

# Wang Yu

## List of Publications by Year in descending order

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2682335

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#	ARTICLE	IF	CITATIONS
1	Quantized feedback particle filter for unmanned aerial vehicles tracking with quantized measurements. Proceedings of the Institution of Mechanical Engineers, Part G: Journal of Aerospace Engineering, 2021, 235, 257-270.	0.7	1
2	Event-based distributed bias compensation pseudomeasurement information filter for 3D bearing-only target tracking. Aerospace Science and Technology, 2021, 117, 106956.	2.5	9
3	Hybrid consensus-based distributed pseudomeasurement information filter for small UAVs tracking in wireless sensor network. IET Radar, Sonar and Navigation, 2020, 14, 556-563.	0.9	5