## Lin Li

## List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/1487879/publications.pdf

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		1163117	1058476	
15	204	8	14	
papers	citations	h-index	g-index	
15	15	15	210	
all docs	docs citations	times ranked	citing authors	

#	Article	IF	Citations
1	Designing distributed consensus protocols for second-order nonlinear multi-agents with unknown control directions under directed graphs. Journal of the Franklin Institute, 2017, 354, 571-592.	3.4	46
2	Fully Distributed Low-Complexity Control for Nonlinear Strict-Feedback Multiagent Systems With Unknown Dead-Zone Inputs. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2020, 50, 421-431.	9.3	35
3	Distributed Cooperative Control of Multiple Nonholonomic Mobile Robots. Journal of Intelligent and Robotic Systems: Theory and Applications, 2016, 83, 525-541.	3.4	25
4	Distributed adaptive output consensus tracking of higher-order systems with unknown control directions. Neurocomputing, 2016, 203, 129-138.	5.9	17
5	On mode-dependent filtering for network-based discrete-time systems. Signal Processing, 2013, 93, 634-640.	3.7	16
6	Generalised nonlinear <i> </i> <sub>2</sub> â€" <i> </i> <sub>â°ž</sub> filtering of discrete-time Markov jump descriptor systems. International Journal of Control, 2014, 87, 653-664.	1.9	16
7	Distributed adaptive output feedback tracking control for a class of uncertain nonlinear multi-agent systems. International Journal of Systems Science, 2017, 48, 587-603.	5.5	14
8	A generalized nonlinear filter design for discrete-time Lipschitz descriptor systems. Nonlinear Analysis: Real World Applications, 2014, 15, 1-11.	1.7	12
9	\$\$ H_{infty} \$\$ Filtering for Discrete-Time Singular Markovian Jump Systems with Generally Uncertain Transition Rates. Circuits, Systems, and Signal Processing, 2021, 40, 3204-3226. <mml:math <="" altimg="si0005.gif" p="" xmlns:mml="http://www.w3.org/1998/Math/MathML"></mml:math>	2.0	9
10	overflow="scroll"> <mml:msub><mml:mrow><mml:mi mathvariant="script">L</mml:mi></mml:mrow><mml:mrow><mml:mn>2</mml:mn></mml:mrow></mml:msub> mathvariant="script">L <mml:mrow><mml:mo>â^ž</mml:mo></mml:mrow> <td>&gt; &lt; mml:mc b &gt; <td>o&gt;–nath&gt;filter</td></td>	> < mml:mc b > <td>o&gt;–nath&gt;filter</td>	o>–nath>filter
11	500-520. Altitude Information Acquisition of UAV Based on Monocular Vision and MEMS. Journal of Intelligent and Robotic Systems: Theory and Applications, 2020, 98, 807-818.	3.4	4
12	Delay-Dependent Hâ^ž Control for Singular Markovian Jump Systems With Generally Uncertain Transition Rates. IEEE Access, 2020, 8, 214128-214140.	4.2	2
13	Reliablel2–lâ^žandHâ^žControl for Nonlinear Singular Systems via Dynamic Output Feedback. Abstract and Applied Analysis, 2014, 2014, 1-9.	0.7	1
14	Mode-dependent robust and non-fragile finite-time Hâ^ž control for nonlinear singular Markovian jump systems. Transactions of the Institute of Measurement and Control, 2022, 44, 368-377.	1.7	1
15	Guaranteedâ€performance consensus for nonlinear singular multiagent systems with directed topologies. Asian Journal of Control, 0, , .	3.0	O