Wook Hyun Kwon

List of Publications by Year in Descending Order

Source: https://exaly.com/author-pdf/12071941/wook-hyun-kwon-publications-by-year.pdf

Version: 2024-04-10

This document has been generated based on the publications and citations recorded by exaly.com. For the latest version of this publication list, visit the link given above.

The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

| 95 | 3,132 citations | 24 | 55 |
|--------------------|----------------------|-------------|-----------------|
| papers | | h-index | g-index |
| 141 ext. papers | 3,979 ext. citations | 3.4 avg, IF | 4.77 L-index |

| # | Paper | IF | Citations |
|----|--|-----|-----------|
| 95 | Guaranteed Cost Controls. Communications and Control Engineering, 2019, 133-185 | 0.6 | |
| 94 | Stability of Time-Delay Systems. Communications and Control Engineering, 2019, 27-63 | 0.6 | 1 |
| 93 | State Feedback Stabilizing Controls. Communications and Control Engineering, 2019, 65-93 | 0.6 | |
| 92 | Active Channel Reservation for Coexistence Mechanism (ACROS) for IEEE 802.15.4 and IEEE 802.11. <i>IEICE Transactions on Communications</i> , 2010 , E93-B, 2082-2087 | 0.5 | 4 |
| 91 | LMS finite memory estimators for discrete-time state space models 2009, | | 1 |
| 90 | Rapid control prototyping for robot soccer. <i>Robotica</i> , 2009 , 27, 1091-1102 | 2.1 | 1 |
| 89 | A Continuous-Time Recursive Fixed-Lag Smoother Converging in Finite Time. <i>IEEE Transactions on Automatic Control</i> , 2009 , 54, 1613-1618 | 5.9 | 4 |
| 88 | A Best Lag Size of Minimum Variance FIR Smoothers. <i>IEEE Signal Processing Letters</i> , 2009 , 16, 307-310 | 3.2 | 1 |
| 87 | Best Linear Unbiased Fir Filters For Continuous-Time State Space Models. <i>Asian Journal of Control</i> , 2008 , 3, 1-9 | 1.7 | 2 |
| 86 | RECEDING HORIZON HICONTROL FOR SYSTEMS WITH A STATE-DELAY. <i>Asian Journal of Control</i> , 2008 , 8, 63-71 | 1.7 | 13 |
| 85 | Receding Horizon Controls for Input-Delayed Systems. <i>IEEE Transactions on Automatic Control</i> , 2008 , 53, 1746-1752 | 5.9 | 23 |
| 84 | Robust FIR Filters for Linear Continuous-Time State-Space Models With Uncertainties. <i>IEEE Signal Processing Letters</i> , 2008 , 15, 621-624 | 3.2 | 1 |
| 83 | A Note on Two-Filter Smoothing Formulas. <i>IEEE Transactions on Automatic Control</i> , 2008 , 53, 849-854 | 5.9 | 9 |
| 82 | FIR Filters for Stationary State Space Signal Models. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2008 , 41, 3701-3706 | | |
| 81 | Packet Error Rate Analysis of ZigBee Under WLAN and Bluetooth Interferences. <i>IEEE Transactions on Wireless Communications</i> , 2007 , 6, 2825-2830 | 9.6 | 117 |
| 80 | DCA: Duty-Cycle Adaptation Algorithm for IEEE 802.15.4 Beacon-Enabled Networks. <i>IEEE Vehicular Technology Conference</i> , 2007 , | 0.1 | 30 |
| 79 | Minimum Variance FIR Smoothers for Continuous-Time State Space Signal Models. <i>IEEE Signal Processing Letters</i> , 2007 , 14, 1024-1027 | 3.2 | 8 |

(2005-2007)

| 78 | A Robust FIR Filter for Linear Discrete-Time StateBpace Signal Models With Uncertainties. <i>IEEE Signal Processing Letters</i> , 2007 , 14, 553-556 | 3.2 | 6 |
|----|---|-----|----|
| 77 | Performance analysis of single Bluetooth piconet in error-prone environments. <i>Journal of Communications and Networks</i> , 2007 , 9, 229-235 | 4.1 | 1 |
| 76 | Minimum Variance FIR Smoothers for Discrete-Time State Space Models. <i>IEEE Signal Processing Letters</i> , 2007 , 14, 557-560 | 3.2 | 30 |
| 75 | Direct Width Control Systems Based on Width Prediction Models in Hot Strip Mill. <i>ISIJ International</i> , 2007 , 47, 105-113 | 1.7 | 8 |
| 74 | Receding horizon control for input-delayed systems 2007, | | 1 |
| 73 | \$L_{2}-E\$ FIR Smoothers for Deterministic Discrete-Time StateBpace Signal Models. <i>IEEE Transactions on Automatic Control</i> , 2007 , 52, 927-932 | 5.9 | 12 |
| 72 | \${cal H}_{infty}\$ Finite Memory Controls for Linear Discrete-Time State-Space Models. <i>IEEE Transactions on Circuits and Systems Part 2: Express Briefs</i> , 2007 , 54, 97-101 | | 40 |
| 71 | Adaptive Channel State Routing for Home Network Systems Using Power Line Communications. <i>IEEE Transactions on Consumer Electronics</i> , 2007 , 53, 1410-1418 | 4.8 | 11 |
| 7º | An Enhanced CSMA-CA Algorithm for IEEE 802.15.4 LR-WPANs. <i>IEEE Communications Letters</i> , 2007 , 11, 461-463 | 3.8 | 38 |
| 69 | ECAP: A Bursty Traffic Adaptation Algorithm for IEEE 802.15.4 Beacon-Enabled Networks. <i>IEEE Vehicular Technology Conference</i> , 2007 , | 0.1 | 8 |
| 68 | Sufficient LMI conditions for H/sub /spl infin// output feedback stabilization of linear discrete-time systems. <i>IEEE Transactions on Automatic Control</i> , 2006 , 51, 675-680 | 5.9 | 65 |
| 67 | Fixed-lag Minimum Variance FIR Smoothers for Continuous-time Systems 2006, | | 2 |
| 66 | RECEDING HORIZON FINITE MEMORY OUTPUT TRACKING CONTROL AND ITS APPLICATION TO INVERTED PENDULUM CONTROL. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2006 , 39, 403-408 | | |
| 65 | Design and implementation of home network control protocol on OSGi for home automation system 2005 , | | 4 |
| 64 | Lecture Notes in Computer Science:Packet Error Rate Analysis of IEEE 802.15.4 Under IEEE 802.11b Interference. <i>Lecture Notes in Computer Science</i> , 2005 , 279-288 | 0.9 | 35 |
| 63 | RECEDING HORIZON NEURAL HICONTROL FOR A CLASS OF NONLINEAR UNKNOWN SYSTEMS. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2005, 38, 960-965 | | |
| 62 | RECEDING HORIZON FINITE MEMORY CONTROLS FOR OUTPUT FEEDBACK CONTROLS OF DISCRETE-TIME STATE SPACE SYSTEMS. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2005 , 38, 17-22 | | 3 |
| 61 | NEW RECURSIVE LEAST SQUARE ALGORITHMS WITHOUT USING THE INITIAL INFORMATION. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2005 , 38, 137-141 | | 2 |

| 60 | Spatial and Temporal Multi-Aggregation for State-Based Sensor Data in Wireless Sensor Networks. <i>Telecommunication Systems</i> , 2004 , 26, 161-179 | 2.3 | 3 |
|---------------|--|-----------------|-----|
| 59 | A nonlinear minimization approach to multiobjective and structured controls for discrete-time systems. <i>International Journal of Robust and Nonlinear Control</i> , 2004 , 14, 1327-1343 | 3.6 | 8 |
| 58 | Receding horizon finite memory controls for output feedback controls of state-space systems. <i>IEEE Transactions on Automatic Control</i> , 2004 , 49, 1905-1915 | 5.9 | 12 |
| 57 | Stabilizing static output feedback receding horizon controls for linear discrete time-invariant systems. <i>International Journal of Control</i> , 2003 , 76, 1437-1445 | 1.5 | |
| 56 | Minimax L2-E2 FIR filters for deterministic continuous-time state space signal models. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2003 , 36, 1029-1034 | | |
| 55 | Response Time Driven Scheduling for Programmable Logic Controllers with Network-Based I/O Systems. <i>Real-Time Systems</i> , 2003 , 25, 67-91 | 1.3 | 2 |
| 54 | Maximum allowable delay bounds of networked control systems. <i>Control Engineering Practice</i> , 2003 , 11, 1301-1313 | 3.9 | 238 |
| 53 | A simple receding horizon control for state delayed systems and its stability criterion. <i>Journal of Process Control</i> , 2003 , 13, 539-551 | 3.9 | 43 |
| 52 | Time-Domain FIR Filters for Stochastic and Deterministic Systems 2003, 45-62 | | |
| 51 | A receding horizon unbiased FIR filter for discrete-time state space models. <i>Automatica</i> , 2002 , 38, 545 | -5 <i>5</i> ;17 | 119 |
| 50 | A new identification approach for FIR models. <i>IEEE Transactions on Circuits and Systems Part 2:</i> Express Briefs, 2002 , 49, 439-446 | | 8 |
| 49 | Quasi-deadbeat minimax filters for deterministic state~space models. <i>IEEE Transactions on Automatic Control</i> , 2002 , 47, 1904-1908 | 5.9 | 28 |
| 48 | DELAY-DEPENDENT ROBUST STABILIZATION OF UNCERTAIN DISCRETE-TIME STATE-DELAYED SYSTEMS. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2002, 35, 261-26 | 56 | 14 |
| 47 | A scheduling method for network-based control systems. <i>IEEE Transactions on Control Systems Technology</i> , 2002 , 10, 318-330 | 4.8 | 122 |
| 46 | Comments on "Optimal solution of the two-stage Kalman estimator. <i>IEEE Transactions on Automatic Control</i> , 2002 , 47, 198-199 | 5.9 | 7 |
| 45 | Receding horizon predictive control for nonlinear time-delay systems with and without input constraints. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2001 , 34, 239- | 244 | 1 |
| 44 | | | |
| 44 | A stabilizing static output feedback receding horizon control for linear discrete time-invariant systems. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2001 , 34, 673-678 | 3 | |

(1997-2001)

| 42 | Robust stabilization of uncertain input-delayed systems using reduction method. <i>Automatica</i> , 2001 , 37, 307-312 | 5.7 | 120 |
|----|--|-----|------|
| 41 | Delay-dependent guaranteed cost control for uncertain state-delayed systems 2001, | | 1 |
| 40 | Delay-dependent robust stabilization of uncertain state-delayed systems. <i>International Journal of Control</i> , 2001 , 74, 1447-1455 | 1.5 | 1049 |
| 39 | Receding-horizon unbiased FIR filters for continuous-time state-space models without a priori initial state information. <i>IEEE Transactions on Automatic Control</i> , 2001 , 46, 766-770 | 5.9 | 33 |
| 38 | Stabilizing receding horizon H/sub /spl infin// controls for linear continuous time-varying systems. <i>IEEE Transactions on Automatic Control</i> , 2001 , 46, 1273-1279 | 5.9 | 16 |
| 37 | On receding horizon controls for time-delay systems. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 2000 , 33, 175-180 | | |
| 36 | Estimation and detection of unknown inputs using optimal FIR filter. <i>Automatica</i> , 2000 , 36, 1481-1488 | 5.7 | 22 |
| 35 | Intervalwise receding horizon H/sub /spl infin// tracking control for discrete linear periodic systems. <i>IEEE Transactions on Automatic Control</i> , 2000 , 45, 747-752 | 5.9 | 14 |
| 34 | On stabilizing receding horizon controls for linear continuous time-invariant systems. <i>IEEE Transactions on Automatic Control</i> , 2000 , 45, 1329-1334 | 5.9 | 24 |
| 33 | A receding horizon Kalman FIR filter for linear continuous-time systems. <i>IEEE Transactions on Automatic Control</i> , 1999 , 44, 2115-2120 | 5.9 | 47 |
| 32 | Robust one-step receding horizon control for constrained systems. <i>International Journal of Robust and Nonlinear Control</i> , 1999 , 9, 381-395 | 3.6 | 19 |
| 31 | A receding horizon Kalman FIR filter for discrete time-invariant systems. <i>IEEE Transactions on Automatic Control</i> , 1999 , 44, 1787-1791 | 5.9 | 126 |
| 30 | On Stability of Constrained Receding Horizon Control with Finite Terminal Weighting Matrix. <i>Automatica</i> , 1998 , 34, 1607-1612 | 5.7 | 119 |
| 29 | Genetic-based fuzzy control for half-car active suspension systems. <i>International Journal of Systems Science</i> , 1998 , 29, 699-710 | 2.3 | 6 |
| 28 | A delay-dependent robust stability criterion for uncertain time-delay systems 1998, | | 1 |
| 27 | A scheduling method for network-based control systems 1998, | | 1 |
| 26 | Delay-Dependent Robust Stabilization of Uncertain Time-Delay Systems. <i>IFAC Postprint Volumes IPPV / International Federation of Automatic Control</i> , 1998 , 31, 619-624 | | |
| 25 | Short-time Fourier analysis via optimal harmonic FIR filters. <i>IEEE Transactions on Signal Processing</i> , 1997 , 45, 1535-1542 | 4.8 | 21 |

| 24 | Autopilot Design for Bank-to-Turn Missiles Using Receding Horizon Predictive Control Scheme. <i>Journal of Guidance, Control, and Dynamics</i> , 1997 , 20, 1248-1254 | 2.1 | 12 |
|----|--|-----|-----|
| 23 | Robust generalised predictive control with terminal output weightings. <i>Journal of Process Control</i> , 1996 , 6, 137-144 | 3.9 | 3 |
| 22 | Bounds in algebraic Riccati and Lyapunov equations: a survey and some new results. <i>International Journal of Control</i> , 1996 , 64, 377-389 | 1.5 | 65 |
| 21 | Fast algorithms for optimal FIR filter and smoother of discrete-time state-space models. <i>Automatica</i> , 1994 , 30, 489-492 | 5.7 | 12 |
| 20 | . IEEE Transactions on Automatic Control, 1994 , 39, 159-162 | 5.9 | 125 |
| 19 | Partition of GPC into a State Observer and a State Feedback Controller 1992 , | | 2 |
| 18 | Recursive solution of generalized predictive control and its equivalence to receding horizon tracking control. <i>Automatica</i> , 1992 , 28, 1235-1238 | 5.7 | 15 |
| 17 | Allowable parameter variations and robustness recovery in LQG regulators. <i>International Journal of Robust and Nonlinear Control</i> , 1991 , 1, 33-42 | 3.6 | 5 |
| 16 | Performance improvement using time delays in multivariable controller design. <i>International Journal of Control</i> , 1990 , 52, 1455-1473 | 1.5 | 29 |
| 15 | Delayed State Feedback Controller for the Stabilization of Ordinary Systems 1989, | | 5 |
| 14 | Receding horizon tracking control as a predictive control and its stability properties. <i>International Journal of Control</i> , 1989 , 50, 1807-1824 | 1.5 | 55 |
| 13 | FIR filters and recursive forms for discrete-time state-space models. <i>Automatica</i> , 1989 , 25, 715-728 | 5.7 | 73 |
| 12 | Genetic-based fuzzy control for automotive active suspensions | | 1 |
| 11 | Stability and a scheduling method for network-based control systems | | 2 |
| 10 | Receding horizon control for linear discrete systems with jump parameters | | 6 |
| 9 | Scheduling algorithm for programmable logic controllers with remote I/Os | | 1 |
| 8 | Improved concept for derivation of velocity profiles for elevator systems | | 2 |
| 7 | Implementation of virtual factory using MMS companion standard | | 2 |

LIST OF PUBLICATIONS

| 6 | Geometric kinematics modeling of omni-directional autonomous mobile robot and its applications | 2 |
|---|---|---|
| 5 | Receding horizon FIR filter with estimated horizon initial state and its application to aircraft engine systems | 1 |
| 4 | Real-time distributed software-in-the-loop simulation for distributed control systems | 1 |
| 3 | Elevator group control with accurate estimation of Hall call waiting times | 3 |
| 2 | An architecture for a network based robot control system | 1 |
| 1 | FPGA-based implementation of Synchronous Petri Nets | 1 |