## Joel Lehman

## List of Publications by Year in Descending Order

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

31	1,174	14	34
papers	citations	h-index	g-index
34	1,571 ext. citations	7	5.14
ext. papers		avg, IF	L-index

#	Paper	IF	Citations
31	First return, then explore. <i>Nature</i> , <b>2021</b> , 590, 580-586	50.4	23
30	The Surprising Creativity of Digital Evolution: A Collection of Anecdotes from the Evolutionary Computation and Artificial Life Research Communities. <i>Artificial Life</i> , <b>2020</b> , 26, 274-306	1.4	31
29	Evolvability ES <b>2019</b> ,		2
28	Tradeoffs in Neuroevolutionary Learning-Based Real-Time Robotic Task Design in the Imprecise Computation Framework. <i>ACM Transactions on Cyber-Physical Systems</i> , <b>2019</b> , 3, 1-29	2.3	3
27	POET <b>2019</b> ,		10
26	Designing neural networks through neuroevolution. <i>Nature Machine Intelligence</i> , <b>2019</b> , 1, 24-35	22.5	227
25	Safe mutations for deep and recurrent neural networks through output gradients 2018,		19
24	ES is more than just a traditional finite-difference approximator 2018,		14
23	The Surprising Creativity of Digital Evolution 2018,		24
22	Learning Behavior Characterizations for Novelty Search 2016,		16
21	Evolvability Search <b>2016</b> ,		7
20	On the Critical Role of Divergent Selection in Evolvability. Frontiers in Robotics and AI, 2016, 3,	2.8	5
19	Enhancing Divergent Search through Extinction Events <b>2015</b> ,		7
18	Investigating Biological Assumptions through Radical Reimplementation. <i>Artificial Life</i> , <b>2015</b> , 21, 21-46	1.4	4
17	Why Greatness Cannot Be Planned <b>2015</b> ,		29
16	Tradeoffs in Real-Time Robotic Task Design with Neuroevolution Learning for Imprecise Computation <b>2015</b> ,		2
15	The Interesting and the Novel <b>2015</b> , 39-54		

## LIST OF PUBLICATIONS

14	Extinction events can accelerate evolution. <i>PLoS ONE</i> , <b>2015</b> , 10, e0132886	3.7	11
13	A Neuroevolution Approach to General Atari Game Playing. IEEE Transactions on Games, 2014, 6, 355-36	66	64
12	Overcoming deception in evolution of cognitive behaviors 2014,		13
11	Grasping novel objects with a dexterous robotic hand through neuroevolution 2014,		10
10	Encouraging reactivity to create robust machines. Adaptive Behavior, 2013, 21, 484-500	1.1	15
9	Evolvability is inevitable: increasing evolvability without the pressure to adapt. <i>PLoS ONE</i> , <b>2013</b> , 8, e621	867	33
8	Boosting Interactive Evolution Using Human Computation Markets. <i>Lecture Notes in Computer Science</i> , <b>2013</b> , 1-18	0.9	1
7	Multirobot Behavior Synchronization through Direct Neural Network Communication. <i>Lecture Notes in Computer Science</i> , <b>2012</b> , 603-614	0.9	7
6	Abandoning objectives: evolution through the search for novelty alone. <i>Evolutionary Computation</i> , <b>2011</b> , 19, 189-223	4.3	400
5	Task switching in multirobot learning through indirect encoding <b>2011</b> ,		5
4	2011,		21
3	Evolving a diversity of virtual creatures through novelty search and local competition 2011,		140
2	Novelty Search and the Problem with Objectives. <i>Genetic and Evolutionary Computation</i> , <b>2011</b> , 37-56	0.8	27
1	Rewarding Reactivity to Evolve Robust Controllers without Multiple Trials or Noise		4