Yau-Zen Chang

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/1392721/publications.pdf

Version: 2024-02-01

1307594 940533 46 301 7 16 citations g-index h-index papers 46 46 46 261 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Practical and flexible path planning for car-like mobile robot using maximal-curvature cubic spiral. Robotics and Autonomous Systems, 2005, 52, 312-335.	5.1	56
2	On the adaptive control of flexible joint robots. Automatica, 1992, 28, 969-974.	5.0	39
3	The electrochemical behavior of austenitic stainless steel with different degrees of sensitization in the transpassive potential region in 1 M H2SO4 containing chloride. Corrosion Science, 2004, 46, 1501-1513.	6.6	37
4	Application of the Genetic Algorithm to the Multi-Objective Optimization of Air Bearings. Tribology Letters, 2004, 17, 119-128.	2.6	30
5	The surface alloying behavior of martensitic stainless steel cut with wire electrical discharge machine. Applied Surface Science, 2006, 252, 2915-2926.	6.1	18
6	Robust fuzzy stabilization of dithered chaotic systems using island-based random optimization algorithm. Information Sciences, 2008, 178, 1171-1188.	6.9	15
7	A Hybrid Search Algorithm for Porous Air Bearings Optimization. Tribology Transactions, 2002, 45, 471-477.	2.0	13
8	A comparative study of smooth path planning for a mobile robot by evolutionary multi-objective optimization., 2007,,.		11
9	Derivation of optimal processing parameters of polypropylene foam thermoforming by an artificial neural network. Polymer Engineering and Science, 2005, 45, 375-384.	3.1	7
10	Biomechanical Evaluation of an Orthodontic Miniimplant Used With Revolving (Translation and) Tj ETQq0 0 0 rg Dentistry, 2013, 22, 77-82.	gBT /Overlo 1.3	ock 10 Tf 50 38 7
11	Stereo matching for infrared images using guided filtering weighted by exponential moving average. IET Image Processing, 2020, 14, 830-837.	2.5	7
12	Robust fuzzy control and evolutionary fuzzy identification of singularly perturbed nonlinear systems with parameter uncertainty. Electrical Engineering, 2008, 90, 379-393.	2.0	6
13	Application of non-destructive impedance-based monitoring technique for cyclic fatigue evaluation of endodontic nickel–titanium rotary instruments. Medical Engineering and Physics, 2011, 33, 604-609.	1.7	6
14	Parallel genetic algorithms for a neurocontrol problem. , 0, , .		5
15	Human face detection with neural networks and the DIRECT algorithm. Artificial Life and Robotics, 2008, 12, 112-115.	1.2	5
15 16	Human face detection with neural networks and the DIRECT algorithm. Artificial Life and Robotics, 2008, 12, 112-115. Efficient Stereo Matching Based on Pervasive Guided Image Filtering. Mathematical Problems in Engineering, 2019, 2019, 1-11.	1.2	
	2008, 12, 112-115. Efficient Stereo Matching Based on Pervasive Guided Image Filtering. Mathematical Problems in		5

#	Article	IF	Citations
19	Collision Detection of Deformable Polyhedral Objects via Inner-outer Ellipsoids. , 2006, , .		3
20	Supervised Adaptive PID Control of Unknown Nonlinear Systems Using Fuzzily Blended Time-Varying Canonical Model. IEEE International Conference on Fuzzy Systems, 2007, , .	0.0	2
21	3D registration of human face using evolutionary computation and Kriging interpolation. Artificial Life and Robotics, 2008, 13, 242-245.	1.2	2
22	Optimizing the Swiss-Roll Recuperator of an Innovative Micro Gas Turbine by a Surrogate Neural Network and the Multi-Objective DIRECT Algorithm. , 2008, , .		2
23	Uniformly spaced 3D modeling of human face from two images using parallel particle swarm optimization. Proceedings of SPIE, $2011, \ldots$	0.8	2
24	Optimal fuzzy tracking control of uncertain nonlinear systems based on genetic algorithms and fuzzy Lyapunov function. Journal of Intelligent and Fuzzy Systems, 2013, 24, 121-132.	1.4	2
25	Development of a visual compressive trackng system enhanced by adaptive boosting. , 2015, , .		2
26	Supervised Adaptive Control of Unknown Nonlinear Systems Using Fuzzily Blended Time-Varying Canonical Model., 2007,, 464-472.		2
27	Integration of a stereo vision system and a laser range finder for 3-D construction. Artificial Life and Robotics, 2009, 14, 228-232.	1.2	1
28	Three dimensional map construction using a scanning laser range finder. Proceedings of SPIE, 2009, , .	0.8	1
29	Calibration of a dual-PTZ camera system for stereo vision. Proceedings of SPIE, 2010, , .	0.8	1
30	Investigation of hybrid optimization methods to evolve effective gaits of a hexapedal robot., 2010,,.		1
31	Switched Two-LevelHâ^žand Robust Fuzzy Learning Control of an Overhead Crane. Mathematical Problems in Engineering, 2013, 2013, 1-12.	1.1	1
32	Construction of Fuzzy Map for Autonomous Mobile Robots Based on Fuzzy Confidence Model. Mathematical Problems in Engineering, 2014, 2014, 1-8.	1.1	1
33	Two-level robust adaptive fuzzy control of aircraft. , 2014, , .		1
34	Adaptive MIMO Supervisory Control Design Using Modeling Error. Mathematical Problems in Engineering, 2015, 2015, 1-8.	1.1	1
35	Stereo Matching Based on Guided Image Filtering with Permeability Filter. , 2019, , .		1
36	Accurate Calibration of a Robotic Positioning System Using the Evolutionary Search. Industrial Electronics Society (IECON), Annual Conference of IEEE, 2006, , .	0.0	0

#	Article	IF	CITATIONS
37	Supervised adaptive control for temperature regulation. , 2009, , .		0
38	Adaptive inverse control of a temperature regulation system with feedforward., 2012,,.		0
39	Application of real-time single camera SLAM technology for image-guided targeting in neurosurgery. , 2012, , .		O
40	Adaptive Neuron-Like Control of Time-Delay Systems Enhanced with Feedforward and Supervisory Strategies. Mathematical Problems in Engineering, 2013, 2013, 1-5.	1.1	0
41	Biomechanical evaluation of an orthodontic mini-implant with plastic removal cap: An in-vitro experimental testing., 2013, 2013, 3183-5.		O
42	Registration for frameless brain surgery based on stereo imaging. , 2013, 2013, 3998-4001.		0
43	Efficient Stereo Matching with Decoupled Dissimilarity Measure Using Successive Weighted Summation. Mathematical Problems in Engineering, 2014, 2014, 1-9.	1.1	O
44	Experimental Investigation of a Prediction Algorithm for an Indoor SLAM Platform. Lecture Notes in Computer Science, 2010, , 154-165.	1.3	0
45	Nonlinear Model Predictive Control of a Rotary Crane System using On-Line Optimization. , 2011, , .		O
46	Accurate stereo matching based on weighted nonlocal aggregation for enhanced disparity refinement. Journal of Electronic Imaging, 2018, 27, 1.	0.9	O