

# Jacques Kaiser

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/1191000/publications.pdf>

Version: 2024-02-01

11  
papers

207  
citations

1307594

7  
h-index

1720034

7  
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11  
all docs

11  
docs citations

11  
times ranked

218  
citing authors

| #  | ARTICLE   | IF  | CITATIONS |
|----|---|-----|-----------|
| 1  | Soft-Grasping With an Anthropomorphic Robotic Hand Using Spiking Neurons. IEEE Robotics and Automation Letters, 2021, 6, 2894-2901.   | 5.1 | 11        |
| 2  | Embodied Neuromorphic Vision with Continuous Random Backpropagation. , 2020, , .  |     | 5         |
| 3  | Combining Motor Primitives for Perception Driven Target Reaching With Spiking Neurons. International Journal of Cognitive Informatics and Natural Intelligence, 2019, 13, 1-12. | 0.4 | 8         |
| 4  | Generating Pointing Motions for a Humanoid Robot by Combining Motor Primitives. Frontiers in Neurobotics, 2019, 13, 77.   | 2.8 | 13        |
| 5  | The Neurobotics Platform for Teaching “ Embodiment Experiments with Spiking Neural Networks and Virtual Robots. , 2019, , .   |     | 1         |
| 6  | Controlling a Robot Arm for Target Reaching without Planning Using Spiking Neurons. , 2018, , .   |     | 13        |
| 7  | Microsaccades for Neuromorphic Stereo Vision. Lecture Notes in Computer Science, 2018, , 244-252.   | 1.3 | 9         |
| 8  | Multi-Modal Motion Activation for Robot Control Using Spiking Neurons. , 2018, , .  |     | 5         |
| 9  | Scaling up liquid state machines to predict over address events from dynamic vision sensors. Bioinspiration and Biomimetics, 2017, 12, 055001.                                  | 2.9 | 19        |
| 10 | Towards Grasping with Spiking Neural Networks for Anthropomorphic Robot Hands. Lecture Notes in Computer Science, 2017, , 43-51.  | 1.3 | 21        |
| 11 | Connecting Artificial Brains to Robots in a Comprehensive Simulation Framework: The Neurobotics Platform. Frontiers in Neurobotics, 2017, 11, 2.                                | 2.8 | 102       |