**,		7
144	Wave motion compensation in dynamic positioning of small autonomous vessels. *Journal of Marine Science and Technology*, **2020**, 26, 693	1.7	7
143	. *IEEE Transactions on Aerospace and Electronic Systems*, **2020**, 56, 2157-2173	3.7	7
142	Multi-Agent Formation Tracking for Autonomous Surface Vehicles. *IEEE Transactions on Control Systems Technology*, **2021**, 1-12	4.8	7
141	Fuzzy domain and meta-heuristic algorithm-based collision avoidance control for ships: Experimental validation in virtual and real environment. *Ocean Engineering*, **2021**, 220, 108502	3.9	7
140	Net recovery of UAV with single-frequency RTK GPS **2015**,		6
139	Optimized current reference generation for system-level harmonic mitigation in a diesel-electric ship using non-linear model predictive control **2015**,		6
138	Constrained MPC design for heave disturbance attenuation in offshore drilling systems **2013**,		6
137	Moving Horizon Estimation for Integrated Navigation Filtering. *IFAC-PapersOnLine*, **2015**, 48, 519-526	0.7	6
136	Nonlinear observer for INS aided by time-delayed GNSS measurements: Implementation and UAV experiments **2015**,		6
135	Fault-tolerant control allocation with actuator dynamics: Finite-time control reconfiguration **2014**,		6
134	Adaptive Model Estimation of Vibration Motion for a Nanopositioner With Moving Horizon Optimized Extended Kalman Filter. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2013**, 135,	1.6	6
133	Distributed MPC-Based Path Planning for UAVs under Radio Communication Path Loss Constraints. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2012**, 45, 254-259		6
132	**2009**,		6
131	Explicit Approximate Approach to Feedback Min-Max Model Predictive Control of Constrained Nonlinear Systems **2006**,		6

130	Approaches to explicit Nonlinear Model Predictive Control with reduced partition complexity **2009**,		6
129	Range-based target localization and pursuit with autonomous vehicles: An approach using posterior CRLB and model predictive control. *Robotics and Autonomous Systems*, **2020**, 132, 103608	3.5	6
128	Experimental Heat Loads for Electrothermal Anti-Icing and De-Icing on UAVs. *Aerospace*, **2021**, 8, 83	2.5	6
127	Enhanced Hydroacoustic Range Robustness of Three-Stage Position Filter based on Long Baseline Measurements with Unknown Wave Speed. *IFAC-PapersOnLine*, **2016**, 49, 61-67	0.7	6
126	. *IEEE Transactions on Aerospace and Electronic Systems*, **2021**, 57, 90-104	3.7	6
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124	Fault-Tolerant Control Allocation for Overactuated Nonlinear Systems. *Asian Journal of Control*, **2018**, 20, 621-634	1.7	5
123	Detection of icing and actuators faults in the longitudinal dynamics of small UAVs using an LPV proportional integral unknown input observer **2016**,		5
122	Further results on the exploration of combinatorial tree in multi-parametric quadratic programming **2016**,		5
121	Design and comparison of adaptive estimators for Under-balanced Drilling **2014**,		5
120	Coordinated maritime missions of unmanned vehicles Network architecture and performance analysis **2017**,		5
119	Nonlinear Moving Horizon Observer for Estimation of States and Parameters in Under-Balanced Drilling Operations **2014**,		5
118	Nonlinear Model Predictive Control. *Lecture Notes in Control and Information Sciences*, **2012**, 39-69	0.5	5
117	Multi-parametric Programming. *Lecture Notes in Control and Information Sciences*, **2012**, 1-37	0.5	5
116	Fault-tolerant control allocation: An Unknown Input Observer based approach with constrained output fault directions **2013**,		5
115	Rotary-Wing UAVs Trajectory Planning by Distributed Linear MPC with Reconfigurable Communication Network Topologies. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2013**, 46, 198-205		5
114	A computational approach to explicit feedback stochastic Nonlinear Model Predictive Control **2010**,		5
113	Nonlinear hierarchical control allocation for vehicle yaw stabilization and rollover prevention **2009**,		5

112	Barrier function nonlinear optimization for optimal Decompression of divers **2009**,		5
111	State and parameter estimation for linear systems with nonlinearly parameterized perturbations **2009**,		5
110	**2011**,		5
109	Modeling of Air-Fuel Ratio Dynamics of Gasoline Combustion Engine With ARX Network. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2008**, 130,	1.6	5
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107	Tightly coupled integrated inertial and real-time-kinematic positioning approach using nonlinear observer **2016**,		5
106	A Survey of Practical Design Considerations of Optical Imaging Stabilization Systems for Small Unmanned Aerial Systems. *Sensors*, **2019**, 19,	3.8	5
105	Nonlinear Observer for Tightly Coupled Integrated Inertial Navigation Aided by RTK-GNSS Measurements. *IEEE Transactions on Control Systems Technology*, **2019**, 27, 1084-1099	4.8	5
104	Precision Deep-Stall Landing of Fixed-Wing UAVs Using Nonlinear Model Predictive Control. *Journal of Intelligent and Robotic Systems: Theory and Applications*, **2021**, 101, 1	2.9	5
103	Adaptive Sampling of Ocean Processes Using an AUV with a Gaussian Proxy Model. *IFAC-PapersOnLine*, **2018**, 51, 238-243	0.7	5
102	Exogenous Kalman Filter for State-of-Charge Estimation in Lithium-Ion Batteries **2018**,		5
101	Management of harmonic propagation in a marine vessel by use of optimization **2015**,		4
100	Fault detection in lever-arm-compensated position reference systems based on nonlinear attitude observers and inertial measurements in dynamic positioning **2016**,		4
99	Track-to-track data fusion for Unmanned Traffic Management System **2019**,		4
98	Online Estimation of ShipŘs Mass and Center of Mass Using Inertial Measurements. *IFAC-PapersOnLine*, **2015**, 48, 134-139	0.7	4
97	Autonomous UAV surveillance of a shipŘs path with MPC for maritime situational awareness **2017**,		4
96	Mission performance trade-offs of battery-powered sUAS **2017**,		4
95	Fault diagnosis and fault-tolerant control allocation for a class of nonlinear systems with redundant inputs **2015**,		4

94	On attitude observers and inertial navigation for reference system fault detection and isolation in dynamic positioning **2015**,		4
93	Optimal Decompression of Divers [Applications of Control]. *IEEE Control Systems*, **2011**, 31, 19-28	2.9	4
92	Flexible piecewise function evaluation methods with application to explicit model predictive control **2011**,		4
91	Distributed Path Planning for a UAV Communication Chain by Dual Decomposition. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2012**, 45, 43-48		4
90	The effect of dimensionality reduction on signature-based target detection for hyperspectral remote sensing **2019**,		4
89	A globally exponentially stable non-linear velocity observer for vision-aided UAV dead reckoning **2016**,		4
88	Long-Endurance Green Energy Autonomous Surface Vehicle Control Architecture **2019**,		4
87	Towards autonomous ocean observing systems using Miniature Underwater Gliders with UAV deployment and recovery capabilities **2018**,		4
86	A Satellite-USV System for Persistent Observation of Mesoscale Oceanographic Phenomena. *Remote Sensing*, **2021**, 13, 3229	5	4
85	Spatially indexed clustering for scalable tracking of remotely sensed drift ice **2017**,		3
84	A Fault Tolerant Control Scheme Using the Feasible Constrained Control Allocation Strategy. *International Journal of Automation and Computing*, **2019**, 16, 628-643	3.5	3
83	Feasibility study of a circularly towed cable-body system for UAV applications **2016**,		3
82	An FPGA-oriented HW/SW Codesign of Lucy-Richardson Deconvolution Algorithm for Hyperspectral Images **2019**,		3
81	Flight test results for autonomous icing protection solution for small unmanned aircraft **2017**,		3
80	Lateral vehicle stabilization using constrained nonlinear control **2003**,		3
79	EXPLICIT MIN-MAX MODEL PREDICTIVE CONTROL OF CONSTRAINED NONLINEAR SYSTEMS WITH MODEL UNCERTAINTY. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2005**, 38, 1019-1024		3
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