## Andrea Monteriù

List of Publications by Year in descending order

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170 papers 1,830 citations

393982 19 h-index 377514 34 g-index

176 all docs

176 docs citations

176 times ranked

1724 citing authors

#	Article	IF	CITATIONS
1	Augmenting robot intelligence via EEG signals to avoid trajectory planning mistakes of a smart wheelchair. Journal of Ambient Intelligence and Humanized Computing, 2023, 14, 223-235.	3.3	7
2	Fault Diagnosis of Rotating Machinery Based on Wasserstein Distance and Feature Selection. IEEE Transactions on Automation Science and Engineering, 2022, 19, 1997-2007.	3.4	11
3	Comparing between Different Sets of Preprocessing, Classifiers, and Channels Selection Techniques to Optimise Motor Imagery Pattern Classification System from EEG Pattern Recognition. Brain Sciences, 2022, 12, 57.	1.1	6
4	Optimal Fault Tolerant Error Governor for PID Controllers. International Journal of Control, Automation and Systems, 2022, 20, 1814-1826.	1.6	2
5	Development and experimental validation of algorithms for human–robot interaction in simulated and real scenarios. Journal of Ambient Intelligence and Humanized Computing, 2021, 12, 4529-4539.	3.3	1
6	Biological age estimation using an eHealth system based on wearable sensors. Journal of Ambient Intelligence and Humanized Computing, 2021, 12, 4449-4460.	3.3	7
7	Hybrid Deep Learning (hDL)-Based Brain-Computer Interface (BCI) Systems: A Systematic Review. Brain Sciences, 2021, 11, 75.	1.1	54
8	Stress Detection in Computer Users From Keyboard and Mouse Dynamics. IEEE Transactions on Consumer Electronics, 2021, 67, 12-19.	3.0	16
9	Optimal error governor for PID controllers. International Journal of Systems Science, 2021, 52, 2480-2492.	3.7	7
10	Disturbance Observer Based Fault Tolerant Control for Tilted Hexarotors., 2021,,.		2
11	Arc fault detection and appliances classification in AC home electrical networks using recurrence quantification plots and image analysis. Electric Power Systems Research, 2021, 201, 107503.	2.1	11
11	Arc fault detection and appliances classification in AC home electrical networks using recurrence quantification plots and image analysis. Electric Power Systems Research, 2021, 201, 107503.  Measuring Environmental Data and Physiological Parameters at Home to Assess the Caregiver Burden in Assistants of People with Dementia. Lecture Notes in Electrical Engineering, 2021, , 3-13.	2.1	0
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12	quantification plots and image analysis. Electric Power Systems Research, 2021, 201, 107503.  Measuring Environmental Data and Physiological Parameters at Home to Assess the Caregiver Burden in Assistants of People with Dementia. Lecture Notes in Electrical Engineering, 2021, , 3-13.  Robotics in Education: A Smart and Innovative Approach to the Challenges of the 21st Century. Lecture	0.3	0
12	quantification plots and image analysis. Electric Power Systems Research, 2021, 201, 107503.  Measuring Environmental Data and Physiological Parameters at Home to Assess the Caregiver Burden in Assistants of People with Dementia. Lecture Notes in Electrical Engineering, 2021, , 3-13.  Robotics in Education: A Smart and Innovative Approach to the Challenges of the 21st Century. Lecture Notes in Networks and Systems, 2021, , 17-26.  Neuromuscular Control Modelling of Human Perturbed Posture Through Piecewise Affine Autoregressive With Exogenous Input Models. Frontiers in Bioengineering and Biotechnology, 2021, 9,	0.3	0
12 13	quantification plots and image analysis. Electric Power Systems Research, 2021, 201, 107503.  Measuring Environmental Data and Physiological Parameters at Home to Assess the Caregiver Burden in Assistants of People with Dementia. Lecture Notes in Electrical Engineering, 2021, , 3-13.  Robotics in Education: A Smart and Innovative Approach to the Challenges of the 21st Century. Lecture Notes in Networks and Systems, 2021, , 17-26.  Neuromuscular Control Modelling of Human Perturbed Posture Through Piecewise Affine Autoregressive With Exogenous Input Models. Frontiers in Bioengineering and Biotechnology, 2021, 9, 804904.  Constrained Control Allocation for a Remotely Operated Vehicle with Collective Azimuth Thrusters. ,	0.3	0 10 1
12 13 14	quantification plots and image analysis. Electric Power Systems Research, 2021, 201, 107503.  Measuring Environmental Data and Physiological Parameters at Home to Assess the Caregiver Burden in Assistants of People with Dementia. Lecture Notes in Electrical Engineering, 2021, , 3-13.  Robotics in Education: A Smart and Innovative Approach to the Challenges of the 21st Century. Lecture Notes in Networks and Systems, 2021, , 17-26.  Neuromuscular Control Modelling of Human Perturbed Posture Through Piecewise Affine Autoregressive With Exogenous Input Models. Frontiers in Bioengineering and Biotechnology, 2021, 9, 804904.  Constrained Control Allocation for a Remotely Operated Vehicle with Collective Azimuth Thrusters. , 2020, , .	0.3	0 10 1

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19	A nonlinear optimal control approach for the autonomous octorotor. Advanced Control for Applications, 2020, 2, e50.	0.8	2
20	Analysis of LGV usage for the improvement of a customized production. Procedia Manufacturing, 2020, 51, 1606-1613.	1.9	1
21	System Thinking Approach for Digital Twin Analysis. , 2020, , .		4
22	Measurement of Users' Well-Being Through Domotic Sensors and Machine Learning Algorithms. IEEE Sensors Journal, 2020, 20, 8029-8038.	2.4	28
23	A functional source separation algorithm to enhance error-related potentials monitoring in noninvasive brain-computer interface. Computer Methods and Programs in Biomedicine, 2020, 191, 105419.	2.6	18
24	Actuator Fault-Tolerant Control Architecture for Multirotor Vehicles in Presence of Disturbances. Journal of Intelligent and Robotic Systems: Theory and Applications, 2020, 99, 859-874.	2.0	9
25	Digital Twin Reference Model Development to Prevent Operators' Risk in Process Plants. Sustainability, 2020, 12, 1088.	1.6	116
26	Decision support methodologies and day-ahead optimization for smart building energy management in a dynamic pricing scenario. Energy and Buildings, 2020, 216, 109963.	3.1	11
27	A Stress Detection System based on Multimedia Input Peripherals. , 2020, , .		2
28	Machine Learning-as-a-Service for Consumer Electronics Fault Diagnosis: a Comparison between Matlab and Azure ML., 2020,,.		3
29	Augmented Reality Smart Glasses in the Workplace: Safety and Security in the Fourth Industrial Revolution Era. Lecture Notes in Computer Science, 2020, , 231-247.	1.0	12
30	Actuator Fault Tolerant Control of Variable Pitch Quadrotor Vehicles. IFAC-PapersOnLine, 2020, 53, 4095-4102.	0.5	6
31	Sparse Approximation of LS-SVM for LPV-ARX Model Identification: Application to a Powertrain Subsystem., 2020,,.		4
32	Convolutional Recurrent Neural Networks and Acoustic Data Augmentation for Snore Detection. Smart Innovation, Systems and Technologies, 2020, , 35-46.	0.5	3
33	Cyber-physical manufacturing systems: An architecture for sensor integration, production line simulation and cloud services. Acta IMEKO (2012), 2020, 9, 39.	0.4	2
34	Day-Ahead Multi-Objective Energy Optimization of a Smart Building in a Dynamic Pricing Scenario. Springer Proceedings in Energy, 2020, , 195-205.	0.2	0
35	Psychophysiological Stress Control via Heart Rate Entrainment. , 2019, , .		1
36	Cyber-Physical Manufacturing Systems for Industry 4.0: Architectural Approach and Pilot Case. , 2019, , .		3

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37	Octarotor Fault Tolerant Control via Dynamic Surface Control. , 2019, , .		2
38	Direct position control of an octarotor unmanned vehicle under wind gust disturbance., 2019,,.		2
39	A life cycle costing of compacted lithium titanium oxide batteries for industrial applications. Journal of Power Sources, 2019, 436, 226837.	4.0	20
40	The KIMORE Dataset: KInematic Assessment of MOvement and Clinical Scores for Remote Monitoring of Physical REhabilitation. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2019, 27, 1436-1448.	2.7	58
41	Actuator Fault Tolerant Position Control of a Quadrotor Unmanned Aerial Vehicle., 2019, , .		4
42	An Automated Procedure to Evaluate Usability of eHealth Platforms In The Wild., 2019, , .		1
43	Design and Implementation of a Real-Time Upper Limbs Dyskinesia Detection System. , 2019, , .		1
44	Human-Robot Cooperation via Brain Computer Interface in Assistive Scenario. Lecture Notes in Electrical Engineering, 2019, , 115-131.	0.3	4
45	A Model-Based Approach to Support the Design of Mold Heating for Composites. Lecture Notes in Mechanical Engineering, 2019, , 391-401.	0.3	0
46	Special Issue on "Smart Homes― Editors' Notes. Sensors, 2019, 19, 836.	2.1	3
47	Architecture for Cooperative Interacting Robotic Systems Towards Assisted Living: A Preliminary Study. Lecture Notes in Electrical Engineering, 2019, , 471-486.	0.3	O
48	Smart Monitoring of User and Home Environment: The Health@Home Acquisition Framework. Lecture Notes in Electrical Engineering, 2019, , 23-37.	0.3	3
49	Smart Homes and Assisted Living as an Additional Service Offered to the Users. , 2019, , .		1
50	A Machine-Learning Based Emotion Recognition System in Patients with Parkinson's Disease. , 2019, , .		2
51	Empowered Optical Inspection by Using Robotic Manipulator in Industrial Applications. , 2019, , .		1
52	Recurrence Quantification Analysis of Stator-Current Measurements for Electric Motor Fault Classification., 2019,,.		1
53	Towards the Design of a Machine Learning-based Consumer Healthcare Platform powered by Electronic Health Records and measurement of Lifestyle through Smartphone Data., 2019,,.		3
54	Fault Tolerant Control for an Over-Actuated WAM-V Catamaran. IFAC-PapersOnLine, 2019, 52, 353-359.	0.5	1

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55	Fault detection of a VTOL UAV using Acceleration Measurements. , 2019, , .		11
56	An Effective and Simple Adaptive Algorithm for Ship Course Control Systems. , 2019, , .		O
57	ErrP Signals Detection for Safe Navigation of a Smart Wheelchair. , 2019, , .		2
58	Real time indoor localization integrating a model based pedestrian dead reckoning on smartphone and BLE beacons. Journal of Ambient Intelligence and Humanized Computing, 2019, 10, 1-12.	3.3	64
59	A Non-invasive Method for Biological Age Estimation Using Frailty Phenotype Assessment. Lecture Notes in Electrical Engineering, 2019, , 81-94.	0.3	3
60	Dual-Arm Manipulators Kinematic Control Under Multiple Constraints via Virtual Joints Approach. , 2019, , .		0
61	Dynamic surface fault tolerant control for underwater remotely operated vehicles. ISA Transactions, 2018, 78, 10-20.	3.1	53
62	Complex activity recognition system based on cascade classifiers and wearable device data. , 2018, , .		8
63	Improving mobility and autonomy of disabled users via cooperation of assistive robots. , 2018, , .		12
64	Statistical Spectral Analysis for Fault Diagnosis of Rotating Machines. IEEE Transactions on Industrial Electronics, 2018, 65, 4301-4310.	5.2	110
65	A robust and self-tuning speed control for permanent magnet synchronous motors via meta-heuristic optimization. International Journal of Advanced Manufacturing Technology, 2018, 96, 1283-1292.	1.5	6
66	A Hidden Semi-Markov Model based approach for rehabilitation exercise assessment. Journal of Biomedical Informatics, 2018, 78, 1-11.	2.5	40
67	An automatic temperature control for induction cooktops to reduce energy consumption. , 2018, , .		1
68	Dual-arm cooperative manipulation under joint limit constraints. Robotics and Autonomous Systems, 2018, 99, 110-120.	3.0	36
69	A Constrained Thrust Allocation Algorithm for Remotely Operated Vehicles. IFAC-PapersOnLine, 2018, 51, 250-255.	0.5	6
70	Fault Tolerant Control Scheme for Robotic Manipulators Affected by Torque Faults. IFAC-PapersOnLine, 2018, 51, 886-893.	0.5	13
71	A Model-based Active Fault Tolerant Control Scheme for a Remotely Operated Vehicle. IFAC-PapersOnLine, 2018, 51, 798-805.	0.5	16
72	Upper and Lower Limbs Dyskinesia Detection for Patients with Parkinson's Disease. , 2018, , .		0

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73	A Smart Home Services Demonstration: Monitoring, Control and Security Services Offered to the User. , $2018,  ,  .$		11
74	Hear to see - See to hear: a Smart Home System User Interface for visually or hearing-impaired people. , $2018, \dots$		O
75	Kinematic Fault Tolerant Control of a Dual-Arm Robotic System Under Torque Faults. , 2018, , .		2
76	Induction Mold Heating: Modelling and Hardware-in-the-Loop Simulation for Temperature Control. , 2018, , .		0
77	Fall Detection System by Using Ambient Intelligence and Mobile Robots. , 2018, , .		9
78	Dynamic Surface Control for Multirotor Vehicles. , 2018, , .		4
79	Cooperative Robots Architecture for an Assistive Scenario. , 2018, , .		5
80	Energy Saving in Industrial Wireless Power Recharge System: Simulation of a PI-Sliding Mode Control for a Non-Inverting Buck-Boost Converter. , 2018, , .		0
81	Fault Detection, Diagnosis and Fault Tolerant Output Control for a Remotely Operated Vehicle. , 2018,		8
82	A Gestures Recognition Based Approach for Human-Robot-Interaction. , 2018, , .		0
83	Collaborative design of a telerehabilitation system enabling virtual second opinion based on fuzzy logic. IET Computer Vision, 2018, 12, 502-512.	1.3	6
84	First Approach to a Holistic Tool for Assessing RES Investment Feasibility. Sustainability, 2018, 10, 1153.	1.6	2
85	A Smart Sensing Architecture for Domestic Monitoring: Methodological Approach and Experimental Validation. Sensors, 2018, 18, 2310.	2.1	45
86	Non intrusive load identification for smart energy management systems. , 2018, , .		1
87	A Preliminary Study of a Cyber Physical System for Industry 4.0: Modelling and Co-Simulation of an AGV for Smart Factories. , $2018$ , , .		9
88	Health@Home: pilot cases and preliminary results: Integrated residential sensor network to promote the active aging of real users. , $2018$ , , .		12
89	Fault-Tolerant Disturbance Observer Based Control for Altitude and Attitude Tracking of a Quadrotor. , 2018, , .		3
90	Fault Detection and Isolation of Linear Discrete-Time Periodic Systems Using the Geometric Approach. IEEE Transactions on Automatic Control, 2017, 62, 1518-1523.	3.6	21

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91	An adaptive VSS control for remotely operated vehicles. International Journal of Adaptive Control and Signal Processing, 2017, 31, 507-521.	2.3	5
92	Robust Control of a Photovoltaic Battery System via Fuzzy Sliding Mode Approach. Studies in Computational Intelligence, 2017, , 115-142.	0.7	1
93	Particle Swarm Optimization Based Sliding Mode Control Design: Application to a Quadrotor Vehicle. Studies in Computational Intelligence, 2017, , 143-169.	0.7	5
94	Temperature control of an innovative aluminium-steel molds induction preheat process placed on automated laser guided vehicles. , 2017, , .		6
95	Active Fault Tolerant Control of Remotely Operated Vehicles via Control Effort Redistribution. , 2017, , .		3
96	A Parametric Optimization Approach of an Induction Heating System for Energy Consumption Reduction. , 2017, , .		3
97	Nonlinear control of a photovoltaic battery system via ABC-tuned Dynamic Surface Controller. , 2017,		1
98	Human-robot cooperation via brain computer interface., 2017,,.		5
99	A QR-code localization system for mobile robots: Application to smart wheelchairs. , 2017, , .		11
100	Cyber-physical system integration for industry 4.0: Modelling and simulation of an induction heating process for aluminium-steel molds in footwear soles manufacturing., 2017,,.		17
101	A Variable Structure System Control and its Application in Underwater Vehicles. IFAC-PapersOnLine, 2017, 50, 7019-7026.	0.5	1
102	An Avoidance Control Strategy for Joint-Position Limits of Dual-Arm Robots. IFAC-PapersOnLine, 2017, 50, 1056-1061.	0.5	7
103	Real-time fall detection system by using mobile robots in smart homes. , 2017, , .		7
104	Modelling and hardware-in-the-loop simulation for energy management in induction cooktops. , 2017, , .		2
105	Human Indoor Localization for AAL Applications: An RSSI Based Approach. Lecture Notes in Electrical Engineering, 2017, , 239-250.	0.3	3
106	An Open and Modular Hardware Node for Wireless Sensor and Body Area Networks. Journal of Sensors, 2016, 2016, 1-16.	0.6	13
107	An Integrated Simulation Module for Cyber-Physical Automation Systems. Sensors, 2016, 16, 645.	2.1	18
108	Redundancy analysis of cooperative dual-arm manipulators. International Journal of Advanced Robotic Systems, 2016, 13, 172988141665775.	1.3	19

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109	A detection-estimation approach with refinement to filtering for Gaussian systems with intermittent observations. , $2016$ , , .		1
110	A kinematic joint fault tolerant control based on relative jacobian method for dual arm manipulation systems. , 2016, , .		4
111	Implementation of an "at-home―e-Health system using heterogeneous devices. , 2016, , .		16
112	The Role of ICT in the Italian Health Care System. Lecture Notes in Electrical Engineering, 2016, , 3-17.	0.3	0
113	Wireless sensor network based management system for electric bicycle-sharing. , 2016, , .		1
114	A thruster failure tolerant control scheme for underwater vehicles. , 2016, , .		4
115	Room occupancy detection: Combining RSS analysis and fuzzy logic. , 2016, , .		6
116	A Nonlinear System with Coupled Switching Surfaces for Remotely Operated Vehicle Control. IFAC-PapersOnLine, 2016, 49, 311-316.	0.5	7
117	A novel RSSI based approach for human indoor localization: The Fuzzy Discrete Multilateration. , 2016, , .		5
118	Fault detection of nonlinear processes based on switching linear regression models., 2016,,.		0
119	rapros: A ROS Package for Rapid Prototyping. Studies in Computational Intelligence, 2016, , 491-508.	0.7	4
120	A Virtual Thruster-Based Failure Tolerant Control Scheme for Underwater Vehicles. IFAC-PapersOnLine, 2015, 48, 146-151.	0.5	11
121	A detection-estimation approach to filtering with intermittent observations with generally correlated packet dropouts. , $2015$ , , .		7
122	A novel LDA-based approach for motor bearing fault detection. , 2015, , .		22
123	An integrated simulation environment for Wireless Sensor Networks. , 2015, , .		4
124	An integrated simulation module for wireless cyber-physical system. , 2015, , .		2
125	A Smart Lighting System for Visual Comfort and Energy Savings in Industrial and Domestic Use. Electric Power Components and Systems, 2015, 43, 1696-1706.	1.0	27
126	AAL Technologies for Independent Life of Elderly People. Biosystems and Biorobotics, 2015, , 329-343.	0.2	10

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127	Low Cost RGB-D Vision Based System to Support Motor Disabilities Rehabilitation at Home. Biosystems and Biorobotics, 2015, , 449-461.	0.2	2
128	Nonlinear Decentralized Model Predictive Control for Unmanned Vehicles Moving in Formation. Information Technology and Control, 2015, 44, .	1.1	7
129	Training and Retraining Motor Functions at Home with the Help of Current Technology for Video Games: Basis for the Project. Biosystems and Biorobotics, 2015, , 439-447.	0.2	2
130	SLAM-based autonomous wheelchair navigation system for AAL scenarios., 2014,,.		16
131	A low cost mobile platform for educational robotic applications. , 2014, , .		3
132	A detection-estimation approach to filtering for Gaussian systems with intermittent observations. , 2014, , .		3
133	Actuator fault detection and isolation system for an hexacopter. , 2014, , .		18
134	Development of a smart LED lighting system: Rapid prototyping scenario. , 2014, , .		1
135	Respiratory rate detection algorithm based on RGBâ€D camera: theoretical background and experimental results. Healthcare Technology Letters, 2014, 1, 81-86.	1.9	58
136	Autonomous Assistive Robot for Respiratory Rate Detection and Tracking., 2014,, 61-72.		4
137	A smart lighting system for industrial and domestic use. , 2013, , .		26
138	Geometric tools for solving the FDI problem for linear periodic discrete-time systems. International Journal of Control, 2013, 86, 1214-1226.	1.2	4
139	Optimal reduced-order quadratic solution for the non-Gaussian finite-horizon regulator problem. , 2013, , .		2
140	Reduced-Order Quadratic Kalman-Like Filtering of Non-Gaussian Systems. IEEE Transactions on Automatic Control, 2013, 58, 1744-1757.	3.6	16
141	A Fault Diagnosis and Prognosis LED Lighting System for Increasing Reliability in Energy Efficient Buildings. , 2013, , .		6
142	Actuator Fault Detection System for a Remotely Operated Vehicle. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2013, 46, 356-361.	0.4	7
143	Reduced-order quadratic Kalman-like filtering for non-Gaussian systems. , 2012, , .		2
144	A Diagnostic Thau Observer for a Class of Unmanned Vehicles. Journal of Intelligent and Robotic Systems: Theory and Applications, 2012, 67, 61-73.	2.0	52

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145	A coordination architecture for UUV fleets. Intelligent Service Robotics, 2012, 5, 133-146.	1.6	13
146	An Actuator Failure Tolerant Control Scheme for an Underwater Remotely Operated Vehicle. IEEE Transactions on Control Systems Technology, 2011, 19, 1036-1046.	3.2	84
147	Cooperative and decentralized navigation of autonomous underwater gliders using predictive control. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2011, 44, 12813-12818.	0.4	5
148	An actuator failure tolerant robust control approach for an underwater Remotely Operated Vehicle. , $2011,  \ldots$		9
149	Fault tolerant decentralized nonlinear MPC for fleets of unmanned marine vehicles. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 348-353.	0.4	2
150	Actuator Failure Tolerant Control Design for Underwater Remotely Operated Vehicles. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 25-30.	0.4	3
151	Observer-based Fault Tolerant Sliding Mode Control for Remotely Operated Vehicles. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2010, 43, 173-178.	0.4	5
152	Actuator fault detection system for a mini-quadrotor. , 2010, , .		37
153	A geometric approach to Fault Detection and Isolation Problem for linear periodic systems. , 2010, , .		4
154	Fault Detection for Linear Periodic Systems Using a Geometric Approach. IEEE Transactions on Automatic Control, 2009, 54, 1637-1643.	3.6	33
155	Real-Time Model-Based Fault Detection and Isolation for UGVs. Journal of Intelligent and Robotic Systems: Theory and Applications, 2009, 56, 425-439.	2.0	18
156	A Model-Based Fault Diagnosis System for Unmanned Aerial Vehicles. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2009, 42, 71-76.	0.4	14
157	An Actuator Failure Tolerant Approach for Underwater Remotely Operated Vehicles. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2009, 42, 267-272.	0.4	2
158	Cooperative control of underwater glider fleets by fault tolerant decentralized MPC. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2008, 41, 16021-16026.	0.4	11
159	A geometric approach to fault detection of periodic systems. , 2007, , .		2
160	AN ACTUATOR FAULT TOLERANT APPROACH FOR UNDERWATER REMOTELY OPERATED VEHICLES. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2007, 40, 293-299.	0.4	0
161	Model-Based Sensor Fault Detection and Isolation System for Unmanned Ground Vehicles: Experimental Validation (part II). Proceedings - IEEE International Conference on Robotics and Automation, 2007, , .	0.0	10
162	Model-Based Sensor Fault Detection and Isolation System for Unmanned Ground Vehicles: Theoretical Aspects (part I). Proceedings - IEEE International Conference on Robotics and Automation, 2007, , .	0.0	27

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163	Safe flying for an UAV helicopter. , 2007, , .		16
164	Residual generation approaches in navigation sensors fault detection applications. , 2007, , .		2
165	Autonomous Helicopter for Surveillance and Security. , 2007, , .		1
166	Experimental Validation of a Real-Time Model-Based Sensor Fault Detection and Isolation System for Unmanned Ground Vehicles. , 2006, , .		15
167	ON-LINE SENSOR FAULT DETECTION SYSTEM FOR A SMART WHEELCHAIR. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2006, 39, 91-96.	0.4	2
168	Experimental Validation of a Real-Time Model-Based Sensor Fault Detection and Isolation System for Unmanned Ground Vehicles. , 2006, , .		6
169	MODEL-BASED SENSOR FAULT DETECTION SYSTEM FOR A SMART WHEELCHAIR. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2005, 38, 269-274.	0.4	6
170	Navigation system for a smart wheelchair. Journal of Zhejiang University Science B, 2005, 6A, 110-117.	0.4	12