

Daniel Hernandez Garcia

List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/2058361/publications.pdf>

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17
papers

238
citations

1684188

5
h-index

1474206

9
g-index

17
all docs

17
docs citations

17
times ranked

260
citing authors

| # | ARTICLE | IF | CITATIONS |
|----|---|-----|-----------|
| 1 | The Robot Made Me Do It: Human-Robot Interaction and Risk-Taking Behavior. <i>Cyberpsychology, Behavior, and Social Networking</i> , 2021, 24, 337-342. | 3.9 | 15 |
| 2 | The DREAM Dataset: Supporting a data-driven study of autism spectrum disorder and robot enhanced therapy. <i>PLoS ONE</i> , 2020, 15, e0236939. | 2.5 | 27 |
| 3 | Deploying a Deep Learning Agent for HRI with Potential "end-users" at Multiple Sheltered Housing Sites. , 2019, , . | | 5 |
| 4 | Second Language Tutoring Using Social Robots: A Large-Scale Study. , 2019, , . | | 89 |
| 5 | Robot-Enhanced Therapy: Development and Validation of Supervised Autonomous Robotic System for Autism Spectrum Disorders Therapy. <i>IEEE Robotics and Automation Magazine</i> , 2019, 26, 49-58. | 2.0 | 52 |
| 6 | Social Robots in Therapy and Care. , 2019, , . | | 13 |
| 7 | Visual attention and object naming in humanoid robots using a bio-inspired spiking neural network. <i>Robotics and Autonomous Systems</i> , 2018, 104, 56-71. | 5.1 | 14 |
| 8 | Using a Robot Peer to Encourage the Production of Spatial Concepts in a Second Language. , 2018, , . | | 3 |
| 9 | Social Robots in Therapy. , 2018, , . | | 2 |
| 10 | Task Oriented Control of a Humanoid Robot Through the Implementation of a Cognitive Architecture. <i>Journal of Intelligent and Robotic Systems: Theory and Applications</i> , 2017, 85, 3-25. | 3.4 | 1 |
| 11 | A use case of an adaptive cognitive architecture for the operation of humanoid robots in real environments. <i>International Journal of Advanced Robotic Systems</i> , 2017, 14, 172988141667813. | 2.1 | 0 |
| 12 | Adaptation of Robot Skills Models to New Task Constraints. <i>International Journal of Humanoid Robotics</i> , 2015, 12, 1550024. | 1.1 | 2 |
| 13 | Behavior sequencing based on demonstrations: a case of a humanoid opening a door while walking. <i>Advanced Robotics</i> , 2015, 29, 315-329. | 1.8 | 9 |
| 14 | Generation and adaptation of robot skills models. , 2014, , . | | 1 |
| 15 | Knowledge Base Representation for Humanoid Robot Skills. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2014, 47, 3042-3047. | 0.4 | 3 |
| 16 | Generation of New Robot Skills from Learned Skills. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2014, 47, 3030-3035. | 0.4 | 0 |
| 17 | Framework for Learning and Adaptation of Humanoid Robot Skills to Task Constraints. <i>Advances in Intelligent Systems and Computing</i> , 2014, , 557-572. | 0.6 | 2 |