

Fei Wang

List of Publications by Year in descending order

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26
papers

265
citations

1040056

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docs citations

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times ranked

215
citing authors

#	ARTICLE	IF	CITATIONS
1	(2+1)D-SLR: an efficient network for video sign language recognition. <i>Neural Computing and Applications</i> , 2022, 34, 2413-2423.	5.6	8
2	A Hierarchical Path Planning Approach with Multi-SARSA Based on Topological Map. <i>Sensors</i> , 2022, 22, 2367.	3.8	10
3	Continuous motion estimation of lower limbs based on deep belief networks and random forest. <i>Review of Scientific Instruments</i> , 2022, 93, 044106.	1.3	5
4	Tracking moving target for 6 degree-of-freedom robot manipulator with adaptive visual servoing based on deep reinforcement learning PID controller. <i>Review of Scientific Instruments</i> , 2022, 93, 045108.	1.3	3
5	Deep Neural Network for Point Sets Based on Local Feature Integration. <i>Sensors</i> , 2022, 22, 3209.	3.8	2
6	An approach based on 1D fully convolutional network for continuous sign language recognition and labeling. <i>Neural Computing and Applications</i> , 2022, 34, 17921-17935.	5.6	2
7	PatchCNN: An Explicit Convolution Operator for Point Clouds Perception. <i>IEEE Geoscience and Remote Sensing Letters</i> , 2021, 18, 726-730.	3.1	3
8	Cornerstone network with feature extractor: a metric-based few-shot model for chinese natural sign language. <i>Applied Intelligence</i> , 2021, 51, 7139-7150.	5.3	9
9	Outline viewpoint feature histogram: An improved point cloud descriptor for recognition and grasping of workpieces. <i>Review of Scientific Instruments</i> , 2021, 92, 025010.	1.3	5
10	Robot grasping method optimization using improved deep deterministic policy gradient algorithm of deep reinforcement learning. <i>Review of Scientific Instruments</i> , 2021, 92, 025114.	1.3	10
11	Keypoint-Based Robotic Grasp Detection Scheme in Multi-Object Scenes. <i>Sensors</i> , 2021, 21, 2132.	3.8	15
12	A two-stage temporal proposal network for precise action localization in untrimmed video. <i>International Journal of Machine Learning and Cybernetics</i> , 2021, 12, 2199-2211.	3.6	2
13	EEG Driving Fatigue Detection With PDC-Based Brain Functional Network. <i>IEEE Sensors Journal</i> , 2021, 21, 10811-10823.	4.7	26
14	LHFF-Net: Local heterogeneous feature fusion network for 6DoF pose estimation. <i>International Journal of Machine Learning and Cybernetics</i> , 2021, 12, 2795-2807.	3.6	1
15	Classification of motor imagery using multisource joint transfer learning. <i>Review of Scientific Instruments</i> , 2021, 92, 094106.	1.3	3
16	Partial directed coherence based graph convolutional neural networks for driving fatigue detection. <i>Review of Scientific Instruments</i> , 2020, 91, 074713.	1.3	21
17	Multiple nonlinear features fusion based driving fatigue detection. <i>Biomedical Signal Processing and Control</i> , 2020, 62, 102075.	5.7	20
18	Joining Force of Human Muscular Task Planning With Robot Robust and Delicate Manipulation for Programming by Demonstration. <i>IEEE/ASME Transactions on Mechatronics</i> , 2020, 25, 2574-2584.	5.8	12

#	ARTICLE	IF	CITATIONS
19	Motor imagery classification using geodesic filtering common spatial pattern and filter-bank feature weighted support vector machine. <i>Review of Scientific Instruments</i> , 2020, 91, 034106.	1.3	8
20	Cross-Subject EEG-Based Emotion Recognition with Deep Domain Confusion. <i>Lecture Notes in Computer Science</i> , 2019, , 558-570.	1.3	24
21	An Recognitionâ€“Verification Mechanism for Real-Time Chinese Sign Language Recognition Based on Multi-Information Fusion. <i>Sensors</i> , 2019, 19, 2495.	3.8	15
22	An Improved Point Cloud Descriptor for Vision Based Robotic Grasping System. <i>Sensors</i> , 2019, 19, 2225.	3.8	17
23	Topological Map Construction Based on Region Dynamic Growing and Map Representation Method. <i>Applied Sciences (Switzerland)</i> , 2019, 9, 816.	2.5	4
24	Research on the shared control technology for robotic wheelchairs based on topological map. <i>Industrial Robot</i> , 2019, 47, 825-835.	2.1	3
25	SAST: Learning Semantic Action-Aware Spatial-Temporal Features for Efficient Action Recognition. <i>IEEE Access</i> , 2019, 7, 164876-164886.	4.2	7
26	Point-wise saliency detection on 3D point clouds via covariance descriptors. <i>Visual Computer</i> , 2018, 34, 1325-1338.	3.5	30