Zijian Wang

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/2108867/publications.pdf

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| | | 1478505 | 1872680 |
|----------|----------------|--------------|----------------|
| 8 | 527 | 6 | 6 |
| papers | citations | h-index | g-index |
| | | | |
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| | | | |
| 8 | 8 | 8 | 453 |
| all docs | docs citations | times ranked | citing authors |
| | | | |

| # | Article | IF | CITATIONS |
|---|--|------|-----------|
| 1 | Game-Theoretic Planning for Self-Driving Cars in Multivehicle Competitive Scenarios. IEEE Transactions on Robotics, 2021, 37, 1313-1325. | 10.3 | 50 |
| 2 | Multirobot Object Transport via Robust Caging. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2020, 50, 270-280. | 9.3 | 29 |
| 3 | A Real-Time Game Theoretic Planner for Autonomous Two-Player Drone Racing. IEEE Transactions on Robotics, 2020, 36, 1389-1403. | 10.3 | 41 |
| 4 | Agile Coordination and Assistive Collision Avoidance for Quadrotor Swarms Using Virtual Structures. IEEE Transactions on Robotics, 2018, 34, 916-923. | 10.3 | 101 |
| 5 | Fast, On-line Collision Avoidance for Dynamic Vehicles Using Buffered Voronoi Cells. IEEE Robotics and Automation Letters, 2017, 2, 1047-1054. | 5.1 | 153 |
| 6 | Force-Amplifying N-robot Transport System (Force-ANTS) for cooperative planar manipulation without communication. International Journal of Robotics Research, 2016, 35, 1564-1586. | 8.5 | 65 |
| 7 | Kinematic multi-robot manipulation with no communication using force feedback. , 2016, , . | | 68 |
| 8 | Multi-robot manipulation with no communication using only local measurements. , 2015, , . | | 20 |