

Hiroshi Ito

List of Publications by Year in descending order

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6
papers

49
citations

2682572

2
h-index

2053705

5
g-index

7
all docs

7
docs citations

7
times ranked

5
citing authors

#	ARTICLE	IF	CITATIONS
1	Efficient multitask learning with an embodied predictive model for door opening and entry with whole-body control. <i>Science Robotics</i> , 2022, 7, eaax8177.	17.6	32
2	Contact-Rich Manipulation of a Flexible Object based on Deep Predictive Learning using Vision and Tactility. , 2022, , .		9
3	Deep Active Visual Attention for Real-Time Robot Motion Generation: Emergence of Tool-Body Assimilation and Adaptive Tool-Use. <i>IEEE Robotics and Automation Letters</i> , 2022, 7, 8550-8557.	5.1	3
4	Evaluation of Generalization Performance of Visuo-Motor Learning by Analyzing Internal State Structured from Robot Motion. <i>New Generation Computing</i> , 2020, 38, 7-22.	3.3	2
5	Rapid prototyping for series of tasks in atypical environment: robotic system with reliable program-based and flexible learning-based approaches. <i>ROBOMECH Journal</i> , 2022, 9, .	1.6	2
6	Deep Learning-Based Manipulation of a Fabric Bag Zipper using Tactile Sensors. <i>The Proceedings of JSME Annual Conference on Robotics and Mechatronics (Robomec)</i> , 2021, 2021, 1P3-D04.	0.0	1