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List of Publications by Year in Descending Order

139 papers	7,251 citations	41 h-index	83 g-index
161 ext. papers	9,232 ext. citations	4.6 avg, IF	5.91 L-index

#	Paper	IF	Citations
139	Optimal Tracking Control of Uncertain Systems **2016**, 165-186		3
138	Neural Networks in Feedback Control Systems **2015**, 1-52		3
137	Stochastic Optimal Design for Unknown Linear Discrete-Time System Zero-Sum Games in Input-Output form Under Communication Constraints. *Asian Journal of Control*, **2014**, 16, 1263-1276	1.7	8
136	A novel actor-critic-identifier architecture for approximate optimal control of uncertain nonlinear systems. *Automatica*, **2013**, 49, 82-92	5.7	283
135	Stochastic optimal control of unknown linear networked control system in the presence of random delays and packet losses. *Automatica*, **2012**, 48, 1017-1030	5.7	129
134	Online solution of nonlinear two-player zero-sum games using synchronous policy iteration. *International Journal of Robust and Nonlinear Control*, **2012**, 22, 1460-1483	3.6	106
133	Online solution of nonlinear two-player zero-sum games using synchronous policy iteration **2010**,		16
132	Optimal adaptive control for unknown systems using output feedback by reinforcement learning methods **2010**,		11
131	. *IEEE Transactions on Industrial Electronics*, **2010**, 57, 784-792	8.9	48
130	Adaptive optimal control for continuous-time linear systems based on policy iteration. *Automatica*, **2009**, 45, 477-484	5.7	444
129	Discrete adaptive neural network disturbance feedforward compensation for non-linear disturbances in servo-control applications. *International Journal of Control*, **2009**, 82, 721-740	1.5	9
128	Feedforward control based on neural networks for disturbance rejection in hard disk drives. *IET Control Theory and Applications*, **2009**, 3, 411-418	2.5	10
127	ROBUST NEURAL NETWORK CONTROL OF RIGID LINK FLEXIBLE-JOINT ROBOTS. *Asian Journal of Control*, **2008**, 1, 188-197	1.7	10
126	NONLINEAR NETWORK STRUCTURES FOR FEEDBACK CONTROL. *Asian Journal of Control*, **2008**, 1, 205-228	1.7	86
125	Robust Adaptive Control of Robots Using Neural Network: Global Stability. *Asian Journal of Control*, **2008**, 3, 111-121	1.7	9
124	Discrete-time nonlinear HJB solution using approximate dynamic programming: convergence proof. *IEEE Transactions on Systems, Man, and Cybernetics*, **2008**, 38, 943-9		592
123	Adaptive optimal control algorithm for continuous-time nonlinear systems based on policy iteration **2008**,		26

122	Neurodynamic Programming and Zero-Sum Games for Constrained Control Systems. *IEEE Transactions on Neural Networks*, **2008**, 19, 1243-1252		117
121	Matrix-based scheduling and control of a mobile sensor network. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **2008**, 41, 10415-10420		1
120	Policy iteration for continuous-time systems with unknown internal dynamics **2007**,		9
119	Matrix-based discrete event control of automated material handling systems **2006**,		1
118	Controller for swing-up and balance of single inverted pendulum using SDRE-based solution **2005**,		5
117	Control of a MEMS optical switch **2004**,		21
116	Hamilton-Jacobi-Isaacs formulation for constrained input nonlinear systems **2004**,		9
115	Platoon-stable adaptive controller design **2004**,		3
114	Neural network frequency control for thermal power systems **2004**,		3
113	Two-time scale fuzzy logic controller of flexible link robot arm. *Fuzzy Sets and Systems*, **2003**, 139, 125-149	3.7	45
112	Neural-network predictive control for nonlinear dynamic systems with time-delay. *IEEE Transactions on Neural Networks*, **2003**, 14, 377-89		152
111	Design and implementation of industrial neural network controller using backstepping. *IEEE Transactions on Industrial Electronics*, **2003**, 50, 193-201	8.9	48
110	A Hamilton-Jacobi setup for constrained neural network control **2003**,		5
109	Internet-based educational control systems lab using NetMeeting. *IEEE Transactions on Education*, **2002**, 45, 145-151	2.1	48
108	Fuzzy controller for flexible-link robot arm by reduced-order techniques. *IET Control Theory and Applications*, **2002**, 149, 177-187		18
107	Neural-network approximation of piecewise continuous functions: application to friction compensation. *IEEE Transactions on Neural Networks*, **2002**, 13, 745-51		104
106	An implementation of the matrix-based supervisory controller of flexible manufacturing systems. *IEEE Transactions on Control Systems Technology*, **2002**, 10, 709-716	4.8	15
105	Intelligent material handling: development and implementation of a matrix-based discrete-event controller. *IEEE Transactions on Industrial Electronics*, **2001**, 48, 1087-1097	8.9	30

104	Adaptive fuzzy logic control of discrete-time dynamical systems. *Automatica*, **2000**, 36, 229-241	5.7	54
103	Computational complexity of determining resource loops in re-entrant flow lines. *IEEE Transactions on Systems, Man and Cybernetics, Part A: Systems and Humans*, **2000**, 30, 222-229		1
102	Robust backstepping control of nonlinear systems using neural networks. *IEEE Transactions on Systems, Man and Cybernetics, Part A: Systems and Humans*, **2000**, 30, 753-766		270
101	Robust backstepping control of induction motors using neural networks. *IEEE Transactions on Neural Networks*, **2000**, 11, 1178-87		112
100	Active suspension control of ground vehicle based on a full-vehicle model **2000**,		46
99	Optimal design of CMAC neural-network controller for robot manipulators. *IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews*, **2000**, 30, 22-31		127
98	Deadzone compensation in motion control systems using neural networks. *IEEE Transactions on Automatic Control*, **2000**, 45, 602-613	5.9	247
97	Reinforcement adaptive learning neural-net-based friction compensation control for high speed and precision. *IEEE Transactions on Control Systems Technology*, **2000**, 8, 118-126	4.8	62
96	Matrix approach to deadlock-free dispatching in multi-class finite buffer flowlines. *IEEE Transactions on Automatic Control*, **2000**, 45, 2086-2090	5.9	23
95	Backstepping based fuzzy logic control of active vehicle suspension systems **2000**,		9
94	Adaptive critic neural network for feedforward compensation **1999**,		11
93	A note on Kalman filtering. *IEEE Transactions on Education*, **1999**, 42, 225-227	2.1	7
92	Neural network output feedback control of robot manipulators. *IEEE Transactions on Automation Science and Engineering*, **1999**, 15, 301-309		178
91	Deadzone compensation in motion control systems using adaptive fuzzy logic control. *IEEE Transactions on Control Systems Technology*, **1999**, 7, 731-742	4.8	129
90	Deadzone compensation in discrete time using adaptive fuzzy logic. *IEEE Transactions on Fuzzy Systems*, **1999**, 7, 697-707	8.3	30
89	New matrix formulation for supervisory controller design in practical flexible manufacturing system **1999**,		3
88	Hybrid control for a class of underactuated mechanical systems. *IEEE Transactions on Systems, Man and Cybernetics, Part A: Systems and Humans*, **1999**, 29, 649-654		43
87	Feedback Linearization using CMAC Neural Networks. *Automatica*, **1998**, 34, 547-557	5.7	25

86	Control of a nonholonomic mobile robot using neural networks. *IEEE Transactions on Neural Networks*, **1998**, 9, 589-600		428
85	Implementation of a neural network tracking controller for a single flexible link: comparison with PD and PID controllers. *IEEE Transactions on Industrial Electronics*, **1998**, 45, 307-318	8.9	52
84	Robust neural-network control of rigid-link electrically driven robots. *IEEE Transactions on Neural Networks*, **1998**, 9, 581-8		88
83	Direct-reinforcement-adaptive-learning neural network control for nonlinear systems **1997**,		7
82	Teaching Discrete Event Control of Manufacturing Systems. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **1997**, 30, 261-266		
81	A new matrix model for discrete event systems: application to simulation. *IEEE Control Systems*, **1997**, 17, 62-71	2.9	42
80	A framework for hybrid control design. *IEEE Transactions on Systems, Man and Cybernetics, Part A: Systems and Humans*, **1997**, 27, 765-773		25
79	Neural Network Control of Robot Arms and Nonlinear Systems **1997**, 161-211		13
78	CMAC neural networks for control of nonlinear dynamical systems: Structure, stability and passivity. *Automatica*, **1997**, 33, 635-641	5.7	53
77	Neural network control of robot manipulators. *IEEE Intelligent Systems*, **1996**, 11, 64-75		60
76	. *IEEE Transactions on Automatic Control*, **1996**, 41, 1693-1699	5.9	88
75	Multilayer neural-net robot controller with guaranteed tracking performance. *IEEE Transactions on Neural Networks*, **1996**, 7, 388-99		689
74	Multilayer discrete-time neural-net controller with guaranteed performance. *IEEE Transactions on Neural Networks*, **1996**, 7, 107-30		110
73	Approximation-Based Neural Network and Fuzzy Logic Control. *IFAC Postprint Volumes IPPV / International Federation of Automatic Control*, **1996**, 29, 5274-5279		3
72	Towards a paradigm for fuzzy logic control. *Automatica*, **1996**, 32, 167-181	5.7	54
71	Robust implicit self-tuning regulator: Convergence and stability. *Automatica*, **1996**, 32, 1629-1644	5.7	12
70	Identification of nonlinear dynamical systems using multilayered neural networks. *Automatica*, **1996**, 32, 1707-1712	5.7	87
69	Flow-shop scheduling design in an FMS matrix framework. *Control Engineering Practice*, **1995**, 3, 561-568	3.9	7

68	Neural net robot controller with guaranteed tracking performance. *IEEE Transactions on Neural Networks*, **1995**, 6, 703-15		383
67	Techniques in 2-D Implicit Systems. *Control and Dynamic Systems*, **1995**, 69, 89-131		4
66	Feedback linearization using neural networks. *Automatica*, **1995**, 31, 1659-1664	5.7	276
65	Hybrid Feedback Linearization/Fuzzy Logic Control of a Flexible Link Manipulator. *Journal of Intelligent and Fuzzy Systems*, **1994**, 2, 325-336	1.6	7
64	. *IEEE Transactions on Automatic Control*, **1993**, 38, 1115-1120	5.9	13
63	Dynamic Equations of a Manipulator With Rigid and Flexible Links: Derivation and Symbolic Computation **1993**,		6
62	. *IEEE Transactions on Automatic Control*, **1992**, 37, 1509-1514	5.9	13
61	. *IEEE Transactions on Automatic Control*, **1992**, 37, 1431-1436	5.9	2
60	. *IEEE Transactions on Automatic Control*, **1992**, 37, 1425-1431	5.9	3
59	A review of 2-D implicit systems. *Automatica*, **1992**, 28, 345-354	5.7	51
58	A tutorial on the geometric analysis of linear time-invariant implicit systems. *Automatica*, **1992**, 28, 119-137	5.7	102
57	Robust eigenvalue assignment for generalized systems. *Automatica*, **1992**, 28, 1223-1228	5.7	16
56	A geometric approach to proportional-plus-derivative feedback using quotient and partitioned subspaces. *Automatica*, **1991**, 27, 349-369	5.7	9
55	. *IEEE Transactions on Automatic Control*, **1991**, 36, 1111-1116	5.9	33
54	Geometric design techniques for observers in singular systems. *Automatica*, **1990**, 26, 411-415	5.7	46
53	**1990**,		2
52	. *IEEE Transactions on Automatic Control*, **1990**, 35, 506-511	5.9	28
51	. *IEEE Transactions on Automatic Control*, **1990**, 35, 1156-1160	5.9	40

50	*. IEEE Transactions on Automatic Control*, **1990**, 35, 1140-1144	5.9	11
49	*. IEEE Transactions on Automatic Control*, **1989**, 34, 1007-1012	5.9	11
48	*. IEEE Transactions on Automatic Control*, **1989**, 34, 450-455	5.9	40
47	Hamilton-Jacobi-Bellman optimal design of CMAC neural network controller for robot manipulators		1
46	Matrix approach to deadlock avoidance of dispatching in multi-class finite buffer reentrant flow lines		5
45	Neural network approximation of piecewise continuous functions: application to friction compensation		7
44	Direct-reinforcement-adaptive-learning fuzzy logic control for a class of nonlinear systems		2
43	Deadzone compensation in motion control systems using adaptive fuzzy logic control		2
42	Analysis of deadlocks and circular waits using a matrix model for discrete event systems		1
41	Neural network H/sub /spl infin// state feedback control with actuator saturation: the nonlinear benchmark problem		3
40	Robotic deployment for environmental sampling applications		4
39	Matrix Computational Framework for Discrete Event Control of Wireless Sensor Networks with Some Mobile Agents		1
38	Open vs. Closed-Loop Control of the MEMS Electrostatic Comb Drive		7
37	Data-Logging and Supervisory Control in Wireless Sensor Networks		2
36	Wireless sensor network for machine condition based maintenance		8
35	Multimodel neural networks identification and failure detection of nonlinear systems		9
34	Nearly optimal HJB solution for constrained input systems using a neural network least-squares approach		10
33	Backlash compensation in discrete time nonlinear systems using dynamic inversion by neural networks		6

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