## Metin Sitti

# List of Publications by Year in Descending Order

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

358	22,155	78	138
papers	citations	h-index	g-index
382	27,177 ext. citations	10.3	7.89
ext. papers		avg, IF	L-index

#	Paper	IF	Citations
358	Light-driven carbon nitride microswimmers with propulsion in biological and ionic media and responsive on-demand drug delivery <i>Science Robotics</i> , <b>2022</b> , 7, eabm1421	18.6	13
357	A Tissue Adhesion-Controllable and Biocompatible Small-scale Hydrogel Adhesive Robot <i>Advanced Materials</i> , <b>2022</b> , e2109325	24	9
356	Order and information in the patterns of spinning magnetic micro-disks at the air-water interface <i>Science Advances</i> , <b>2022</b> , 8, eabk0685	14.3	5
355	A Localization Method for Untethered Small-Scale Robots Using Electrical Impedance Tomography. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2022</b> , 1-11	5.5	1
354	Heat-Mitigated Design and Lorentz Force-Based Steering of an MRI-Driven Microcatheter toward Minimally Invasive Surgery <i>Advanced Science</i> , <b>2022</b> , e2105352	13.6	5
353	Control and Transport of Passive Particles Using Self-Organized Spinning Micro-Disks. <i>IEEE Robotics and Automation Letters</i> , <b>2022</b> , 7, 2156-2161	4.2	2
352	Soft actuators for real-world applications <i>Nature Reviews Materials</i> , <b>2022</b> , 7, 235-249	73.3	45
351	High-Performance Magnetic FePt (L1 0 ) Surface Microrollers Towards Medical Imaging-Guided Endovascular Delivery Applications (Adv. Funct. Mater. 8/2022). <i>Advanced Functional Materials</i> , <b>2022</b> , 32, 2270049	15.6	
350	Smart materials: rational design in biosystems via artificial intelligence <i>Trends in Biotechnology</i> , <b>2022</b> ,	15.1	3
349	Miniature coiled artificial muscle for wireless soft medical devices Science Advances, 2022, 8, eabm561	614.3	5
348	BirdBot achieves energy-efficient gait with minimal control using avian-inspired leg clutching <i>Science Robotics</i> , <b>2022</b> , 7, eabg4055	18.6	3
347	High shear rate propulsion of acoustic microrobots in complex biological fluids <i>Science Advances</i> , <b>2022</b> , 8, eabm5126	14.3	5
346	Creating three-dimensional magnetic functional microdevices via molding-integrated direct laser writing <i>Nature Communications</i> , <b>2022</b> , 13, 2016	17.4	3
345	Microrobot collectives with reconfigurable morphologies, behaviors, and functions <i>Nature Communications</i> , <b>2022</b> , 13, 2239	17.4	7
344	Real-time 3D optoacoustic tracking of cell-sized magnetic microrobots circulating in the mouse brain vasculature <i>Science Advances</i> , <b>2022</b> , 8, eabm9132	14.3	7
343	Deep Learning-based 3D Magnetic Microrobot Tracking using 2D MR Images. <i>IEEE Robotics and Automation Letters</i> , <b>2022</b> , 1-1	4.2	2
342	Bayesian Machine Learning for Efficient Minimization of Defects in ALD Passivation Layers. <i>ACS Applied Materials &amp; Defects in ALD Passivation Layers</i> . <i>ACS Applied Materials &amp; Defects in ALD Passivation Layers</i> . <i>ACS Applied Materials &amp; Defects in ALD Passivation Layers</i> .	9.5	2

#### (2021-2021)

3	341	Shape-programmable liquid crystal elastomer structures with arbitrary three-dimensional director fields and geometries. <i>Nature Communications</i> , <b>2021</b> , 12, 5936	17.4	12	
3	340	Permanent magnet array-driven navigation of wireless millirobots inside soft tissues. <i>Science Advances</i> , <b>2021</b> , 7, eabi8932	14.3	10	
3	39	3D-Printed Multi-Stimuli-Responsive Mobile Micromachines. <i>ACS Applied Materials &amp; Amp; Interfaces</i> , <b>2021</b> , 13, 12759-12766	9.5	23	
3	38	Shape anisotropy-governed locomotion of surface microrollers on vessel-like microtopographies against physiological flows. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , <b>2021</b> , 118,	11.5	21	
3	337	Opportunities and utilization of branching and step-out behavior in magnetic microswimmers with a nonlinear response. <i>Applied Physics Letters</i> , <b>2021</b> , 118, 174102	3.4	2	
3	36	Voxelated three-dimensional miniature magnetic soft machines via multimaterial heterogeneous assembly. <i>Science Robotics</i> , <b>2021</b> , 6,	18.6	32	
3	35	Magnetically switchable soft suction grippers. Extreme Mechanics Letters, 2021, 44, 101263	3.9	11	
3	34	Wireless MRI-Powered Reversible Orientation-Locking Capsule Robot <i>Advanced Science</i> , <b>2021</b> , 8, 2100-	4 <b>63</b> .6	10	
3	333	Wirelessly Actuated Thermo- and Magneto-Responsive Soft Bimorph Materials with Programmable Shape-Morphing. <i>Advanced Materials</i> , <b>2021</b> , 33, e2100336	24	16	
3	32	Liquid-Crystal-Elastomer-Actuated Reconfigurable Microscale Kirigami Metastructures. <i>Advanced Materials</i> , <b>2021</b> , 33, e2008605	24	11	
3	331	Effect of body stiffness distribution on larval fish-like efficient undulatory swimming. <i>Science Advances</i> , <b>2021</b> , 7,	14.3	16	
3	30	Mattertronics for programmable manipulation and multiplex storage of pseudo-diamagnetic holes and label-free cells. <i>Nature Communications</i> , <b>2021</b> , 12, 3024	17.4	2	
3	329	Magnetic soft micromachines made of linked microactuator networks. Science Advances, 2021, 7,	14.3	16	
3	28	Task space adaptation via the learning of gait controllers of magnetic soft millirobots <i>International Journal of Robotics Research</i> , <b>2021</b> , 40, 1331-1351	5.7	4	
3	527	Kirigami Metastructures: Liquid-Crystal-Elastomer-Actuated Reconfigurable Microscale Kirigami Metastructures (Adv. Mater. 25/2021). <i>Advanced Materials</i> , <b>2021</b> , 33, 2170195	24		
3	326	Soft-bodied adaptive multimodal locomotion strategies in fluid-filled confined spaces. <i>Science Advances</i> , <b>2021</b> , 7,	14.3	21	
3	325	Stimuli-Responsive Materials: Wirelessly Actuated Thermo- and Magneto-Responsive Soft Bimorph Materials with Programmable Shape-Morphing (Adv. Mater. 30/2021). <i>Advanced Materials</i> , <b>2021</b> , 33, 21	7 <mark>62</mark> 38		
3	324	Design, Actuation, and Control of an MRI-Powered Untethered Robot for Wireless Capsule Endoscopy. <i>IEEE Robotics and Automation Letters</i> , <b>2021</b> , 6, 6000-6007	4.2	5	

323	Remote Modular Electronics for Wireless Magnetic Devices. <i>Advanced Science</i> , <b>2021</b> , 8, e2101198	13.6	3
322	Adaptive Self-Sealing Suction-Based Soft Robotic Gripper. <i>Advanced Science</i> , <b>2021</b> , 8, e2100641	13.6	7
321	Physical intelligence as a new paradigm. Extreme Mechanics Letters, 2021, 46, 101340	3.9	24
320	3D Microprinting of Iron Platinum Nanoparticle-Based Magnetic Mobile Microrobots. <i>Advanced Intelligent Systems</i> , <b>2021</b> , 3, 2000204	6	17
319	Interfacial Engineering for Improved Photocatalysis in a Charge Storing 2D Carbon Nitride: Melamine Functionalized Poly(heptazine imide). <i>Advanced Energy Materials</i> , <b>2021</b> , 11, 2003016	21.8	21
318	Magnetic Resonance Imaging-Compatible Optically Powered Miniature Wireless Modular Lorentz Force Actuators. <i>Advanced Science</i> , <b>2021</b> , 8, 2002948	13.6	7
317	Spider Origami: Folding Principle of Jumping Spider Leg Joints for Bioinspired Fluidic Actuators. <i>Advanced Science</i> , <b>2021</b> , 8, 2003890	13.6	9
316	Nonresonant powering of injectable nanoelectrodes enables wireless deep brain stimulation in freely moving mice. <i>Science Advances</i> , <b>2021</b> , 7,	14.3	25
315	Liquid Crystal Elastomer-Based Magnetic Composite Films for Reconfigurable Shape-Morphing Soft Miniature Machines. <i>Advanced Materials</i> , <b>2021</b> , 33, e2006191	24	31
314	Flexural wave-based soft attractor walls for trapping microparticles and cells. <i>Lab on A Chip</i> , <b>2021</b> , 21, 582-596	7.2	9
313	Liquid Crystal Structure of Supercooled Liquid Gallium and Eutectic Gallium-Indium. <i>Advanced Materials</i> , <b>2021</b> , 33, e2104807	24	1
312	Machine Learning-Based and Experimentally Validated Optimal Adhesive Fibril Designs. <i>Small</i> , <b>2021</b> , 17, e2102867	11	6
311	3D Printing of Elastomeric Bioinspired Complex Adhesive Microstructures. <i>Advanced Materials</i> , <b>2021</b> , 33, e2103826	24	8
310	Liquid Crystal Structure of Supercooled Liquid Gallium and Eutectic GalliumIndium (Adv. Mater. 38/2021). <i>Advanced Materials</i> , <b>2021</b> , 33, 2170301	24	
309	3D printed personalized magnetic micromachines from patient blood-derived biomaterials. <i>Science Advances</i> , <b>2021</b> , 7, eabh0273	14.3	20
308	Fluid mechanics and rheology of the jumping spider body fluid. Soft Matter, 2021, 17, 5532-5539	3.6	1
307	3D Microprinting of Iron Platinum Nanoparticle-Based Magnetic Mobile Microrobots. <i>Advanced Intelligent Systems</i> , <b>2021</b> , 3, 2170012	6	
306	Physical intelligence as a new paradigm Extreme Mechanics Letters, <b>2021</b> , 46, 101340	3.9	

### (2020-2020)

305	Bioinspired cilia arrays with programmable nonreciprocal motion and metachronal coordination. <i>Science Advances</i> , <b>2020</b> , 6,	14.3	40
304	Multifunctional surface microrollers for targeted cargo delivery in physiological blood flow. <i>Science Robotics</i> , <b>2020</b> , 5,	18.6	116
303	Statistical reprogramming of macroscopic self-assembly with dynamic boundaries. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , <b>2020</b> , 117, 11306-11313	11.5	7
302	Introducing Progress in Biomedical Engineering; Issue 2 Vol 2. <i>Progress in Biomedical Engineering</i> , <b>2020</b> , 2, 020201	7.2	
301	Microscale Polarization Color Pixels from Liquid Crystal Elastomers. <i>Advanced Optical Materials</i> , <b>2020</b> , 8, 1902098	8.1	9
300	Microribbons composed of directionally self-assembled nanoflakes as highly stretchable ionic neural electrodes. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , <b>2020</b> , 117, 14667-14675	11.5	29
299	Elucidating the interaction dynamics between microswimmer body and immune system for medical microrobots. <i>Science Robotics</i> , <b>2020</b> , 5,	18.6	66
298	Wearable and Stretchable Strain Sensors: Materials, Sensing Mechanisms, and Applications. <i>Advanced Intelligent Systems</i> , <b>2020</b> , 2, 2000039	6	120
297	A Realistic Simulation Environment for MRI-Based Robust Control of Untethered Magnetic Robots With Intra-Operational Imaging. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 4501-4508	4.2	6
296	Ultrasound-Guided Wireless Tubular Robotic Anchoring System. <i>IEEE Robotics and Automation Letters</i> , <b>2020</b> , 5, 4859-4866	4.2	10
295	High-Yield Production of Biohybrid Microalgae for On-Demand Cargo Delivery. <i>Advanced Science</i> , <b>2020</b> , 7, 2001256	13.6	31
294	Thermal Effects on the Crystallization Kinetics, and Interfacial Adhesion of Single-Crystal Phase-Change Gallium. <i>Advanced Materials</i> , <b>2020</b> , 32, e1907453	24	3
293	Additive manufacturing of cellulose-based materials with continuous, multidirectional stiffness gradients. <i>Science Advances</i> , <b>2020</b> , 6, eaay0929	14.3	33
292	Bioinspired underwater locomotion of light-driven liquid crystal gels. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , <b>2020</b> , 117, 5125-5133	11.5	118
291	Pros and Cons: Magnetic versus Optical Microrobots. <i>Advanced Materials</i> , <b>2020</b> , 32, e1906766	24	96
290	Cohesive self-organization of mobile microrobotic swarms. <i>Soft Matter</i> , <b>2020</b> , 16, 1996-2004	3.6	31
289	Controlling two-dimensional collective formation and cooperative behavior of magnetic microrobot swarms. <i>International Journal of Robotics Research</i> , <b>2020</b> , 39, 617-638	5.7	52
288	Acoustically powered surface-slipping mobile microrobots. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , <b>2020</b> , 117, 3469-3477	11.5	83

287	Multiwavelength-Steerable Visible-Light-Driven Magnetic CoO-TiO Microswimmers. <i>ACS Applied Materials &amp; ACS Applied &amp; </i>	9.5	20
286	Mechanical Coupling of Puller and Pusher Active Microswimmers Influences Motility. <i>Langmuir</i> , <b>2020</b> , 36, 5435-5443	4	21
285	Nanoerythrosome-functionalized biohybrid microswimmers. APL Bioengineering, 2020, 4, 026103	6.6	17
284	Liquid-Superrepellent Bioinspired Fibrillar Adhesives. <i>Advanced Materials</i> , <b>2020</b> , 32, e2000497	24	31
283	Learning of Sub-optimal Gait Controllers for Magnetic Walking Soft Millirobots <b>2020</b> , 2020,		5
282	Multifunctional magnetic soft composites: a review. <i>Multifunctional Materials</i> , <b>2020</b> , 3, 042003	5.2	51
281	Magnetic Resonance Imaging System <b>D</b> riven Medical Robotics. <i>Advanced Intelligent Systems</i> , <b>2020</b> , 2, 1900110	6	22
280	Towards 5-DoF Control of an Untethered Magnetic Millirobot via MRI Gradient Coils <b>2020</b> ,		6
279	The effect of substrate wettability and modulus on gecko and gecko-inspired synthetic adhesion in variable temperature and humidity. <i>Scientific Reports</i> , <b>2020</b> , 10, 19748	4.9	14
278	3D Microstructures of Liquid Crystal Networks with Programmed Voxelated Director Fields. <i>Advanced Materials</i> , <b>2020</b> , 32, e2002753	24	36
277	In-air fast response and high speed jumping and rolling of a light-driven hydrogel actuator. <i>Nature Communications</i> , <b>2020</b> , 11, 3988	17.4	59
276	Selection for Function: From Chemically Synthesized Prototypes to 3D-Printed Microdevices. <i>Advanced Intelligent Systems</i> , <b>2020</b> , 2, 2000078	6	2
275	Biosynthetic self-healing materials for soft machines. <i>Nature Materials</i> , <b>2020</b> , 19, 1230-1235	27	86
274	Reconfigurable multifunctional ferrofluid droplet robots. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , <b>2020</b> , 117, 27916-27926	11.5	49
273	Carbon nitride-based light-driven microswimmers with intrinsic photocharging ability. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , <b>2020</b> , 117, 24748-24756	11.5	26
272	Zwitterionic 3D-Printed Non-Immunogenic Stealth Microrobots. <i>Advanced Materials</i> , <b>2020</b> , 32, e200301	324	47
271	Biodegradable Untethered Magnetic Hydrogel Milli-Grippers. <i>Advanced Functional Materials</i> , <b>2020</b> , 30, 2004975	15.6	39
270	Reprogrammable shape morphing of magnetic soft machines. Science Advances, 2020, 6,	14.3	81

269	Magnetically Actuated Soft Capsule Endoscope for Fine-Needle Biopsy. Soft Robotics, 2020, 7, 10-21	9.2	62
268	Selectively controlled magnetic microrobots with opposing helices. <i>Applied Physics Letters</i> , <b>2020</b> , 116, 134101	3.4	12
267	Welcome toProgress in Biomedical Engineering. <i>Progress in Biomedical Engineering</i> , <b>2019</b> , 1, 010201	7.2	
266	Precise Control of Lyotropic Chromonic Liquid Crystal Alignment through Surface Topography. <i>ACS Applied Materials &amp; District Sciences</i> , <b>2019</b> , 11, 36110-36117	9.5	13
265	Elevation and Azimuth Rotational Actuation of an Untethered Millirobot by MRI Gradient Coils. <i>IEEE Transactions on Robotics</i> , <b>2019</b> , 35, 1323-1337	6.5	20
264	The near and far of a pair of magnetic capillary disks. <i>Soft Matter</i> , <b>2019</b> , 15, 1497-1507	3.6	3
263	Graphene Oxide Synergistically Enhances Antibiotic Efficacy in Vancomycin-Resistant <i>ACS Applied Bio Materials</i> , <b>2019</b> , 2, 1148-1157	4.1	20
262	Mechanics of a pressure-controlled adhesive membrane for soft robotic gripping on curved surfaces. <i>Extreme Mechanics Letters</i> , <b>2019</b> , 30, 100485	3.9	11
261	Shape-encoded dynamic assembly of mobile micromachines. <i>Nature Materials</i> , <b>2019</b> , 18, 1244-1251	27	68
260	Multifarious Transit Gates for Programmable Delivery of Bio-functionalized Matters. <i>Small</i> , <b>2019</b> , 15, e1901105	11	7
259	Temperature Gradients Drive Bulk Flow Within Microchannel Lined by Fluid-Fluid Interfaces. <i>Small</i> , <b>2019</b> , 15, e1900472	11	11
258	Bio-inspired Composite Microfibers for Strong and Reversible Adhesion on Smooth Surfaces. <i>Integrative and Comparative Biology</i> , <b>2019</b> , 59, 227-235	2.8	11
257	3D-Printed Microrobotic Transporters with Recapitulated Stem Cell Niche for Programmable and Active Cell Delivery. <i>Advanced Functional Materials</i> , <b>2019</b> , 29, 1808992	15.6	66
256	Programmable Collective Behavior in Dynamically Self-Assembled Mobile Microrobotic Swarms. <i>Advanced Science</i> , <b>2019</b> , 6, 1801837	13.6	69
255	3D-Printed Biodegradable Microswimmer for Theranostic Cargo Delivery and Release. <i>ACS Nano</i> , <b>2019</b> , 13, 3353-3362	16.7	187
254	. IEEE Transactions on Robotics, <b>2019</b> , 35, 589-601	6.5	3
253	Multifunctional magnetic hairbot for untethered osteogenesis, ultrasound contrast imaging and drug delivery. <i>Biomaterials</i> , <b>2019</b> , 219, 119394	15.6	53
252	Multifunctional and biodegradable self-propelled protein motors. <i>Nature Communications</i> , <b>2019</b> , 10, 3188	17.4	48

251	Thrust and Hydrodynamic Efficiency of the Bundled Flagella. Micromachines, 2019, 10,	3.3	6
250	Translational prospects of untethered medical microrobots. <i>Progress in Biomedical Engineering</i> , <b>2019</b> , 1, 012002	7.2	70
249	Multi-functional soft-bodied jellyfish-like swimming. <i>Nature Communications</i> , <b>2019</b> , 10, 2703	17.4	182
248	Learning to Navigate Endoscopic Capsule Robots. <i>IEEE Robotics and Automation Letters</i> , <b>2019</b> , 4, 3075-3	30,82	11
247	Cutting the Cord: Progress in Untethered Soft Robotics and Actuators. MRS Advances, 2019, 4, 2787-28	<b>04</b> .7	6
246	Optimal controller design for 3D manipulation of buoyant magnetic microrobots via constrained linear quadratic regulation approach. <i>Journal of Micro-Bio Robotics</i> , <b>2019</b> , 15, 105-117	1.4	4
245	Monolithic shape-programmable dielectric liquid crystal elastomer actuators. <i>Science Advances</i> , <b>2019</b> , 5, eaay0855	14.3	60
244	A Simultaneous Calibration Method for Magnetic Robot Localization and Actuation Systems. <i>IEEE Transactions on Robotics</i> , <b>2019</b> , 35, 343-352	6.5	27
243	Simultaneous Six-Degree-of-Freedom Control of a Single-Body Magnetic Microrobot. <i>IEEE Robotics and Automation Letters</i> , <b>2019</b> , 4, 508-514	4.2	15
242	Microfluidics Integrated Lithography-Free Nanophotonic Biosensor for the Detection of Small Molecules. <i>Advanced Optical Materials</i> , <b>2019</b> , 7, 1801313	8.1	13
241	Review of emerging concepts in nanotoxicology: opportunities and challenges for safer nanomaterial design. <i>Toxicology Mechanisms and Methods</i> , <b>2019</b> , 29, 378-387	3.6	100
240	Microrobotics and Microorganisms: Biohybrid Autonomous Cellular Robots. <i>Annual Review of Control, Robotics, and Autonomous Systems</i> , <b>2019</b> , 2, 205-230	11.8	86
239	Mobile Microrobots for Active Therapeutic Delivery. Advanced Therapeutics, 2019, 2, 1800064	4.9	105
238	Wrinkling Instability and Adhesion of a Highly Bendable Gallium Oxide Nanofilm Encapsulating a Liquid-Gallium Droplet. <i>Nano Letters</i> , <b>2018</b> , 18, 2498-2504	11.5	25
237	Sparse-then-dense alignment-based 3D map reconstruction method for endoscopic capsule robots. <i>Machine Vision and Applications</i> , <b>2018</b> , 29, 345-359	2.8	15
236	Independent Actuation of Two-Tailed Microrobots. <i>IEEE Robotics and Automation Letters</i> , <b>2018</b> , 3, 1703	-147.11 0	28
235	Swimming Back and Forth Using Planar Flagellar Propulsion at Low Reynolds Numbers. <i>Advanced Science</i> , <b>2018</b> , 5, 1700461	13.6	24
234	Redox metals homeostasis in multiple sclerosis and amyotrophic lateral sclerosis: a review. <i>Cell Death and Disease</i> , <b>2018</b> , 9, 348	9.8	60

### (2018-2018)

233	Cancer cells biomineralize ionic gold into nanoparticles-microplates via secreting defense proteins with specific gold-binding peptides. <i>Acta Biomaterialia</i> , <b>2018</b> , 71, 61-71	10.8	33
232	Soft erythrocyte-based bacterial microswimmers for cargo delivery. Science Robotics, 2018, 3,	18.6	165
231	Mechanical Rubbing of Blood Clots Using Helical Robots Under Ultrasound Guidance. <i>IEEE Robotics and Automation Letters</i> , <b>2018</b> , 3, 1112-1119	4.2	46
230	Light-Driven Janus Hollow Mesoporous TiO2Au Microswimmers. <i>Advanced Functional Materials</i> , <b>2018</b> , 28, 1704902	15.6	66
229	Small-scale soft-bodied robot with multimodal locomotion. <i>Nature</i> , <b>2018</b> , 554, 81-85	50.4	898
228	Analysis of Magnetic Interaction in Remotely Controlled Magnetic Devices and its Application to a Capsule Robot for Drug Delivery. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2018</b> , 23, 298-310	5.5	25
227	Recent Advances in Wearable Transdermal Delivery Systems. Advanced Materials, 2018, 30, 1704530	24	105
226	Self-Folded Hydrogel Tubes for Implantable Muscular Tissue Scaffolds. <i>Macromolecular Bioscience</i> , <b>2018</b> , 18, e1700377	5.5	38
225	. IEEE Transactions on Magnetics, <b>2018</b> , 54, 1-13	2	6
224	Three-dimensional patterning in biomedicine: Importance and applications in neuropharmacology. Journal of Biomedical Materials Research - Part B Applied Biomaterials, <b>2018</b> , 106, 1369-1382	3.5	19
223	3D Nanoprinted Plastic Kinoform X-Ray Optics. <i>Advanced Materials</i> , <b>2018</b> , 30, e1802503	24	20
222	Motility and chemotaxis of bacteria-driven microswimmers fabricated using antigen 43-mediated biotin display. <i>Scientific Reports</i> , <b>2018</b> , 8, 9801	4.9	26
221	Innate turning preference of leaf-cutting ants in the absence of external orientation cues. <i>Journal of Experimental Biology</i> , <b>2018</b> , 221,	3	6
220	Deep EndoVO: A recurrent convolutional neural network (RCNN) based visual odometry approach for endoscopic capsule robots. <i>Neurocomputing</i> , <b>2018</b> , 275, 1861-1870	5.4	63
219	Collectives of Spinning Mobile Microrobots for Navigation and Object Manipulation at the Air-Water Interface <b>2018</b> ,		8
218	2018,		1
217	Unsupervised Odometry and Depth Learning for Endoscopic Capsule Robots 2018,		13
216	Magnetic- Visual Sensor Fusion-based Dense 3D Reconstruction and Localization for Endoscopic Capsule Robots <b>2018</b> ,		6

215	Seed-mediated synthesis of plasmonic gold nanoribbons using cancer cells for hyperthermia applications. <i>Journal of Materials Chemistry B</i> , <b>2018</b> , 6, 7573-7581	7.3	25
214	Incorporation of Terbium into a Microalga Leads to Magnetotactic Swimmers. <i>Advanced Biology</i> , <b>2018</b> , 2, 1800039	3.5	20
213	Microalga-Powered Microswimmers toward Active Cargo Delivery. <i>Advanced Materials</i> , <b>2018</b> , 30, e1804	11 <u>3.</u> p	86
212	Kinetics of orbitally shaken particles constrained to two dimensions. <i>Physical Review E</i> , <b>2018</b> , 98,	2.4	2
211	Anisotropic Gold Nanostructures: Optimization via in Silico Modeling for Hyperthermia. <i>ACS Applied Nano Materials</i> , <b>2018</b> , 1, 6205-6216	5.6	35
210	Controllable switching between planar and helical flagellar swimming of a soft robotic sperm. <i>PLoS ONE</i> , <b>2018</b> , 13, e0206456	3.7	14
209	EndoSensorFusion: Particle Filtering-Based Multi-Sensory Data Fusion with Switching State-Space Model for Endoscopic Capsule Robots <b>2018</b> ,		7
208	Endo-VMFuseNet: A Deep Visual-Magnetic Sensor Fusion Approach for Endoscopic Capsule Robots <b>2018</b> ,		3
207	Light-Triggered Drug Release from 3D-Printed Magnetic Chitosan Microswimmers. <i>ACS Nano</i> , <b>2018</b> , 12, 9617-9625	16.7	184
206	Morphological intelligence counters foot slipping in the desert locust and dynamic robots.  Proceedings of the National Academy of Sciences of the United States of America, 2018, 115, E8358-E836	7 <sup>11.5</sup>	17
205	Self-Sensing Paper Actuators Based on Graphite-Carbon Nanotube Hybrid Films. <i>Advanced Science</i> , <b>2018</b> , 5, 1800239	13.6	96
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,	An XY ☑ flexure mechanism with optimal stiffness properties <b>2017</b> ,	,	4
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172	Recent Advances in Skin Penetration Enhancers for Transdermal Gene and Drug Delivery. <i>Current Gene Therapy</i> , <b>2017</b> , 17, 139-146	4.3	37
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150 149	Biomedical Applications of Untethered Mobile Milli/Microrobots. <i>Proceedings of the IEEE</i> , <b>2015</b> ,	14.3	456
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149 148 147	Biomedical Applications of Untethered Mobile Milli/Microrobots. <i>Proceedings of the IEEE</i> , <b>2015</b> , 103, 205-224  Experimental Investigation of Optimal Adhesion of Mushroomlike Elastomer Microfibrillar Adhesives. <i>Langmuir</i> , <b>2015</b> , 31, 10119-24  pH-Taxis of Biohybrid Microsystems. <i>Scientific Reports</i> , <b>2015</b> , 5, 11403  Segmented molecular design of self-healing proteinaceous materials. <i>Scientific Reports</i> , <b>2015</b> , 5, 13482  Transfer Printing of Metallic Microstructures on Adhesion-Promoting Hydrogel Substrates.	4.9	<ul><li>21</li><li>79</li><li>29</li></ul>

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118	Tank-Like Module-Based Climbing Robot Using Passive Compliant Joints. <i>IEEE/ASME Transactions on Mechatronics</i> , <b>2013</b> , 18, 397-408	5.5	82
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99	Magnetic hysteresis for multi-state addressable magnetic microrobotic control 2012,		6
98	Automated 2-D Nanoparticle Manipulation Using Atomic Force Microscopy. <i>IEEE Nanotechnology Magazine</i> , <b>2011</b> , 10, 472-481	2.6	32
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94	Assembly and disassembly of magnetic mobile micro-robots towards deterministic 2-D reconfigurable micro-systems <b>2011</b> ,		2
93	Assembly and disassembly of magnetic mobile micro-robots towards deterministic 2-D reconfigurable micro-systems. <i>International Journal of Robotics Research</i> , <b>2011</b> , 30, 1667-1680	5.7	72
92	Free flight simulations and pitch and roll control experiments of a sub-gram flapping-flight micro aerial vehicle <b>2011</b> ,		12
91	Control of multiple heterogeneous magnetic micro-robots on non-specialized surfaces 2011,		7
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84	Microstructured elastomeric surfaces with reversible adhesion and examples of their use in deterministic assembly by transfer printing. <i>Proceedings of the National Academy of Sciences of the United States of America</i> , <b>2010</b> , 107, 17095-100	11.5	280
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82	Adhesion recovery and passive peeling in a wall climbing robot using adhesives 2010,		4
81	Control performance simulation in the design of a flapping wing micro-aerial vehicle 2010,		2
80	Flat Dry Elastomer Adhesives as Attachment Materials for Climbing Robots. <i>IEEE Transactions on Robotics</i> , <b>2010</b> , 26, 131-141	6.5	38
79	Characterization of bacterial actuation of micro-objects 2009,		8
78	Waalbot: Agile climbing with synthetic fibrillar dry adhesives <b>2009</b> ,		3
77	Microparticle manipulation using multiple untethered magnetic micro-robots on an electrostatic surface <b>2009</b> ,		14
76	Multiple magnetic microrobot control using electrostatic anchoring. <i>Applied Physics Letters</i> , <b>2009</b> , 94, 164108	3.4	92
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7 <sup>2</sup>	Enhanced adhesion by gecko-inspired hierarchical fibrillar adhesives. <i>ACS Applied Materials &amp;</i> Interfaces, <b>2009</b> , 1, 849-55	9.5	277

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70	Automated 2-D nanoparticle manipulation with an atomic force microscope <b>2009</b> ,		4
69	Two-Dimensional Contact and Noncontact Micromanipulation in Liquid Using an Untethered Mobile Magnetic Microrobot. <i>IEEE Transactions on Robotics</i> , <b>2009</b> , 25, 1332-1342	6.5	122
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67	A miniature ceiling walking robot with flat tacky elastomeric footpads 2009,		28
66	Compliant footpad design analysis for a bio-inspired quadruped amphibious robot 2009,		10
65	Reversible dry micro-fibrillar adhesives with thermally controllable adhesion. <i>Soft Matter</i> , <b>2009</b> , 5, 3689	3.6	106
64	Modeling and Experimental Characterization of an Untethered Magnetic Micro-Robot. <i>International Journal of Robotics Research</i> , <b>2009</b> , 28, 1077-1094	5.7	234
63	Gecko-inspired directional and controllable adhesion. <i>Small</i> , <b>2009</b> , 5, 170-5	11	350
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61	Adhesion of Biologically Inspired Oil-Coated Polymer Micropillars. <i>Journal of Adhesion Science and Technology</i> , <b>2008</b> , 22, 569-589	2	31
60	Gecko inspired micro-fibrillar adhesives for wall climbing robots on micro/nanoscale rough surfaces <b>2008</b> ,		71
59	A motorized anchoring mechanism for a tethered capsule robot using fibrillar adhesives for interventions in the esophagus <b>2008</b> ,		10
58	An untethered magnetically actuated micro-robot capable of motion on arbitrary surfaces 2008,		49
57	Bacterial propulsion of chemically patterned micro-cylinders 2008,		4
56	Performance of different foot designs for a water running robot 2008,		10
55	Design and Development of the Lifting and Propulsion Mechanism for a Biologically Inspired Water Runner Robot <b>2008</b> , 24, 698-709		58
54	Rolling and Spinning Friction Characterization of Fine Particles Using Lateral Force Microscopy Based Contact Pushing. <i>Journal of Adhesion Science and Technology</i> , <b>2008</b> , 22, 481-506	2	56

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52	Dynamic modeling of a basilisk lizard inspired quadruped robot running on water 2008,		1
51	Fabrication of Bio-Inspired Elastomer Nanofiber Arrays with Spatulate Tips using Notching Effect <b>2008</b> ,		4
50	Simulation and analysis of a passive pitch reversal flapping wing mechanism for an aerial robotic platform <b>2008</b> ,		6
49	Effect of quantity and configuration of attached bacteria on bacterial propulsion of microbeads. <i>Applied Physics Letters</i> , <b>2008</b> , 93, 223901	3.4	113
48	Vision-based feedback strategy for controlled pushing of microparticles. <i>Journal of Micro-Nano Mechatronics</i> , <b>2008</b> , 4, 73-83		11
47	Adhesion and anisotropic friction enhancements of angled heterogeneous micro-fiber arrays with spherical and spatula tips. <i>Journal of Adhesion Science and Technology</i> , <b>2007</b> , 21, 1281-1296	2	170
46	Bacterial flagella-based propulsion and on/off motion control of microscale objects. <i>Applied Physics Letters</i> , <b>2007</b> , 90, 023902	3.4	255
45	Surface-Tension-Driven Biologically Inspired Water Strider Robots: Theory and Experiments <b>2007</b> , 23, 578-589		134
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