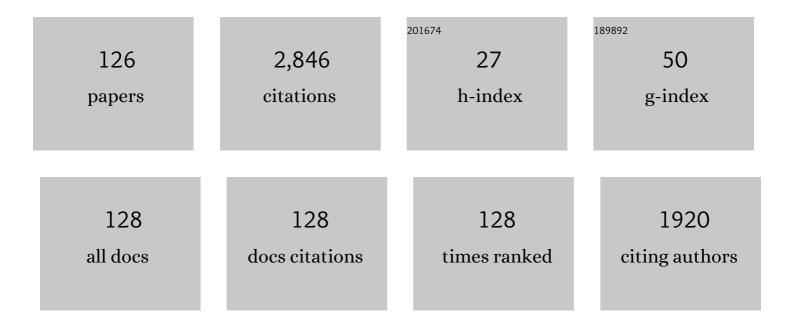
## **Yanling Tian**

List of Publications by Year in descending order

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ΥΛΝΕΙΝΟ ΤΙΛΝ

| #  | Article  | IF  | CITATIONS |
|----|--|-----|-----------|
| 1  | A Novel Direct Inverse Modeling Approach for Hysteresis Compensation of Piezoelectric Actuator in<br>Feedforward Applications. IEEE/ASME Transactions on Mechatronics, 2013, 18, 981-989.  | 5.8 | 213       |
| 2  | Insights into the wettability transition of nanosecond laser ablated surface under ambient air exposure. Journal of Colloid and Interface Science, 2019, 533, 268-277.   | 9.4 | 193       |
| 3  | Design of a Piezoelectric-Actuated Microgripper With a Three-Stage Flexure-Based Amplification.<br>IEEE/ASME Transactions on Mechatronics, 2015, 20, 2205-2213.  | 5.8 | 140       |
| 4  | Design and Control of a Compliant Microgripper With a Large Amplification Ratio for High-Speed Micro Manipulation. IEEE/ASME Transactions on Mechatronics, 2016, 21, 1262-1271.  | 5.8 | 140       |
| 5  | Multi-morphology transition hybridization CAD design of minimal surface porous structures for use in tissue engineering. CAD Computer Aided Design, 2014, 56, 11-21.   | 2.7 | 133       |
| 6  | Design and Computational Optimization of a Decoupled 2-DOF Monolithic Mechanism. IEEE/ASME<br>Transactions on Mechatronics, 2014, 19, 872-881.   | 5.8 | 126       |
| 7  | Fabrication of super-hydrophobic nickel film on copper substrate with improved corrosion inhibition<br>by electrodeposition process. Colloids and Surfaces A: Physicochemical and Engineering Aspects, 2019,<br>560, 205-212.          | 4.7 | 106       |
| 8  | A Novel Actuator-Internal Micro/Nano Positioning Stage With an Arch-Shape Bridge-Type Amplifier.<br>IEEE Transactions on Industrial Electronics, 2019, 66, 9161-9172.  | 7.9 | 82        |
| 9  | Design and Kinematics Modeling of a Novel 3-DOF Monolithic Manipulator Featuring Improved<br>Scott-Russell Mechanisms. Journal of Mechanical Design, Transactions of the ASME, 2013, 135, .  | 2.9 | 77        |
| 10 | Novel real function based method to construct heterogeneous porous scaffolds and additive manufacturing for use in medical engineering. Medical Engineering and Physics, 2015, 37, 1037-1046.  | 1.7 | 70        |
| 11 | A novel voice coil motor-driven compliant micropositioning stage based on flexure mechanism.<br>Review of Scientific Instruments, 2015, 86, 095001.  | 1.3 | 66        |
| 12 | Experimental Investigation of Robust Motion Tracking Control for a 2-DOF Flexure-Based Mechanism.<br>IEEE/ASME Transactions on Mechatronics, 2014, 19, 1737-1745.  | 5.8 | 65        |
| 13 | Design of a Novel Dual-Axis Micromanipulator With an Asymmetric Compliant Structure. IEEE/ASME<br>Transactions on Mechatronics, 2019, 24, 656-665.   | 5.8 | 64        |
| 14 | Hybrid Laser Ablation and Chemical Modification for Fast Fabrication of Bio-inspired<br>Super-hydrophobic Surface with Excellent Self-cleaning, Stability and Corrosion Resistance. Journal<br>of Bionic Engineering, 2019, 16, 13-26. | 5.0 | 62        |
| 15 | A novel piezo-driven microgripper with a large jaw displacement. Microsystem Technologies, 2015, 21,<br>931-942.   | 2.0 | 57        |
| 16 | A novel monolithic piezoelectric actuated flexure-mechanism based wire clamp for microelectronic device packaging. Review of Scientific Instruments, 2015, 86, 045106.   | 1.3 | 55        |
| 17 | A 2-DOF Monolithic Compliant Rotation Platform Driven by Piezoelectric Actuators. IEEE Transactions on Industrial Electronics, 2020, 67, 6963-6974.  | 7.9 | 54        |
| 18 | Experimental Analysis of Laser Interferometry-Based Robust Motion Tracking Control of a<br>Flexure-Based Mechanism. IEEE Transactions on Automation Science and Engineering, 2013, 10, 267-275.  | 5.2 | 48        |

| #  | Article   | IF  | CITATIONS |
|----|---|-----|-----------|
| 19 | A Spatial Deployable Three-DOF Compliant Nano-Positioner With a Three-Stage Motion Amplification<br>Mechanism. IEEE/ASME Transactions on Mechatronics, 2020, 25, 1322-1334.                                     | 5.8 | 47        |
| 20 | Modelling the cutting forces in micro-end-milling using a hybrid approach. International Journal of<br>Advanced Manufacturing Technology, 2014, 73, 1647-1656.  | 3.0 | 38        |
| 21 | Development of a Passive Compliant Mechanism for Measurement of Micro/Nanoscale Planar 3-DOF<br>Motions. IEEE/ASME Transactions on Mechatronics, 2016, 21, 1222-1232.   | 5.8 | 38        |
| 22 | Study on the Fabrication of Super-Hydrophobic Surface on Inconel Alloy via Nanosecond Laser<br>Ablation. Materials, 2019, 12, 278.  | 2.9 | 38        |
| 23 | A runout measuring method using modeling and simulation cutting force in micro end-milling.<br>International Journal of Advanced Manufacturing Technology, 2017, 91, 4191-4201.                                 | 3.0 | 34        |
| 24 | Investigation of Effects of Acid, Alkali, and Salt Solutions on Fluorinated Superhydrophobic Surfaces.<br>Langmuir, 2019, 35, 17027-17036.  | 3.5 | 33        |
| 25 | Modeling and Analysis of Soft Pneumatic Network Bending Actuators. IEEE/ASME Transactions on Mechatronics, 2021, 26, 2195-2203.   | 5.8 | 33        |
| 26 | A contrastive investigation on anticorrosive performance of laser-induced super-hydrophobic and oil-infused slippery coatings. Progress in Organic Coatings, 2020, 138, 105313.                                 | 3.9 | 30        |
| 27 | A Contrastive Investigation on the Anticorrosive Performance of Stearic Acid and<br>Fluoroalkylsilane-Modified Superhydrophobic Surface in Salt, Alkali, and Acid Solution. Langmuir,<br>2020, 36, 10279-10292. | 3.5 | 29        |
| 28 | A Two-Finger Soft-Robotic Gripper with Enveloping and Pinching Grasping Modes. IEEE/ASME<br>Transactions on Mechatronics, 2020, , 1-1.  | 5.8 | 29        |
| 29 | A novel instantaneous uncut chip thickness model for mechanistic cutting force model in<br>micro-end-milling. International Journal of Advanced Manufacturing Technology, 2017, 93, 2305-2319.                  | 3.0 | 27        |
| 30 | Novel metal-organic super-hydrophobic surface fabricated by nanosecond laser irradiation in solution. Colloids and Surfaces A: Physicochemical and Engineering Aspects, 2020, 587, 124343.                      | 4.7 | 27        |
| 31 | A hybrid contact state analysis methodology for robotic-based adjustment of cylindrical pair.<br>International Journal of Advanced Manufacturing Technology, 2011, 52, 329-342.                                 | 3.0 | 25        |
| 32 | Machining forces prediction for peripheral milling of low-rigidity component with curved geometry.<br>International Journal of Advanced Manufacturing Technology, 2013, 64, 1599-1610.                          | 3.0 | 25        |
| 33 | Droplet Impact on the Super-Hydrophobic Surface with Micro-Pillar Arrays Fabricated by Hybrid Laser<br>Ablation and Silanization Process. Materials, 2019, 12, 765.   | 2.9 | 24        |
| 34 | Improving environmental noise suppression for micronewton force sensing based on electrostatic by injecting air damping. Review of Scientific Instruments, 2014, 85, 055002.                                    | 1.3 | 23        |
| 35 | Design of a novel 3D ultrasonic vibration platform with tunable characteristics. International<br>Journal of Mechanical Sciences, 2020, 186, 105895.  | 6.7 | 23        |
| 36 | Fabrication of controllable wettability of crystalline silicon surfaces by laser surface texturing and silanization. Applied Surface Science, 2019, 497, 143805.  | 6.1 | 22        |

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|----|---|-----|-----------|
| 37 | Design of a rhombus-type stick-slip actuator with two driving modes for micropositioning.<br>Mechanical Systems and Signal Processing, 2022, 166, 108421.   | 8.0 | 22        |
| 38 | Design and Control of a Spatial Micromanipulator Inspired by Deployable Structure. IEEE Transactions on Industrial Electronics, 2022, 69, 971-979.  | 7.9 | 22        |
| 39 | Grasping force hysteresis compensation of a piezoelectric-actuated wire clamp with a modified inverse Prandtl-Ishlinskii model. Review of Scientific Instruments, 2017, 88, 115101.   | 1.3 | 21        |
| 40 | Dynamic modeling and control of a novel <i>XY</i> positioning stage for semiconductor packaging.<br>Transactions of the Institute of Measurement and Control, 2015, 37, 177-189.  | 1.7 | 20        |
| 41 | Modeling and analyses of helical milling process. International Journal of Advanced Manufacturing Technology, 2017, 90, 1003-1022.  | 3.0 | 20        |
| 42 | The investigation of mechanical and thermal properties of super-hydrophobic nitinol surfaces<br>fabricated by hybrid methods of laser irradiation and carbon ion implantation. Applied Surface<br>Science, 2020, 527, 146889. | 6.1 | 19        |
| 43 | An XYZ micromanipulator for precise positioning applications. Journal of Micro-Bio Robotics, 2020, 16, 53-63.   | 2.1 | 19        |
| 44 | A Dual-Driven High Precision Rotary Platform Based on Stick-Slip Principle. IEEE/ASME Transactions on Mechatronics, 2022, 27, 3053-3064.  | 5.8 | 17        |
| 45 | Design of a novel 3D tip-based nanofabrication system with high precision depth control capability.<br>International Journal of Mechanical Sciences, 2020, 169, 105328.   | 6.7 | 16        |
| 46 | Low-cost and fast fabrication of the ultrasonic embossing on polyethylene terephthalate (PET) films using laser processed molds. Microsystem Technologies, 2017, 23, 5653-5668.   | 2.0 | 15        |
| 47 | Design, modelling and characterization of a 2-DOF precision positioning platform. Transactions of the Institute of Measurement and Control, 2015, 37, 396-405.  | 1.7 | 14        |
| 48 | Design of a flexure-based mechanism possessing low stiffness and constant force. Review of Scientific<br>Instruments, 2019, 90, .   | 1.3 | 14        |
| 49 | Design of a XYZ scanner for home-made high-speed atomic force microscopy. Microsystem<br>Technologies, 2018, 24, 3123-3132.   | 2.0 | 13        |
| 50 | Insights into the stability of fluorinated super-hydrophobic coating in different corrosive solutions.<br>Progress in Organic Coatings, 2021, 151, 106043.  | 3.9 | 13        |
| 51 | Thermal simulation modeling of a hydrostatic machine feed platform. International Journal of<br>Advanced Manufacturing Technology, 2015, 79, 1581-1595.   | 3.0 | 12        |
| 52 | Modeling and tracking control of a novel XYÎ,z stage. Microsystem Technologies, 2017, 23, 3575-3588.  | 2.0 | 11        |
| 53 | Surface topography modeling and roughness extraction in helical milling operation. International<br>Journal of Advanced Manufacturing Technology, 2018, 95, 4561-4571.  | 3.0 | 11        |
| 54 | Influence of external heat sources on volumetric thermal errors of precision machine tools.<br>International Journal of Advanced Manufacturing Technology, 2018, 99, 475-495.   | 3.0 | 11        |

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|----|--|-----|-----------|
| 55 | An experimental study on the rotational accuracy of variable preload spindle-bearing system.<br>Advances in Mechanical Engineering, 2018, 10, 168781401877617.   | 1.6 | 11        |
| 56 | Dynamic analysis of tapping mode atomic force microscope (AFM) for critical dimension measurement.<br>Precision Engineering, 2020, 64, 269-279.  | 3.4 | 10        |
| 57 | The Study on the Anti-corrosion Performance of NiTi Alloy in Human Body Solution with the<br>Fabricating Processes of Laser Irradiation and PDMS Modification. Journal of Bionic Engineering, 2021,<br>18, 77-91.                          | 5.0 | 10        |
| 58 | Probe system design for three dimensional micro/nano scratching machine. Microsystem<br>Technologies, 2017, 23, 2285-2295.   | 2.0 | 9         |
| 59 | Dynamic Optimization of Constrained Layer Damping Structure for the Headstock of Machine Tools with Modal Strain Energy Method. Shock and Vibration, 2017, 2017, 1-13.   | 0.6 | 9         |
| 60 | Design and characteristic analysis of an aerostatic decoupling table for microelectronic packaging.<br>Proceedings of the Institution of Mechanical Engineers, Part C: Journal of Mechanical Engineering<br>Science, 2018, 232, 1079-1090. | 2.1 | 9         |
| 61 | Investigation on Modeling and Formation Mechanism of Dynamic Rotational Error for Spindle-Rolling<br>Bearing System. Applied Sciences (Switzerland), 2020, 10, 5753.   | 2.5 | 9         |
| 62 | Experimental investigation of the effects of vibration parameters on ultrasonic vibration-assisted tip-based nanofabrication. International Journal of Mechanical Sciences, 2021, 198, 106387.   | 6.7 | 9         |
| 63 | Investigation of the mechanical effects of targeted drugs on cancerous cells based on atomic force microscopy. Analytical Methods, 2021, 13, 3136-3146.  | 2.7 | 9         |
| 64 | Antlion Optimized Robust Control Approach for Micropositioning Trajectory Tracking Tasks. IEEE Access, 2020, 8, 220889-220907.   | 4.2 | 8         |
| 65 | Stability Mechanism of Laser-induced Fluorinated Super-hydrophobic Coating in Alkaline Solution.<br>Journal of Bionic Engineering, 2022, 19, 113-125.  | 5.0 | 8         |
| 66 | Laser-induced changes in titanium by femtosecond, picosecond and millisecond laser ablation.<br>Radiation Effects and Defects in Solids, 2015, 170, 528-540.   | 1.2 | 7         |
| 67 | Development of a novel 3-DOF suspension mechanism for multi-function stylus profiling systems.<br>International Journal of Precision Engineering and Manufacturing, 2016, 17, 1415-1423.   | 2.2 | 7         |
| 68 | Dodecyl Mercaptan Functionalized Copper Mesh for Water Repellence and Oil-water Separation.<br>Journal of Bionic Engineering, 2021, 18, 887-899.   | 5.0 | 7         |
| 69 | Insights into cell classification based on combination of multiple cellular mechanical phenotypes by<br>using machine learning algorithm. Journal of the Mechanical Behavior of Biomedical Materials, 2022,<br>128, 105097.                | 3.1 | 7         |
| 70 | Structure design and experimental investigation of a multi-function stylus profiling system for characterization of engineering surfaces at micro/nano scales. Microsystem Technologies, 2018, 24, 2177-2187.                              | 2.0 | 6         |
| 71 | Modeling and control methodology for an XYZ micro manipulator. Review of Scientific Instruments, 2019, 90, .   | 1.3 | 6         |
|    |  |     |           |

72 Design of a novel parallel monolithic 3-DOF compliant micromanipulator. , 2019, , .

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| #  | Article  | IF  | CITATIONS |
|----|--|-----|-----------|
| 73 | Vacuum conditions for tunable wettability transition on laser ablated Ti-6Al-4V alloy surfaces.<br>Colloids and Surfaces A: Physicochemical and Engineering Aspects, 2022, 647, 129023.          | 4.7 | 6         |
| 74 | Dynamic analysis of an XY positioning table. , 2013, , .   |     | 5         |
| 75 | Laser-induced hydrophobicity on Ti-6Al-4V surface. , 2015, , .   |     | 5         |
| 76 | Active and intelligent control onto thermal behaviors of a motorized spindle unit. International<br>Journal of Advanced Manufacturing Technology, 2018, 98, 3133-3146.                           | 3.0 | 5         |
| 77 | Rapid fabrication of super-hydrophobic surfaces of silicon wafers with excellent anisotropic wetting. Microsystem Technologies, 2019, 25, 237-243.   | 2.0 | 5         |
| 78 | Design and Modeling of a Decoupled 2-DOF Stick-slip Positioning Stage. , 2019, , .   |     | 5         |
| 79 | Lithography-induced hydrophobic surfaces of silicon wafers with excellent anisotropic wetting properties. Microsystem Technologies, 2019, 25, 735-745.   | 2.0 | 5         |
| 80 | Theoretical analysis of detection sensitivity in nano-resonator-based sensors for elasticity and density measurement. International Journal of Mechanical Sciences, 2021, 197, 106309.           | 6.7 | 5         |
| 81 | Experimental System Identification, Feed-Forward Control, and Hysteresis Compensation of a 2-DOF Mechanism. International Journal of Intelligent Mechatronics and Robotics, 2013, 3, 1-21.       | 0.4 | 5         |
| 82 | Fabrication of polymer optical diffusers by buffer-assisted ultrasonic embossing. , 2015, , .  |     | 4         |
| 83 | A novel method and system for calibrating the spring constant of atomic force microscope cantilever based on electromagnetic actuation. Review of Scientific Instruments, 2018, 89, 125119.      | 1.3 | 4         |
| 84 | Design and Characteristics of a Novel Compliant Symmetric Microgripper Mechanism. , 2018, , .  |     | 4         |
| 85 | Enhancing multiple harmonics in tapping mode atomic force microscopy by added mass with finite size.<br>Applied Physics Express, 2019, 12, 126505.   | 2.4 | 4         |
| 86 | A unified element stiffness matrix model for variable cross-section flexure hinges in compliant mechanisms for micro/nano positioning. Microsystem Technologies, 2019, 25, 4257-4268.            | 2.0 | 4         |
| 87 | A Novel Soft-Robotic Gripper with Vertically Plane Contact of the Object. , 2019, , .  |     | 4         |
| 88 | Adhesion performance study of a novel microstructured stamp for micro-transfer printing. Soft<br>Matter, 2021, 17, 4989-4997.  | 2.7 | 4         |
| 89 | The effects of measurement parameters on the cancerous cell nucleus characterisation by atomic force microscopy in vitro. Journal of Microscopy, 2022, 287, 3-18.                                | 1.8 | 4         |
| 90 | Prediction of Dynamic Milling Stability considering Time Variation of Deflection and Dynamic<br>Characteristics in Thin-Walled Component Milling Process. Shock and Vibration, 2016, 2016, 1-14. | 0.6 | 3         |

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|-----|---|-----|-----------|
| 91  | Design and stiffness analysis of a XYZ scanning stage. , 2016, , .  |     | 3         |
| 92  | A Novel Decoupled Flexure Nanopositioner With Thermal Distortion Self-Elimination Function.<br>IEEE/ASME Transactions on Mechatronics, 2022, 27, 2953-2962.                       | 5.8 | 3         |
| 93  | Design and kinematics analysis of a 3-DOF precision positioning stage. , 2009, , .  |     | 2         |
| 94  | Parameters identification of a novel micro-positioning stage based on adaptive real-coded genetic algorithm. , 2015, , .  |     | 2         |
| 95  | Fabrication of polymer electronic boards by ultrasonic embossing and welding. Microsystem<br>Technologies, 2015, 21, 365-369.   | 2.0 | 2         |
| 96  | Design of a novel asymmetrical piezoelectric actuated microgripper for micromanipulation. , 2016, , .   |     | 2         |
| 97  | Lithography-induced wettability changes of silicon. , 2017, , .   |     | 2         |
| 98  | Smooth Displacement/Force Switching Control of a Piezoelectric Actuated Microgripper for Micro Manipulation. , 2019, , .  |     | 2         |
| 99  | Mechanobiology Analysis of Manifold Live Cells in Vitro with Atomic Force Acoustic Microscopy. ACS<br>Applied Bio Materials, 2020, 3, 1210-1215.                                  | 4.6 | 2         |
| 100 | Compressive and tensile behaviors of carbon and boron nitride nanotubes. , 2012, , .  |     | 1         |
| 101 | Transverse vibration analyses of cantilevered boron nitride nanocones. Micro and Nano Letters, 2013,<br>8, 899-902.   | 1.3 | 1         |
| 102 | Modified rate-dependent hysteresis modeling of piezoelectric actuator. , 2014, , .  |     | 1         |
| 103 | A novel electromagnetic force method for micro/nano newton force measurement. , 2017, , .   |     | 1         |
| 104 | Design and modeling of a 2-DOF decoupled rotation platform for micro-manipulation. , 2017, , .  |     | 1         |
| 105 | Identification of incident parameters of interference beams using angular power spectral density.<br>Applied Physics Letters, 2019, 114, 241902.                                  | 3.3 | 1         |
| 106 | A Novel XY Nano Positioning Stage with a Three Stage Motion Amplification Mechanism. , 2019, , .  |     | 1         |
| 107 | INFLUENCE OF FEMTOSECOND-LASER-INDUCED PERIODIC SURFACE STRUCTURES ON THE TRIBOLOGICAL PERFORMANCE OF CVD NANO-CRYSTALLINE DIAMOND FILMS. Surface Review and Letters, 2022, 29, . | 1.1 | 1         |
| 108 | Dynamic analysis of a flexure-based mechanism for precision machining operation. , 2010, , .  |     | 0         |

| #   | Article  | IF  | CITATIONS |
|-----|--|-----|-----------|
| 109 | Motion control of a 2-DOF decoupled compliant mechanism using H <inf>∞</inf> synthesis. , 2012, , .  |     | О         |
| 110 | Dynamic Performance Evaluation of a Parallel Manipulator with Non Axial Symmetrical<br>Characteristics by Computing the Respective Actuating Joint Capability. International Journal of<br>Intelligent Mechatronics and Robotics, 2012, 2, 1-14. | 0.4 | 0         |
| 111 | Mechanical design and optimization of a suspension of multi-function sensing probes. , 2013, , .   |     | Ο         |
| 112 | Design, analysis, and experimental investigations of a 2-DOF monolithic parallel mechanism. , 2013, , .  |     | 0         |
| 113 | Development and Application of Molded Interconnect Devices. International Journal of Robotics Applications and Technologies, 2014, 2, 1-18.  | 0.4 | 0         |
| 114 | Mathematical modelling of a droplet sitting on super hydrophobic surface with Hertz model. , 2014, , .   |     | 0         |
| 115 | Probe suspension mechanism design for nano machining system. , 2015, , .   |     | 0         |
| 116 | Design of a 6-DOF precision positioning stage: Kinematic analysis and dynamic modeling. , 2015, , .  |     | 0         |
| 117 | Tip modeling of a probe for nanochannel fabrication. , 2016, , .   |     | 0         |
| 118 | The investigation of equilibrium contact state of liquid droplet on determined rough surfaces. , 2017, , .   |     | 0         |
| 119 | Characteristics of a Decoupled 2-Dof Nano-Positioning Stage. , 2018, , .   |     | 0         |
| 120 | Effects of Carbon Ion Implantation on Surface Performance of Modified NiTi Shape Memory Alloy. ,<br>2018, , .  |     | 0         |
| 121 | A Symmetry Flexure Structure and its Application in Micro/Nano Newton Force Generation. , 2018, , .  |     | 0         |
| 122 | A Novel Archimedes Planar Springs Flexure Structure for Microforce Actuator. , 2018, , .   |     | 0         |
| 123 | A Parasitic Motionless Piezoelectric Actuated Microgripper for Micro/Nano Manipulation. , 2019, , .  |     | Ο         |
| 124 | Morphological and Mechanical Properties Characterization for Healthy and Cancerous Cells by<br>Home-made Atomic Force Acoustic Microscopy (AFAM). , 2019, , .  |     | 0         |
| 125 | Design, Modeling and Analysis of a Novel Piezoactuated XYZ Compliant Mechanism for Large<br>Workspace Nano-positioning. , 2019, , .  |     | Ο         |
| 126 | A shear force assisted tiny object releasing method of a 2-DOF microgripper. , 2021, , .   |     | 0         |

A shear force assisted tiny object releasing method of a 2-DOF microgripper. , 2021, , . 126