Pubudu N Pathirana

List of Publications by Year in descending order

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229 papers

5,814 citations

147726 31 h-index 91828 69 g-index

232 all docs 232 docs citations

times ranked

232

3937 citing authors

#	Article	IF	CITATIONS
1	6G Internet of Things: A Comprehensive Survey. IEEE Internet of Things Journal, 2022, 9, 359-383.	5.5	366
2	Federated Learning for Internet of Things: A Comprehensive Survey. IEEE Communications Surveys and Tutorials, 2021, 23, 1622-1658.	24.8	365
3	Optimality analysis of sensor-target localization geometries. Automatica, 2010, 46, 479-492.	3.0	362
4	Blockchain for Secure EHRs Sharing of Mobile Cloud Based E-Health Systems. IEEE Access, 2019, 7, 66792-66806.	2.6	340
5	Federated Learning Meets Blockchain in Edge Computing: Opportunities and Challenges. IEEE Internet of Things Journal, 2021, 8, 12806-12825.	5.5	255
6	Blockchain for 5G and beyond networks: A state of the art survey. Journal of Network and Computer Applications, 2020, 166, 102693.	5.8	239
7	Node localization using mobile robots in delay-tolerant sensor networks. IEEE Transactions on Mobile Computing, 2005, 4, 285-296.	3.9	215
8	Artificial Intelligence (AI) and Big Data for Coronavirus (COVID-19) Pandemic: A Survey on the State-of-the-Arts. IEEE Access, 2020, 8, 130820-130839.	2.6	212
9	A survey on blockchain for big data: Approaches, opportunities, and future directions. Future Generation Computer Systems, 2022, 131, 209-226.	4.9	184
10	Discrete Wirtinger-based inequality and its application. Journal of the Franklin Institute, 2015, 352, 1893-1905.	1.9	155
11	Monitoring and Analysis of Respiratory Patterns Using Microwave Doppler Radar. IEEE Journal of Translational Engineering in Health and Medicine, 2014, 2, 1-12.	2.2	119
12	Integration of Blockchain and Cloud of Things: Architecture, Applications and Challenges. IEEE Communications Surveys and Tutorials, 2020, 22, 2521-2549.	24.8	117
13	Privacy-Preserved Task Offloading in Mobile Blockchain With Deep Reinforcement Learning. IEEE Transactions on Network and Service Management, 2020, 17, 2536-2549.	3.2	114
14	Bearing-Only Localization using Geometrically Constrained Optimization. IEEE Transactions on Aerospace and Electronic Systems, 2009, 45, 308-320.	2.6	98
15	Blockchain and Al-Based Solutions to Combat Coronavirus (COVID-19)-Like Epidemics: A Survey. IEEE Access, 2021, 9, 95730-95753.	2.6	93
16	Blockchain for Edge of Things: Applications, Opportunities, and Challenges. IEEE Internet of Things Journal, 2022, 9, 964-988.	5.5	90
17	Location Estimation and Trajectory Prediction for Cellular Networks With Mobile Base Stations. IEEE Transactions on Vehicular Technology, 2004, 53, 1903-1913.	3.9	85
18	BEdgeHealth: A Decentralized Architecture for Edge-Based IoMT Networks Using Blockchain. IEEE Internet of Things Journal, 2021, 8, 11743-11757.	5.5	85

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19	Exploiting geometry for improved hybrid AOA/TDOA-based localization. Signal Processing, 2008, 88, 1775-1791.	2.1	81
20	Further result on reachable set bounding for linear uncertain polytopic systems with interval time-varying delays. Automatica, 2011, 47, 1838-1841.	3.0	80
21	Discrete inequalities based on multiple auxiliary functions and their applications to stability analysis of time-delay systems. Journal of the Franklin Institute, 2015, 352, 5810-5831.	1.9	77
22	Enabling AI in Future Wireless Networks: A Data Life Cycle Perspective. IEEE Communications Surveys and Tutorials, 2021, 23, 553-595.	24.8	75
23	Smartwatch: Performance evaluation for long-term heart rate monitoring. , 2015, , .		62
24	Genomic mutations and changes in protein secondary structure and solvent accessibility of SARS-CoV-2 (COVID-19 virus). Scientific Reports, 2021, 11, 3487.	1.6	62
25	Problem of precision missile guidance: LQR and H//supâ^ž/ control frameworks. IEEE Transactions on Aerospace and Electronic Systems, 2003, 39, 901-910.	2.6	60
26	Optimality Analysis of Sensor-Target Geometries in Passive Localization: Part 2 - Time-of-Arrival Based Localization., 2007,,.		60
27	Optimality Analysis of Sensor-Target Geometries in Passive Localization: Part 1 - Bearing-Only Localization. , 2007, , .		60
28	Federated Learning for COVID-19 Detection With Generative Adversarial Networks in Edge Cloud Computing. IEEE Internet of Things Journal, 2022, 9, 10257-10271.	5.5	55
29	Reachable set bounding for nonlinear perturbed time-delay systems: The smallest bound. Applied Mathematics Letters, 2015, 43, 68-71.	1.5	45
30	A Mobile Cloud based IoMT Framework for Automated Health Assessment and Management., 2019, 2019, 6517-6520.		42
31	Optimal Range-Difference-Based Localization Considering Geometrical Constraints. IEEE Journal of Oceanic Engineering, 2008, 33, 289-301.	2.1	39
32	Robust observer design for uncertain oneâ€sided Lipschitz systems with disturbances. International Journal of Robust and Nonlinear Control, 2018, 28, 1366-1380.	2.1	39
33	Assessment of Shoulder Range of Motion Using a Wireless Inertial Motion Capture Device—A Validation Study. Sensors, 2019, 19, 1781.	2.1	36
34	BioKin: an ambulatory platform for gait kinematic and feature assessment. Healthcare Technology Letters, 2015, 2, 40-45.	1.9	34
35	Localization of Emitters via the Intersection of Bearing Lines: A Ghost Elimination Approach. IEEE Transactions on Vehicular Technology, 2007, 56, 3106-3110.	3.9	33
36	Quantitative assessment of cerebellar ataxia, through automated limb functional tests. Journal of NeuroEngineering and Rehabilitation, 2019, 16, 31.	2.4	33

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37	Swarm intelligence for next-generation networks: Recent advances and applications. Journal of Network and Computer Applications, 2021, 191, 103141.	5.8	32
38	Quantification of Axial Abnormality Due to Cerebellar Ataxia with Inertial Measurements. Sensors, 2018, 18, 2791.	2.1	31
39	Robust observer and observer-based control designs for discrete one-sided Lipschitz systems subject to uncertainties and disturbances. Applied Mathematics and Computation, 2019, 353, 42-53.	1.4	31
40	Secure Computation Offloading in Blockchain Based IoT Networks With Deep Reinforcement Learning. IEEE Transactions on Network Science and Engineering, 2021, 8, 3192-3208.	4.1	31
41	Stability of positive coupled differential-difference equations with unbounded time-varying delays. Automatica, 2018, 92, 259-263.	3.0	28
42	$\hat{l}\mu\text{-bounded}$ state estimation for time-delay systems with bounded disturbances. International Journal of Control, 2014, 87, 1747-1756.	1.2	27
43	Noncontact Detection and Analysis of Respiratory Function Using Microwave Doppler Radar. Journal of Sensors, 2015, 2015, 1-13.	0.6	27
44	Convergence within a polyhedron: controller design for timeâ€delay systems with bounded disturbances. IET Control Theory and Applications, 2015, 9, 905-914.	1.2	27
45	Optimal Sensor Arrangements in Angle of Arrival (AoA) and Range Based Localization with Linear Sensor Arrays. Sensors, 2013, 13, 12277-12294.	2.1	25
46	A Non-Contact Measurement System for the Range of Motion of the Hand. Sensors, 2015, 15, 18315-18333.	2.1	25
47	Radar Target Tracking via Robust Linear Filtering. IEEE Signal Processing Letters, 2007, 14, 1028-1031.	2.1	24
48	Minimization of State Bounding for Perturbed Positive Systems with Delays. SIAM Journal on Control and Optimization, 2018, 56, 1739-1755.	1.1	22
49	Quantitative Evaluation of Cerebellar Ataxia Through Automated Assessment of Upper Limb Movements. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2019, 27, 1081-1091.	2.7	22
50	A Random Forest Approach for Quantifying Gait Ataxia With Truncal and Peripheral Measurements Using Multiple Wearable Sensors. IEEE Sensors Journal, 2020, 20, 723-734.	2.4	22
51	Robust observer-based control designs for discrete nonlinear systems with disturbances. European Journal of Control, 2018, 44, 65-72.	1.6	21
52	Cooperative Task Offloading and Block Mining in Blockchain-Based Edge Computing With Multi-Agent Deep Reinforcement Learning. IEEE Transactions on Mobile Computing, 2023, 22, 2021-2037.	3.9	21
53	Robust Video/Ultrasonic Fusion-Based Estimation for Automotive Applications. IEEE Transactions on Vehicular Technology, 2007, 56, 1631-1639.	3.9	20
54	Vision-Based Target Tracking and Surveillance With Robust Set-Valued State Estimation. IEEE Signal Processing Letters, 2010, 17, 289-292.	2.1	20

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55	Robust Real-Time Bio-Kinematic Movement Tracking Using Multiple Kinects for Tele-Rehabilitation. IEEE Transactions on Industrial Electronics, 2016, 63, 1822-1833.	5.2	20
56	Identification of moving obstacles with Pyramidal Lucas Kanade optical flow and ${\tt k}$ means clustering. , 2007, , .		19
57	Remote Monitoring System Enabling Cloud Technology upon Smart Phones and Inertial Sensors for Human Kinematics. , 2014 , , .		19
58	Automated Topographic Prominence based quantitative assessment of speech timing in Cerebellar Ataxia. Biomedical Signal Processing and Control, 2020, 57, 101759.	3.5	19
59	Objective Assessment of Cerebellar Ataxia: A Comprehensive and Refined Approach. Scientific Reports, 2020, 10, 9493.	1.6	19
60	A Cooperative Architecture of Data Offloading and Sharing for Smart Healthcare with Blockchain. , 2021, , .		18
61	Stability analysis of a general family of nonlinear positive discrete time-delay systems. International Journal of Control, 2016, 89, 1303-1315.	1.2	17
62	Measurement of Axial Rigidity and Postural Instability Using Wearable Sensors. Sensors, 2018, 18, 495.	2.1	16
63	On <mml:math altimg="si192.svg" display="inline" id="d1e91" xmlns:mml="http://www.w3.org/1998/Math/MathML"><mml:msub><mml:mrow><mml:mi>â,,"</mml:mi></mml:mrow><mml:mrow><mml:mn>1< control of 2-D positive Roesser systems with directional delays: Necessary and sufficient conditions. Automatica. 2020. 112. 108720.</mml:mn></mml:mrow></mml:msub></mml:math>	:/mml;mn>	·
64	Blockchain and Edge Computing for Decentralized EMRs Sharing in Federated Healthcare. , 2020, , .		16
65	On backwards and forwards reachable sets bounding for perturbed time-delay systems. Applied Mathematics and Computation, 2015, 269, 664-673.	1.4	15
66	The Assessment of Upper Limb Functionality in Friedreich Ataxia via Self-Feeding Activity. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2020, 28, 924-933.	2.7	15
67	De-risking resource recovery value chains for a circular economy – Accounting for supply and demand variations in recycled aggregate concrete. Resources, Conservation and Recycling, 2021, 168, 105312.	5.3	15
68	Robust extended Kalman filter based technique for location management in PCS networks. Computer Communications, 2004, 27, 502-512.	3.1	14
69	Robust Optical Flow with Combined Lucas-Kanade/Horn-Schunck and Automatic Neighborhood Selection. , 2006, , .		14
70	Linear functional state bounding for positive systems with disturbances varying within a bounded set. Automatica, 2020, 111, 108644.	3.0	14
71	Quantitative Assessment of Speech in Cerebellar Ataxia Using Magnitude and Phase Based Cepstrum. Annals of Biomedical Engineering, 2020, 48, 1322-1336.	1.3	14
72	Exponential Convergence of Time-Delay Systems in the Presence of Bounded Disturbances. Journal of Optimization Theory and Applications, 2013, 157, 843-852.	0.8	13

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73	Partial state bounding with a preâ€specified time of nonâ€linear discrete systems with timeâ€varying delays. IET Control Theory and Applications, 2016, 10, 1496-1502.	1.2	13
74	Secrecy Performance of the UAV Enabled Cognitive Relay Network., 2018,,.		13
75	Robust and Accurate Capture of Human Joint Pose Using an Inertial Sensor. IEEE Journal of Translational Engineering in Health and Medicine, 2018, 6, 1-11.	2.2	13
76	Balance Deficits due to Cerebellar Ataxia: A Machine Learning and Cloud-Based Approach. IEEE Transactions on Biomedical Engineering, 2021, 68, 1507-1517.	2.5	13
77	Geometric formations in swarm aggregation: An artificial formation force based approach., 2007,,.		12
78	Simultaneous estimation of optical flow and object state: A modified approach to optical flow calculation. , 2007, , .		12
79	Formations of Robotic Swarm: An Artificial Force Based Approach. International Journal of Advanced Robotic Systems, 2009, 6, 7.	1.3	12
80	Multitarget Tracking via Space Transformations Using a Single Frequency Continuous Wave Radar. IEEE Transactions on Signal Processing, 2012, 60, 5217-5229.	3.2	12
81	Multi-kinect skeleton fusion for physical rehabilitation monitoring. , 2014, 2014, 5060-3.		12
82	A comprehensive scheme for the objective upper body assessments of subjects with cerebellar ataxia. Journal of NeuroEngineering and Rehabilitation, 2020, 17, 162.	2.4	12
83	Componentwise ultimate bounds for positive discrete time-delay systems perturbed by interval disturbances. Automatica, 2016, 72, 153-157.	3.0	11
84	Optimal Trajectories for Homing Navigation with Bearing Measurements. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2008, 41, 12117-12123.	0.4	10
85	A Syntactic Two-Component Encoding Model for the Trajectories of Human Actions. IEEE Journal of Biomedical and Health Informatics, 2014, 18, 1903-1914.	3.9	10
86	An adaptive complementary filter for inertial sensor based data fusion to track upper body motion. , 2014, , .		10
87	Separation of Doppler radar-based respiratory signatures. Medical and Biological Engineering and Computing, 2016, 54, 1169-1179.	1.6	10
88	Entropy-based analysis of rhythmic tapping for the quantitative assessment of cerebellar ataxia. Biomedical Signal Processing and Control, 2020, 59, 101916.	3.5	10
89	Deep Reinforcement Learning for Collaborative Offloading in Heterogeneous Edge Networks. , 2021, , .		10
90	Artificial Formation Forces for Stable Aggregation of Multi-Agent System. , 2006, , .		9

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91	Speed control and policing in a cellular mobile network: SpeedNet. Computer Communications, 2006, 29, 3633-3646.	3.1	9
92	Improvement on delay dependent absolute stability of Lurie control systems with multiple time delays. Applied Mathematics and Computation, 2010, 216, 1024-1027.	1.4	9
93	Robust Localization With Minimum Number of TDoA Measurements. IEEE Signal Processing Letters, 2013, 20, 949-951.	2.1	9
94	Doppler radar in respiratory monitoring: Detection and analysis. , 2013, , .		9
95	Stability Analysis of Nonlinear Time-Delay Systems Using a Novel Piecewise Positive Systems Method. IEEE Transactions on Automatic Control, 2018, 63, 291-297.	3.6	9
96	Position estimation and tracking of an autonomous mobile sensor using received signal strength. , 2008, , .		8
97	Formations of Robotic Swarm: An Artificial Force Based Approach. International Journal of Advanced Robotic Systems, 2010, 7, 23.	1.3	8
98	PLANE WAVE SCATTERING BY A SPHERICAL DIELECTRIC PARTICLE IN MOTION: A RELATIVISTIC EXTENSION OF THE MIE THEORY. Progress in Electromagnetics Research, 2011, 112, 349-379.	1.6	8
99	Fusion Based 3D Tracking of Mobile Transmitters via Robust Set-Valued State Estimation with RSS Measurements. IEEE Communications Letters, 2011, 15, 554-556.	2.5	8
100	Robust state estimation for nonâ€linear systems with unknown delays. IET Control Theory and Applications, 2019, 13, 1147-1154.	1.2	8
101	Federated Deep Learning for the Diagnosis of Cerebellar Ataxia: Privacy Preservation and Auto-Crafted Feature Extractor. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2022, 30, 803-811.	2.7	8
102	Decentralized and Robust Target Tracking with Sensor Networks. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2008, 41, 14969-14975.	0.4	7
103	Functional range of movement of the hand: Declination angles to reachable space. , 2014, 2014, 6230-3.		7
104	Quantitative Assessment of Cerebellar Ataxia With Kinematic Sensing During Rhythmic Tapping. , 2018, 2018, 1098-1101.		7
105	Utility Optimization for Blockchain Empowered Edge Computing with Deep Reinforcement Learning. , 2021, , .		7
106	Smart Cluster Bombs - Control of Multi-agent Systems for Military Applications. , 2007, , .		6
107	Data monitoring sensor network for BigNet research Testbed. , 2009, , .		6
108	Optimal sensor separation for AoA based localization via linear sensor array. , 2010, , .		6

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109	Uplink Power Control via Adaptive Hidden-Markov-Model-Based Pathloss Estimation. IEEE Transactions on Mobile Computing, 2013, 12, 657-665.	3.9	6
110	Linear functional state bounding for perturbed time-delay systems and its application. IMA Journal of Mathematical Control and Information, 2015, 32, 245-255.	1.1	6
111	Entropyâ€based method to quantify limb length discrepancy using inertial sensors. IET Wireless Sensor Systems, 2018, 8, 10-16.	1.3	6
112	Sensing and Characterization of the Wrist Using Dart Thrower's Movement. IEEE Sensors Journal, 2018, 18, 4145-4153.	2.4	6
113	Automated Finger Chase (ballistic tracking) in the Assessment of Cerebellar Ataxia. , 2018, 2018, 3521-3524.		6
114	Quantitative Assessment of Syllabic Timing Deficits in Ataxic Dysarthria., 2018, 2018, 425-428.		6
115	Quantitative Assessment of Ataxic Gait using Inertial Sensing at Different Walking Speeds. , 2019, 2019, 4600-4603.		6
116	Sensor fusion based missile guidance. , 2003, , .		5
117	Localization with orientation using RSSI measurements: RF map based approach., 2007,,.		5
118	A Robust Solution to the Stereo-Vision-Based Simultaneous Localization and Mapping Problem with Steady and Moving Landmarks. Advanced Robotics, 2011, 25, 765-788.	1.1	5
119	Facilitating communication and computer use with EEG devices for non-vocal quadriplegics. , 2014, , .		5
120	Real-Time Lane Detection on Suburban Streets Using Visual Cue Integration. International Journal of Advanced Robotic Systems, 2014, 11 , 61 .	1.3	5
121	Quantitative Assessment of ADL: A Pilot Study of Upper Extremity Reaching Tasks. Journal of Sensors, 2015, 2015, 1-13.	0.6	5
122	Identification of Cerebellar Dysarthria with SISO Characterisation., 2017,,.		5
123	An Instrumented Measurement Scheme for the Assessment of Upper Limb Function in Individuals with Friedreich Ataxia., 2019, 2019, 317-320.		5
124	Automated Evaluation of Upper Limb Motor Impairment of Patient with Cerebellar Ataxia., 2019, 2019, 6846-6849.		5
125	Instrumented Objective Clinical Examination of Cerebellar Ataxia: the Upper and Lower Limbâ€"a Review. Cerebellum, 2021, , 1.	1.4	5
126	Quantitative Assessment of Friedreich Ataxia via Self-Drinking Activity. IEEE Journal of Biomedical and Health Informatics, 2021, 25, 1985-1996.	3.9	5

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127	Sensor Fusion Based Localization of a Mobile User in a Wireless Network., 2005,,.		4
128	A discussion on passive location discovery in emitter networks using angle-only measurements. , 2006, , .		4
129	Object focused simultaneous estimation of optical flow and state dynamics. , 2008, , .		4
130	Visual Tracking of Vehicles using Multiresolution Analysis and Neural Network., 2008,,.		4
131	TDOA based transmitter localization with minimum number of receivers and power measurements. , 2008, , .		4
132	Tracking multiple mobile agents with single frequency Continuous Wave radar., 2009,,.		4
133	A state space based approach in non-linear hemodynamic response modeling with fMRI data. , 2010, 2010, 2391-4.		4
134	Eigen decomposition solution to the one-dimensional time-dependent photon transport equation. Optics Express, 2011, 19, 2922.	1.7	4
135	Further applications of Doppler radar for non-contact respiratory assessment. , 2013, 2013, 3833-6.		4
136	Respiration rate and breathing patterns from Doppler radar measurements. , 2014, , .		4
137	Cloud-based non-invasive tele-rehabilitation exercise monitoring. , 2014, , .		4
138	A summative scoring system for evaluation of human kinematic performance. Biomedical Signal Processing and Control, 2016, 23, 85-92.	3.5	4
139	Developing an Instrumented Measure of Upper Limb Function in Friedreich Ataxia. Cerebellum, 2021, 20, 430-438.	1.4	4
140	Objective Assessment of Progression and Disease Characterization of Friedreich Ataxia via an Instrumented Drinking Cup: Preliminary Results. IEEE Transactions on Neural Systems and Rehabilitation Engineering, 2021, 29, 2365-2377.	2.7	4
141	Location based Power Control for Mobile Devices in a Cellular Network. , 2005, , .		3
142	Target Tracking with Range and Bearing Measurements via Robust Linear Filtering. , 2007, , .		3
143	Optimal sensor placement in linear arrays: Part I & Dytimal sensor pla		3
144	Optimization-based formation of autonomous mobile robots. Robotica, 2011, 29, 515-525.	1.3	3

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145	Motion artefact separation in single channel Doppler radar respiration measurement., 2015,,.		3
146	Quantification of the Finger Functional Range via Explicit Descriptions of Reachable Subspaces. IEEE Transactions on Instrumentation and Measurement, 2016, 65, 1412-1422.	2.4	3
147	Quantitative Assessment of Cerebella Ataxia, through Automated Limb-Coordination tests. , 2019, 2019, 6850-6853.		3
148	Measurement and Assessment of Hand Functionality via a Cloud-Based Implementation. Lecture Notes in Computer Science, 2015, , 289-294.	1.0	3
149	Quantitative assessment of cerebella ataxia through automated upper limb functional tests. , 2019, , .		3
150	Using Autonomous Mobile Agents for Efficient Data Collection in Sensor Networks. , 2006, , .		2
151	On the Effect of Path Loss Rates on the Optimal Receiver Position in Sensor Networks. , 2006, , .		2
152	Location Based Power Control for Energy Critical Sensors in a Disconnected Network., 2006,,.		2
153	Distributed Power Control in Cellular Mobile Radio Systems with Time-Varying Link Gains. , 2007, , .		2
154	Energy Efficient, Fully-Connected Mesh Networks for High Speed Applications. IEEE Vehicular Technology Conference, 2008, , .	0.2	2
155	A method for stereo-vision-based tracking for robotic applications. Robotica, 2010, 28, 517-524.	1.3	2
156	Optimal sensor placement in range based localization for linear arrays. , 2012, , .		2
157	Non-contact measurement of respiratory function and deduction of tidal volume., 2014, 2014, 594-7.		2
158	Real-time measurement of radiocarpal joint angle during dart-thrower's movement., 2015,,.		2
159	A Mobile Cloud Computing Framework Integrating Multilevel Encoding for Performance Monitoring in Telerehabilitation. Mathematical Problems in Engineering, 2015, 2015, 1-14.	0.6	2
160	Motion trajectory analysis for evaluating the performance of functional upper extremity tasks in daily living: a pilot study., 2015, 2015, 2701-4.		2
161	An adaptive orientation misalignment calibration method for shoulder movements using inertial sensors: A feasibility study. , 2015, , .		2
162	Motion capturing of biomechanical systems in traditional dance using IMU sensors., 2017,,.		2

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163	Automated tongue-twister phrase-based screening for Cerebellar Ataxia using Vocal tract Biomarkers. , 2019, 2019, 7173-7176.		2
164	Multi-domain Data Capture and Cloud Buffered Multimodal Evaluation Platform for Clinical Assessment of Cerebellar Ataxia., 2020, 2020, 5640-5643.		2
165	A Comparative Severity Assessment of Impaired Balance due to Cerebellar Ataxia using Regression Models., 2020, 2020, 4571-4574.		2
166	Multimodal Data Acquisition for the Assessment of Cerebellar Ataxia via Ballistic Tracking. , 2020, 2020, 859-862.		2
167	Modeling the Progression of Speech Deficits in Cerebellar Ataxia Using a Mixture Mixed-Effect Machine Learning Framework. IEEE Access, 2021, 9, 135343-135353.	2.6	2
168	A Sensor-Based Comprehensive Objective Assessment of Motor Symptoms in Cerebellar Ataxia. , 2020, 2020, 816-819.		2
169	Diagnosis Cerebellar Ataxia using Deep Learning with Time Series Transformed Image. , 2021, 2021, 3101-3104.		2
170	Terminal approach navigation for autonomous robots in a sensory network. , 0, , .		1
171	Speed control and policing in a cellular mobile network: SpeedNet. , 0, , .		1
172	Robust Parallel Filtering for Mobile Agent Tracking. , 2006, , .		1
173	Distributed power control in cellular mobile radio systems with time-varying link gains. , 2006, , .		1
174	Robust Video/Ultrasonic Fusion Based Estimation for Automotive Applications. , 2006, , .		1
175	Planar Receiver Placement for Unique Emitter Localization for Indoor Applications. , 2007, , .		1
176	Stereo-Vision-Based Moving Object Tracking via Robust Linear Filtering. , 2007, , .		1
177	Localization of mobile transmitters by means of linear state estimation using RSS measurements. , 2008, , .		1
178	Detection of vehicles with monolithic classifier vis-à-vis a boosted cascaded classifier., 2009,,.		1
179	Knowlege on road information in sub-urban lane detection via multiple cue integration. , 2010, , .		1
180	Maximum likelihood estimation for Rician distributed data in analytical q-ball imaging. , 2010, 2010, 2702-5.		1

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181	Formation control of weak autonomous robots. , 2011, , .		1
182	Localization with ghost elimination of emitters via time-of-arrival measurements. , 2012, , .		1
183	A general pose estimation algorithm in a multi-Kinect system. , 2014, , .		1
184	A machine-driven process for human limb length estimation using inertial sensors. , 2015, , .		1
185	Deducing the reachable space from fingertip positions. , 2015, 2015, 7578-81.		1
186	A comparison for capturing arm kinematics using solutions of Wahba's problem and ordinary data fusion mechanisms. , 2016, , .		1
187	Suppression of interference in continuous wave Doppler radar based respiratory measurements. Biomedical Signal Processing and Control, 2016, 25, 86-90.	3.5	1
188	Restricted dart throwing movement for the assessment of wrist functionality. , 2017, , .		1
189	Human Gender Recognition with Upper Body Gait Kinematics. , 2017, , .		1
190	A constrained nonlinear optimization solution for 3D orientation estimation of the human limb. , 2017, , .		1
191	Parkinsonian Axial Movement Capture using Wearable Sensors during the Pull Test., 2017, , .		1
192	Effect of Parkinsonism on Proximal Unstructured Movement Captured by Inertial Sensors. , 2018, 2018, 5507-5510.		1
193	Qualification of Wrist Functional Performance During Dart Thrower's Movement. , 2018, 2018, 5790-5793.		1
194	Quantitative Assessment of Friedreich Ataxia through the self-drinking activity., 2020, 2020, 820-823.		1
195	Functional Dart-Throwing Motion: A Clinical Comparison of Four-Corner Fusion to Radioscapholunate Fusion Using Inertial Motion Capture. Journal of Wrist Surgery, 2020, 09, 321-327.	0.3	1
196	A Kinematic Based Evaluation of Upper Extremity Movement Smoothness for Tele-Rehabilitation. Lecture Notes in Computer Science, 2015, , 221-231.	1.0	1
197	Distributed Power Control in Cellular Mobile Radio Systems with Time-Varying Link Gains. , 2006, , .		1
198	Assessment of Disease Progression in Friedreich Ataxia using an Instrumented Self Feeding Activity., 2020, 2020, 3827-3830.		1

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199	Vision based target tracking using robust linear filtering. , 2007, , .		1
200	Robust Terminal Attitude Navigation for Autonomous Vehicles., 2005,,.		0
201	Robust Parallel Filtering Design of a Swarm Tracking System. , 2006, , .		0
202	Maintaining Optimal Co-Channel Interference for Power Efficient Wireless Communication., 2007,,.		0
203	Passive Angle Measurement Based LocalizationConsistency via Geometric Constraints., 2007,,.		0
204	Trajectory characterizations for a discrete-time bearing-only navigation strategy. , 2008, , .		0
205	Two Stage Architecture for Navigating Multiple Guided Weapons into a Widespread Target. Aerospace Conference Proceedings IEEE, 2008, , .	0.0	0
206	A New Distributed Power Control Formula In CDMA Mobile Networks. IEEE Vehicular Technology Conference, 2008, , .	0.2	0
207	A method for stereo-vision based tracking for robotic applications. , 2008, , .		0
208	Power control in CDMA systems based on channel identification. , 2008, , .		0
209	Optimal Trajectory Characterization for a Pursuer Navigation Scheme. , 2008, , .		0
210	Robust Power Controllers in Cellular Radio Systems. IEEE Vehicular Technology Conference, 2008, , .	0.2	0
211	A robust set-valued state estimation approach to the problem of vision based SLAM for mobile robots. , 2009, , .		0
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