## Ryo Miyazaki

List of Publications by Year in descending order

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RVO MIVAZAKI

| #  | Article   | IF  | CITATIONS |
|----|---|-----|-----------|
| 1  | TAMS: development of a multipurpose three-arm aerial manipulator system. Advanced Robotics, 2021, 35, 31-47.  | 1.8 | 28        |
| 2  | Airborne Docking for Multi-Rotor Aerial Manipulations. , 2018, , .  |     | 21        |
| 3  | Aerial Manipulation Using Multirotor UAV: A Review from the Aspect of Operating Space and Force.<br>Journal of Robotics and Mechatronics, 2021, 33, 196-204.                                | 1.0 | 21        |
| 4  | Landing of a Multirotor Aerial Vehicle on an Uneven Surface Using Multiple On-board Manipulators. ,<br>2019, , .  |     | 19        |
| 5  | Long-Reach Aerial Manipulation Employing Wire-Suspended Hand With Swing-Suppression Device. IEEE<br>Robotics and Automation Letters, 2019, 4, 3045-3052.                                    | 5.1 | 16        |
| 6  | Wire-Suspended Device Control Based on Wireless Communication With Multirotor for Long<br>Reach-Aerial Manipulation. IEEE Access, 2020, 8, 172096-172104.                                   | 4.2 | 9         |
| 7  | Development of Add-On Planar Translational Driving System for Aerial Manipulation with Multirotor Platform. Applied Sciences (Switzerland), 2021, 11, 1462.                                 | 2.5 | 7         |
| 8  | A Versatile Aerial Manipulator Design and Realization of UAV Take-Off from a Rocking Unstable<br>Surface. Applied Sciences (Switzerland), 2021, 11, 9157.                                   | 2.5 | 6         |
| 9  | Active Tethered Hook: Heavy Load Movement using Hooks that Move Actively with Micro UAVs and Winch System. , 2021, , .  |     | 2         |
| 10 | Passive Perching and Landing Mechanism for Multirotor Flying Robot. , 2021, , .   |     | 1         |
| 11 | Development of High-Pressure Washing Aerial Robot Employing Multirotor Platform with Add-on<br>Planar Translational Driving System. , 2021, , .   |     | 1         |
| 12 | Adaptively Leveling a UAV with Three-arm Aerial Manipulator System on Shifting Ground. , 2021, , .  |     | 1         |
| 13 | Development of Multirotor Aerial Robot with Add-on Planar Translational Driving System for<br>High-Pressure Washing Task. Journal of the Robotics Society of Japan, 2022, 40, 170-173.<br>– | 0.1 | 0         |