Nicola Bellotto

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/1413674/publications.pdf

Version: 2024-02-01

| | | 567281 | 477307 |
|----------|----------------|--------------|----------------|
| 52 | 1,324 | 15 | 29 |
| papers | citations | h-index | g-index |
| | | | |
| | | | |
| - 4 | - 4 | - 4 | 1057 |
| 54 | 54 | 54 | 1257 |
| all docs | docs citations | times ranked | citing authors |
| | | | |

| # | Article | IF | Citations |
|----|---|------|-----------|
| 1 | Multisensor-Based Human Detection and Tracking for Mobile Service Robots. IEEE Transactions on Systems, Man, and Cybernetics, 2009, 39, 167-181. | 5.0 | 259 |
| 2 | Stress Detection Using Wearable Physiological and Sociometric Sensors. International Journal of Neural Systems, 2017, 27, 1650041. | 5.2 | 132 |
| 3 | Online learning for human classification in 3D LiDAR-based tracking. , 2017, , . | | 69 |
| 4 | ENRICHME: Perception and Interaction of an Assistive Robot for the Elderly at Home. International Journal of Social Robotics, 2020, 12, 779-805. | 4.6 | 65 |
| 5 | Pedestrian Models for Autonomous Driving Part II: High-Level Models of Human Behavior. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 5453-5472. | 8.0 | 62 |
| 6 | Cue-based aggregation with a mobile robot swarm: a novel fuzzy-based method. Adaptive Behavior, 2014, 22, 189-206. | 1.9 | 61 |
| 7 | Online learning for 3DÂLiDAR-based human detection: experimental analysis of point cloud clustering and classification methods. Autonomous Robots, 2020, 44, 147-164. | 4.8 | 61 |
| 8 | Computationally efficient solutions for tracking people withÂaÂmobile robot: an experimental evaluation of Bayesian filters. Autonomous Robots, 2010, 28, 425-438. | 4.8 | 56 |
| 9 | Stress Detection Using Wearable Physiological Sensors. Lecture Notes in Computer Science, 2015, , 526-532. | 1.3 | 56 |
| 10 | Pedestrian Models for Autonomous Driving Part I: Low-Level Models, From Sensing to Tracking. IEEE Transactions on Intelligent Transportation Systems, 2021, 22, 6131-6151. | 8.0 | 40 |
| 11 | Vision and Laser Data Fusion for Tracking People with a Mobile Robot. , 2006, , . | | 34 |
| 12 | A distributed camera system for multi-resolution surveillance. , 2009, , . | | 27 |
| 13 | Cognitive visual tracking and camera control. Computer Vision and Image Understanding, 2012, 116, 457-471. | 4.7 | 25 |
| 14 | Analysis of human-robot spatial behaviour applying a qualitative trajectory calculus. , 2012, , . | | 24 |
| 15 | Social activity recognition based on probabilistic merging of skeleton features with proximity priors from RGB-D data., 2016,,. | | 24 |
| 16 | Deep Spiking Neural Network for Video-Based Disguise Face Recognition Based on Dynamic Facial Movements. IEEE Transactions on Neural Networks and Learning Systems, 2020, 31, 1843-1855. | 11.3 | 24 |
| 17 | Multisensor Online Transfer Learning for 3D LiDAR-Based Human Detection with a Mobile Robot. , 2018, , . | | 22 |
| 18 | Appearance-based localization for mobile robots using digital zoom and visual compass. Robotics and Autonomous Systems, 2008, 56, 143-156. | 5.1 | 21 |

| # | Article | IF | CITATIONS |
|----|---|------|-----------|
| 19 | A Bank of Unscented Kalman Filters for Multimodal Human Perception with Mobile Service Robots. International Journal of Social Robotics, 2010, 2, 121-136. | 4.6 | 21 |
| 20 | A Computational Model of Human-Robot Spatial Interactions Based on a Qualitative Trajectory Calculus. Robotics, 2015, 4, 63-102. | 3.5 | 21 |
| 21 | Multisensor data fusion for joint people tracking and identification with a service robot., 2007,,. | | 20 |
| 22 | Integrating Mobile Robotics and Vision With Undergraduate Computer Science. IEEE Transactions on Education, 2013, 56, 48-53. | 2.4 | 16 |
| 23 | Progressive Co-adaptation in Human-Machine Interaction. , 2015, , . | | 15 |
| 24 | Automatic detection of human interactions from RGB-D data for social activity classification. , 2017, , . | | 14 |
| 25 | Social Activity Recognition on Continuous RGB-D Video Sequences. International Journal of Social Robotics, 2020, 12, 201-215. | 4.6 | 12 |
| 26 | Robot perception of static and dynamic objects with an autonomous floor scrubber. Intelligent Service Robotics, 2020, 13, 403-417. | 2.6 | 12 |
| 27 | Thermal Camera Based Physiological Monitoring with an Assistive Robot. , 2018, 2018, 5010-5013. | | 11 |
| 28 | Human Re-Identification with a Robot Thermal Camera Using Entropy-Based Sampling. Journal of Intelligent and Robotic Systems: Theory and Applications, 2020, 98, 85-102. | 3.4 | 11 |
| 29 | People Tracking and Identification with a Mobile Robot. , 2007, , . | | 10 |
| 30 | Qualitative Design and Implementation of Human-Robot Spatial Interactions. Lecture Notes in Computer Science, 2013, , 331-340. | 1.3 | 10 |
| 31 | Comparison of Different Cue-Based Swarm Aggregation Strategies. Lecture Notes in Computer Science, 2014, , 1-8. | 1.3 | 10 |
| 32 | Enhancing LGMD's Looming Selectivity for UAV With Spatial–Temporal Distributed Presynaptic Connections. IEEE Transactions on Neural Networks and Learning Systems, 2023, 34, 2539-2553. | 11.3 | 8 |
| 33 | Performance of a Visual Fixation Model in an Autonomous Micro Robot Inspired by Drosophila Physiology. , 2018, , . | | 6 |
| 34 | The EnrichMe Project. Lecture Notes in Computer Science, 2016, , 326-334. | 1.3 | 6 |
| 35 | HMM-based Activity Recognition with a Ceiling RGB-D Camera., 2017,,. | | 6 |
| 36 | QTC3D: Extending the qualitative trajectory calculus to three dimensions. Information Sciences, 2015, 322, 20-30. | 6.9 | 5 |

| # | Article | IF | Citations |
|----|---|-----|-----------|
| 37 | Multimodal perception and recognition of humans with a mobile service robot., 2009,,. | | 4 |
| 38 | Generative design and fabrication of a locust-inspired gliding wing prototype for micro aerial robots. Journal of Computational Design and Engineering, 2021, 8, 1191-1203. | 3.1 | 4 |
| 39 | Social distance augmented qualitative trajectory calculus for Human-Robot Spatial Interaction. , 2014, | | 3 |
| 40 | On-Line Inference Comparison with Markov Logic Network Engines for Activity Recognition in AAL Environments. , 2016, , . | | 3 |
| 41 | Human Detection and Tracking. , 2018, , 1-10. | | 3 |
| 42 | Understanding images in biological and computer vision. Interface Focus, 2018, 8, 20180027. | 3.0 | 3 |
| 43 | A Dataset for Action Recognition in the Wild. Lecture Notes in Computer Science, 2019, , 362-374. | 1.3 | 3 |
| 44 | Volume-based Human Re-identification with RGB-D Cameras. , 2017, , . | | 3 |
| 45 | Experimental Analysis of a Spatialised Audio Interface for People with Visual Impairments. ACM Transactions on Accessible Computing, 2020, 13, 1-21. | 2.4 | 3 |
| 46 | Cognitive active vision for human identification. , 2012, , . | | 2 |
| 47 | Entropy-based abnormal activity detection fusing RGB-D and domotic sensors. , 2017, , . | | 2 |
| 48 | Real-time Object Detection using Deep Learning for helping People with Visual Impairments. , 2020, , . | | 2 |
| 49 | Bone-Conduction Audio Interface to Guide People with Visual Impairments. Communications in Computer and Information Science, 2019, , 542-553. | 0.5 | 2 |
| 50 | Active Object Search with a Mobile Device for People with Visual Impairments. , 2019, , . | | 2 |
| 51 | Lux - An interactive receptionist robot for university open days. , 2008, , . | | 1 |
| 52 | Neural Task Success Classifiers for Robotic Manipulation from Few Real Demonstrations., 2021,,. | | 1 |