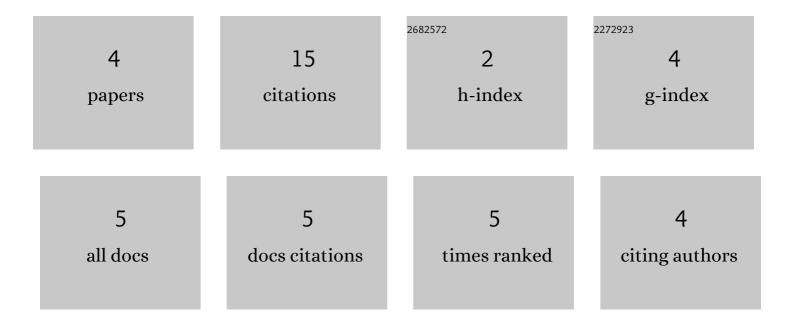
## Marcus Hamann

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/1756786/publications.pdf Version: 2024-02-01



#	Article	IF	CITATIONS
1	Model-Based Control of a Pendulum by a 3-DoF Cable Robot Using Exact Linearization. IFAC-PapersOnLine, 2020, 53, 9053-9060.	0.9	5
2	Model-Based Control of a Planar 3-DoF Cable Robot Using Exact Linearization. Mechanisms and Machine Science, 2021, , 260-270.	0.5	4
3	Calibration Procedure For a Geometrically Reconfigurable 3-DoF Cable-Driven Parallel Robot. , 2018, , .		3
4	Development of an Active End Effector for Cable Robot Calibration. Mechanisms and Machine Science, 2021, , 336-347.	0.5	1