## Hiroyuki Nakamoto

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/1561737/publications.pdf

Version: 2024-02-01

54 papers 342 citations

1307366 7 h-index

14 g-index

55 all docs

55 docs citations 55 times ranked 474 citing authors

| #  | Article   | IF  | CITATIONS |
|----|---|-----|-----------|
| 1  | Joint angle measurement by stretchable strain sensor. Journal of Ambient Intelligence and Humanized Computing, 2023, 14, 14623-14628.   | 3.3 | 8         |
| 2  | Food Texture Measurement System Using Rod Type Actuator for Imitation of Human Mastication. International Journal of Automation Technology, 2022, 16, 421-426.  | 0.5 | 0         |
| 3  | Sum of variance for quantifying the variation of multiple sequential data for the crispness evaluation of chicken nugget. Journal of Texture Studies, 2021, 52, 470-479.  | 1.1 | O         |
| 4  | A Magnetic Food Texture Sensor and Comparison of the Measurement Data of Chicken Nuggets. Sensors, 2021, 21, 3310.  | 2.1 | 5         |
| 5  | Wearable Band-Shaped Device and Detection Algorithm for Laryngeal Elevation in Mendelsohn<br>Maneuver. IEEE Sensors Journal, 2021, 21, 14352-14359.   | 2.4 | 3         |
| 6  | Validity of a novel respiratory rate monitor comprising stretchable strain sensors during a 6-min walking test in patients with chronic pulmonary obstructive disease. Respiratory Medicine, 2021, 190, 106675. | 1.3 | 0         |
| 7  | Measurement of laryngeal elevation time using a flexible surface stretch sensor. Journal of Oral Rehabilitation, 2020, 47, 1489-1495.   | 1.3 | O         |
| 8  | Development of Magnetic Food Texture Sensor with Spring and Sliding Mechanism., 2020,,.   |     | 3         |
| 9  | Monitoring respiratory rates with a wearable system using a stretchable strain sensor during moderate exercise. Medical and Biological Engineering and Computing, 2019, 57, 2741-2756.                          | 1.6 | 31        |
| 10 | Inspection of illumination pillar using ultrasonic guided wave by electromagnetic acoustic transducer. International Journal of Applied Electromagnetics and Mechanics, 2019, 59, 1487-1493.                    | 0.3 | O         |
| 11 | Laryngeal Elevation Measurement for Dysphagia Rehabilitation by Stretchable Strain Sensors.<br>Transactions of the Society of Instrument and Control Engineers, 2019, 55, 655-661.                              | 0.1 | O         |
| 12 | Food Texture Quantification of Tempura Using Magnetic Food Texture Sensor and Time-series Data. Sensors and Materials, 2019, 31, 2357.  | 0.3 | 1         |
| 13 | Food texture evaluation using logistic regression model and magnetic food texture sensor. Journal of Food Engineering, 2018, 222, 20-28.  | 2.7 | 10        |
| 14 | Food Texture Quantification Using a Magnetic Food Texture Sensor and Dynamic Time Warping. Food Science and Technology Research, 2018, 24, 257-263.   | 0.3 | 1         |
| 15 | Wearable Lumbar-Motion Monitoring Device with Stretchable Strain Sensors. Journal of Sensors, 2018, 2018, 1-7.  | 0.6 | 10        |
| 16 | Development of a Measurement Device Using a Sheet Stretch Sensor for Chest Wall Motion. The Japanese Journal of Rehabilitation Medicine, 2018, 55, 348-357.   | 0.0 | 2         |
| 17 | Robot-human handover based on motion prediction of human. , 2017, , .   |     | 2         |
| 18 | Rapid Prototyping Human Interfaces Using Stretchable Strain Sensor. Journal of Sensors, 2017, 2017, 1-9.  | 0.6 | 7         |

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|----|---|-----|-----------|
| 19 | Method for measuring tri-axial lumbar motion angles using wearable sheet stretch sensors. PLoS ONE, 2017, 12, e0183651.   | 1.1 | 16        |
| 20 | Estimation method using genetic programming for location and depth on distributed tactile sensor. International Journal of Applied Electromagnetics and Mechanics, 2016, 52, 1221-1229. | 0.3 | 0         |
| 21 | Tactile texture classification using magnetic tactile sensor. International Journal of Applied Electromagnetics and Mechanics, 2016, 52, 1673-1679.                                     | 0.3 | 5         |
| 22 | Pick-Up Motion Based on Vision and Tactile Information in Hand/Arm Robot., 2016,,.  |     | 2         |
| 23 | Stretchable strain sensor for distributed strain measurement and design of measurement circuit. International Journal of Applied Electromagnetics and Mechanics, 2016, 52, 1681-1688.   | 0.3 | 0         |
| 24 | Magnetic Food Texture Sensor Incorporating Human Tooth Structure. Journal of the Japanese Society for Food Science and Technology, 2016, 63, 268-273.                                   | 0.1 | 1         |
| 25 | Human motion caption with vision and inertial sensors for hand/arm robot teleoperation.<br>International Journal of Applied Electromagnetics and Mechanics, 2016, 52, 1629-1636.        | 0.3 | 5         |
| 26 | Stretchable Strain Sensor With Anisotropy and Application for Joint Angle Measurement. IEEE Sensors Journal, 2016, 16, 3572-3579.   | 2.4 | 40        |
| 27 | The Flexible Interface Using a Stretch Sensor. Procedia Manufacturing, 2015, 3, 845-849.  | 1.9 | 1         |
| 28 | Stretchable Strain Sensor Based on Areal Change of Carbon Nanotube Electrode. IEEE Sensors Journal, 2015, 15, 2212-2218.  | 2.4 | 37        |
| 29 | Vision based grasping system with universal jamming hand. , 2015, , .   |     | 5         |
| 30 | Development of Food Texture Sensor Using Two Magnetic Sensing Elements. , 2015, , .   |     | 2         |
| 31 | Design and response performance of capacitance meter for stretchable strain sensor. , 2015, , .   |     | 5         |
| 32 | Estimation of Displacement and Rotation by Magnetic Tactile Sensor Using Stepwise Regression Analysis. Journal of Sensors, 2014, 2014, 1-7.   | 0.6 | 1         |
| 33 | Reliability evaluation of pipe thickness measurement by electromagnetic acoustic transducer. International Journal of Applied Electromagnetics and Mechanics, 2014, 45, 923-929.        | 0.3 | 3         |
| 34 | Application of stretchable strain sensor for pneumatic artificial muscle. , 2014, , .   |     | 7         |
| 35 | Slip based pick-and-place by universal robot hand with force/torque sensors. , 2014, , .  |     | 1         |
| 36 | Motion capture with inertial measurement units for hand/arm robot teleoperation. International Journal of Applied Electromagnetics and Mechanics, 2014, 45, 931-937.                    | 0.3 | 9         |

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|----|--|-----|-----------|
| 37 | Hand/Arm Robot Teleoperation by Inertial Motion Capture. , 2013, , .   |     | 12        |
| 38 | Slip detection using robot fingertip with 6-axis force/torque sensor., 2013,,.   |     | 8         |
| 39 | A study on tactile texture recognition using magnetic type tactile sensor. , 2013, , .   |     | 1         |
| 40 | Application of magnetic type tactile sensor to gripper. , 2013, , .  |     | 3         |
| 41 | Development of haptic device for five-fingered robot hand teleoperation. , 2013, , .   |     | 6         |
| 42 | Evaluation of Circle Diameter by Distributed Tactile Information in Active Tracing. Journal of Sensors, 2013, 2013, 1-7.   | 0.6 | 1         |
| 43 | Structure and fundamental evaluation of magnetic type tactile sensor. International Journal of Applied Electromagnetics and Mechanics, 2012, 39, 1021-1026.                      | 0.3 | 5         |
| 44 | Multipoint haptic device for robot hand teleoperation. , 2012, , .   |     | 4         |
| 45 | Multiple joints reference for robot finger control in robot hand teleoperation. , 2012, , .  |     | 10        |
| 46 | Slip detection with multi-axis force/torque sensor in universal robot hand. International Journal of Applied Electromagnetics and Mechanics, 2012, 39, 1047-1054.                | 0.3 | 7         |
| 47 | Tactile-based object manipulation (TbOM) for a multi-fingered robot hand. International Journal of Applied Electromagnetics and Mechanics, 2012, 39, 1055-1061.                  | 0.3 | 0         |
| 48 | A magnetic type tactile sensor by GMR elements and inductors. , 2010, , .  |     | 21        |
| 49 | Development of multi-fingered universal robot hand with torque limiter mechanism. , 2009, , .  |     | 24        |
| 50 | Outer shape classification in rotation manipulation by Universal Robot Hand., 2009, , .  |     | 0         |
| 51 | Shape Classification in Continuous Rotation Manipulation by Universal Robot Hand. Journal of Advanced Computational Intelligence and Intelligent Informatics, 2009, 13, 178-184. | 0.5 | 2         |
| 52 | Shape classification in rotation manipulation by universal robot hand., 2008,,.  |     | 5         |
| 53 | Development of an Articulated Mechanical Hand with Enveloping Grasp Capability. Journal of Robotics and Mechatronics, 2007, 19, 308-314.   | 0.5 | 3         |
| 54 | Shape Classification using Tactile Information in Rotation Manipulation by Universal Robot Hand. , 0, , .  |     | 7         |