

Xuechao Duan

List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/1451225/publications.pdf>

Version: 2024-02-01

26
papers

286
citations

933447

10
h-index

940533

16
g-index

26
all docs

26
docs citations

26
times ranked

234
citing authors

| # | ARTICLE | IF | CITATIONS |
|----|--|-----|-----------|
| 1 | Improved Extreme Learning Machine Based UWB Positioning for Mobile Robots with Signal Interference. <i>Machines</i> , 2022, 10, 218. | 2.2 | 8 |
| 2 | Investigation of compact packing strategy for large rigid-panel deployable antennas. <i>Mechanism and Machine Theory</i> , 2022, 176, 104930. | 4.5 | 6 |
| 3 | Robust Loop Closure Detection Integrating Visual“Spatial”Semantic Information via Topological Graphs and CNN Features. <i>Remote Sensing</i> , 2020, 12, 3890. | 4.0 | 18 |
| 4 | Principal Component Weighted Grey Relational Analysis Method for Power Load Characteristic Forecasting. <i>Lecture Notes in Electrical Engineering</i> , 2020, , 222-229. | 0.4 | 0 |
| 5 | An Improved Robust Method for Pose Estimation of Cylindrical Parts with Interference Features. <i>Sensors</i> , 2019, 19, 2234. | 3.8 | 6 |
| 6 | Design and DOF Analysis of a Novel Compliant Parallel Mechanism for Large Load. <i>Sensors</i> , 2019, 19, 828. | 3.8 | 11 |
| 7 | Topology optimization of pretensioned reflector antennas with unified cable-bar model. <i>Acta Astronautica</i> , 2018, 152, 872-879. | 3.2 | 7 |
| 8 | Short-Term Power Load Forecasting Method Based on Improved Exponential Smoothing Grey Model. <i>Mathematical Problems in Engineering</i> , 2018, 2018, 1-11. | 1.1 | 59 |
| 9 | The Application Research of Inverse Finite Element Method for Frame Deformation Estimation. <i>International Journal of Aerospace Engineering</i> , 2017, 2017, 1-8. | 0.9 | 14 |
| 10 | Modeling and Control of the Redundant Parallel Adjustment Mechanism on a Deployable Antenna Panel. <i>Sensors</i> , 2016, 16, 1632. | 3.8 | 4 |
| 11 | Modeling and Analysis of a 2-DOF Spherical Parallel Manipulator. <i>Sensors</i> , 2016, 16, 1485. | 3.8 | 21 |
| 12 | Vibration Isolation and Trajectory Following Control of a Cable Suspended Stewart Platform. <i>Machines</i> , 2016, 4, 20. | 2.2 | 5 |
| 13 | On the mechatronic servo bandwidth of a stewart platform for active vibration isolating in a super antenna. <i>Robotics and Computer-Integrated Manufacturing</i> , 2016, 40, 66-77. | 9.9 | 12 |
| 14 | A Novel Online Self-Structuring Fuzzy Control Algorithm and Its Application. <i>Mathematical Problems in Engineering</i> , 2015, 2015, 1-10. | 1.1 | 0 |
| 15 | Complete real solution of the five-orientation motion generation problem for a spherical four-bar linkage. <i>Chinese Journal of Mechanical Engineering (English Edition)</i> , 2015, 28, 258-266. | 3.7 | 3 |
| 16 | A large-stroke compliant joint“based force/displacement integrated sensor. <i>Advances in Mechanical Engineering</i> , 2015, 7, 168781401562290. | 1.6 | 0 |
| 17 | Optimization of the workspace of a MEMS hexapod nanopositioner using an adaptive genetic algorithm. , 2014, , . | | 6 |
| 18 | Workspace Classification and Quantification Calculations of Cable-Driven Parallel Robots. <i>Advances in Mechanical Engineering</i> , 2014, 6, 358727. | 1.6 | 22 |

| # | ARTICLE | IF | CITATIONS |
|----|--|-----|-----------|
| 19 | Calibration and Motion Control of a Cable-Driven Parallel Manipulator Based Triple-Level Spatial Positioner. <i>Advances in Mechanical Engineering</i> , 2014, 6, 368018. | 1.6 | 19 |
| 20 | Dynamic Analysis and Vibration Attenuation of Cable-Driven Parallel Manipulators for Large Workspace Applications. <i>Advances in Mechanical Engineering</i> , 2013, 5, 361585. | 1.6 | 9 |
| 21 | Nonlinear PD Control of a Long-Span Cable-Supporting Manipulator in Quasi-Static Motion. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2012, 134, . | 1.6 | 3 |
| 22 | Real-time motion planning for the macro-micro parallel manipulator system. , 2011, , . | | 3 |
| 23 | Motion prediction and supervisory control of the macro-micro parallel manipulator system. <i>Robotica</i> , 2011, 29, 1005-1015. | 1.9 | 16 |
| 24 | Jacobian analysis of a long-span cable-driven manipulator and its application to forward solution. <i>Mechanism and Machine Theory</i> , 2010, 45, 1227-1238. | 4.5 | 25 |
| 25 | Supervisory control of a macro-micro parallel manipulator system. , 2010, , . | | 1 |
| 26 | Adaptive Interactive PID Supervisory Control of the Macro-micro Parallel Manipulator. <i>Jixie Gongcheng Xuebao/Chinese Journal of Mechanical Engineering</i> , 2010, 46, 10. | 0.5 | 8 |