Li Gen

List of Publications by Year in descending order

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1307594 1372567 20 133 7 10 citations g-index h-index papers 20 20 20 71 docs citations citing authors all docs times ranked

| # | Article | IF | CITATIONS |
|----|---|--------------|-----------|
| 1 | Fault-Tolerant Dynamic Control of a Four-Wheel Redundantly-Actuated Mobile Robot. IEEE Access, 2019, 7, 157909-157921. | 4.2 | 23 |
| 2 | Hybrid Maps Enhanced Localization System for Mobile Manipulator in Harsh Manufacturing Workshop. IEEE Access, 2020, 8, 10782-10795. | 4.2 | 17 |
| 3 | A safe and efficient LIDAR-based navigation system for 4WS4WD mobile manipulators in manufacturing plants. Measurement Science and Technology, 2021, 32, 045203. | 2.6 | 17 |
| 4 | Reliable and Fast Localization in Ambiguous Environments Using Ambiguity Grid Map. Sensors, 2019, 19, 3331. | 3.8 | 15 |
| 5 | Efficient and Reliable LiDAR-Based Global Localization of Mobile Robots Using Multiscale/Resolution Maps. IEEE Transactions on Instrumentation and Measurement, 2021, 70, 1-15. | 4.7 | 12 |
| 6 | Motion planning and tracking control of a four-wheel independently driven steered mobile robot with multiple maneuvering modes. Frontiers of Mechanical Engineering, 2021, 16, 504-527. | 4.3 | 9 |
| 7 | An Improved Observation Model for Monte-Carlo Localization Integrated with Reliable Reflector Prediction. , 2019, , . | | 7 |
| 8 | Efficient re-localization of mobile robot using strategy of finding a missing person. Measurement: Journal of the International Measurement Confederation, 2021, 176, 109212. | 5 . O | 7 |
| 9 | Welding seam recognition and tracking for a novel mobile welding robot based on multi-layer sensing strategy. Measurement Science and Technology, 2022, 33, 055109. | 2.6 | 7 |
| 10 | A Fast Path Planning Method for Mobile Robot Based on Voronoi Diagram and Improved D* Algorithm. , 2019, , . | | 5 |
| 11 | A Novel Extrinsic Calibration Method of Mobile Manipulator Camera and 2D-LiDAR via Arbitrary Trihedron-Based Reconstruction. IEEE Sensors Journal, 2021, 21, 24672-24682. | 4.7 | 4 |
| 12 | Double-sided weld seam detection system for aircraft T-joint welds by using vision sensor. , 2016, , . | | 3 |
| 13 | Excess noise in strip off-axis confocal unstable resonators. Journal of Modern Optics, 2012, 59, 235-240. | 1.3 | 2 |
| 14 | Accurate LiDAR-based Localization in Glass-walled Environment. , 2020, , . | | 2 |
| 15 | Trajectory Tracking of a 4wis4wid Robot Using Adaptive Receding Horizon Control Based on Neurodynamics Optimization*. , 2019 , , . | | 1 |
| 16 | Graph-based Extrinsic Calibration of Multiple 2D-Lidars. , 2021, , . | | 1 |
| 17 | Fast and Reliable Global Localization Using Reflector Landmarks. , 2020, , . | | 1 |
| 18 | Numerical simulation of a laser resonator with an in-phase doughnut-like output beam. Journal of Modern Optics, 2009, 56, 1804-1811. | 1.3 | 0 |

| ą | # | Article | IF | CITATIONS |
|---|----|---|----|-----------|
| | 19 | High-precision measurement of defocus amount for laser welding by analyzing image definition. , 2016, | | 0 |
| 2 | 20 | An Efficient and Robust Approach to Solve the Kidnapped Robot Problem Considering Time Variation. , 2020, , . | | 0 |