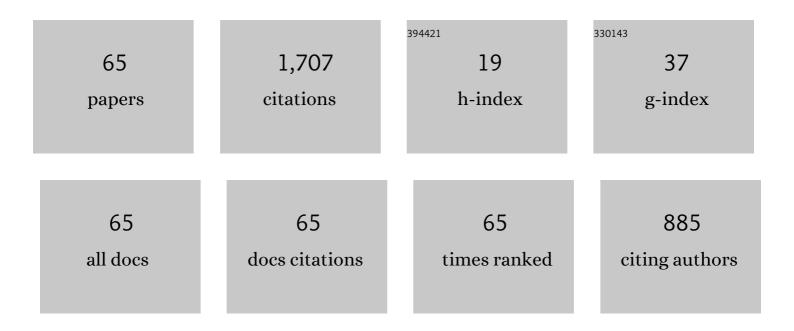


List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/11605214/publications.pdf Version: 2024-02-01



| # | Article | IF | CITATIONS |
|----|-------------------------------------------------------------------------------------------------------------------------------------------------------------------|------|-----------|
| 1 | Feedforward Neural Networks and Compositional Functions with Applications to Dynamical Systems. SIAM Journal on Control and Optimization, 2022, 60, 786-813. | 2.1 | 7 |
| 2 | Defense against Adversarial Swarms with Parameter Uncertainty. Sensors, 2022, 22, 4773. | 3.8 | 6 |
| 3 | Adaptive Deep Learning for High-Dimensional Hamilton-JacobiBellman Equations. SIAM Journal of Scientific Computing, 2021, 43, A1221-A1247. | 2.8 | 39 |
| 4 | Algorithms of data generation for deep learning and feedback design: A survey. Physica D: Nonlinear Phenomena, 2021, 425, 132955. | 2.8 | 8 |
| 5 | Partial Observability Analysis of an Adversarial Swarm Model. Journal of Guidance, Control, and Dynamics, 2020, 43, 250-261. | 2.8 | 7 |
| 6 | A new scalable algorithm for computational optimal control under uncertainty. Journal of Computational Physics, 2020, 420, 109710. | 3.8 | 12 |
| 7 | Consistent numerical methods for state and control constrained trajectory optimisation with parameter dependency. International Journal of Control, 2020, , 1-11. | 1.9 | 2 |
| 8 | A Causality-Free Neural Network Method for High-Dimensional Hamilton-Jacobi-Bellman Equations. , 2020, , . | | 13 |
| 9 | Optimization based resource and cooling management for a high performance computing data center. ISA Transactions, 2019, 90, 202-212. | 5.7 | 7 |
| 10 | Relationships Between Maneuver Time and Energy for Reaction Wheel Attitude Control. Journal of Guidance, Control, and Dynamics, 2018, 41, 335-348. | 2.8 | 13 |
| 11 | Robust Control of a Flexible Double Gimbal Mechanism. , 2018, , . | | 1 |
| 12 | Observability Analysis of an Adversarial Swarmâ \in $^{ m Ms}$ Cooperation Strategy. , 2018, , . | | 1 |
| 13 | Optimal motion planning in rapidâ€fire combat situations with attacker uncertainty. Naval Research Logistics, 2018, 65, 101-119. | 2.2 | 6 |
| 14 | Thermal-Aware Energy Management of an HPC Data Center via Two-Time-Scale Control. IEEE Transactions on Industrial Informatics, 2017, 13, 2260-2269. | 11.3 | 44 |
| 15 | Aerodynamic Three-Axis Attitude Stabilization of a Spacecraft by Center-of-Mass Shifting. Journal of Guidance, Control, and Dynamics, 2017, 40, 1613-1626. | 2.8 | 24 |
| 16 | A Numerical Algorithm for Optimal Control of Systems with Parameter Uncertainty. IFAC-PapersOnLine, 2016, 49, 468-475. | 0.9 | 10 |
| 17 | Spectral and Pseudospectral Optimal Control Over Arbitrary Grids. Journal of Optimization Theory and Applications, 2016, 169, 759-783. | 1.5 | 16 |
| | | | |

18 Unscented guidance for waypoint navigation of a fixed-wing UAV. , 2016, , .

QI GONG

| # | Article | IF | CITATIONS |
|----|-------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|-----------|
| 19 | QoS-Driven Power Management of Data Centers via Model Predictive Control. IEEE Transactions on Automation Science and Engineering, 2016, 13, 1557-1566. | 5.2 | 33 |
| 20 | Energy Constrained Shortest-Time Maneuvers For Reaction Wheel Satellites. , 2016, , . | | 2 |
| 21 | Galerkin Optimal Control. Journal of Optimization Theory and Applications, 2016, 169, 825-847. | 1.5 | 6 |
| 22 | Optimal Control of Uncertain Systems Using Sample Average Approximations. SIAM Journal on Control and Optimization, 2016, 54, 1-29. | 2.1 | 38 |
| 23 | Automatic Contour-Based Road Network Design for Optimized Wind Farm Micrositing. IEEE Transactions on Sustainable Energy, 2015, 6, 281-289. | 8.8 | 13 |
| 24 | Riemann–Stieltjes Optimal Control Problems for Uncertain Dynamic Systems. Journal of Guidance, Control, and Dynamics, 2015, 38, 1251-1263. | 2.8 | 30 |
| 25 | Feasibility of the Galerkin optimal control method. , 2014, , . | | 2 |
| 26 | Discontinuous Galerkin optimal control for constrained nonlinear problems. , 2014, , . | | 3 |
| 27 | Consistent approximation of a nonlinear optimal control problem with uncertain parameters. Automatica, 2014, 50, 2987-2997. | 5.0 | 29 |
| 28 | Galerkin optimal control for constrained nonlinear problems. , 2014, , . | | 3 |
| 29 | Automatic Mass Balancing of a Spacecraft Three-Axis Simulator: Analysis and Experimentation. Journal of Guidance, Control, and Dynamics, 2014, 37, 197-206. | 2.8 | 39 |
| 30 | Optimal Motion Planning for Searching for Uncertain Targets. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 8977-8982. | 0.4 | 13 |
| 31 | Sample average approximations in optimal control of uncertain systems. , 2013, , . | | 8 |
| 32 | Consistent approximation of an optimal search problem. , 2012, , . | | 8 |
| 33 | Feedback Control for Formation Flying Maintenance Using State Transition Matrix. Journal of the Astronautical Sciences, 2012, 59, 177-192. | 1.5 | 7 |
| 34 | High-Accuracy Trajectory Optimization for a Trans-Earth Lunar Mission. Journal of Guidance, Control, and Dynamics, 2011, 34, 1219-1227. | 2.8 | 17 |
| 35 | Costate Computation by a Chebyshev Pseudospectral Method. Journal of Guidance, Control, and Dynamics, 2010, 33, 623-628. | 2.8 | 24 |
| 36 | High-Accuracy Moon to Earth Escape Trajectory Optimization. , 2010, , . | | 1 |

QI GONG

| # | Article | IF | CITATIONS |
|----|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|-----------|
| 37 | Necessary conditions for singular arcs for general restricted multi-body problem. , 2010, , . | | 7 |
| 38 | Autonomous Observability of Networked Multisatellite Systems. Journal of Guidance, Control, and Dynamics, 2009, 32, 869-877. | 2.8 | 19 |
| 39 | Pseudospectral Motion Planning for Autonomous Vehicles. Journal of Guidance, Control, and Dynamics, 2009, 32, 1039-1045. | 2.8 | 48 |
| 40 | A Chebyshev pseudospectral method for nonlinear constrained optimal control problems. , 2009, , . | | 23 |
| 41 | Connections between the covector mapping theorem and convergence of pseudospectral methods for optimal control. Computational Optimization and Applications, 2008, 41, 307-335. | 1.6 | 141 |
| 42 | Guess-Free Trajectory Optimization. , 2008, , . | | 15 |
| 43 | Bellman Pseudospectral Method. , 2008, , . | | 12 |
| 44 | Fuel-Optimal Design of Moon-Earth Trajectories Using Legendre Pseudospectral Method. , 2008, , . | | 12 |
| 45 | Triangle Formation Design in Eccentric Orbits Using Pseudospectral Optimal Control. , 2008, , . | | 5 |
| 46 | Optimal Feedback Control: Foundations, Examples, and Experimental Results for a New Approach. Journal of Guidance, Control, and Dynamics, 2008, 31, 307-321. | 2.8 | 78 |
| 47 | Spectral Algorithm for Pseudospectral Methods in Optimal Control. Journal of Guidance, Control, and Dynamics, 2008, 31, 460-471. | 2.8 | 143 |
| 48 | Pseudospectral Optimal Control and Its Convergence Theorems. , 2008, , 109-124. | | 27 |
| 49 | Pseudospectral Optimal Control for Military and Industrial Applications. , 2007, , . | | 43 |
| 50 | A Unified Pseudospectral Framework for Nonlinear Controller and Observer Design. Proceedings of the American Control Conference, 2007, , . | 0.0 | 5 |
| 51 | Low-Thrust, High-Accuracy Trajectory Optimization. Journal of Guidance, Control, and Dynamics, 2007, 30, 921-933. | 2.8 | 66 |
| 52 | Pseudospectral motion planning techniques for autonomous obstacle avoidance. , 2007, , . | | 23 |
| 53 | Global practical tracking of a class of nonlinear systems by output feedback. Automatica, 2007, 43, 184-189. | 5.0 | 154 |
| 54 | A pseudospectral observer for nonlinear systems. Discrete and Continuous Dynamical Systems - Series B, 2007, 8, 589-611. | 0.9 | 6 |

QI GONG

| # | Article | IF | CITATIONS |
|----|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|-----------|
| 55 | Pseudospectral Feedback Control: Foundations, Examples and Experimental Results. , 2006, , . | | 24 |
| 56 | A Pseudospectral Method for the Optimal Control of Constrained Feedback Linearizable Systems. IEEE Transactions on Automatic Control, 2006, 51, 1115-1129. | 5.7 | 219 |
| 57 | On the Pseudospectral Covector Mapping Theorem for Nonlinear Optimal Control. , 2006, , . | | 28 |
| 58 | Practical stabilization through real-time optimal control. , 2006, , . | | 25 |
| 59 | Authors' reply [to comments on 'A remark on partial-state feedback stabilization of cascade systems using small gain theorem'. IEEE Transactions on Automatic Control, 2005, 50, 928-929. | 5.7 | 0 |
| 60 | A note on global output regulation of nonlinear systems in the output feedback form. IEEE Transactions on Automatic Control, 2003, 48, 1049-1054. | 5.7 | 23 |
| 61 | A remark on partial-state feedback stabilization of cascade systems using small gain theorem. IEEE Transactions on Automatic Control, 2003, 48, 497-500. | 5.7 | 53 |
| 62 | Global output regulation of cascade systems by time-varying partial state feedback. , 0, , . | | 0 |
| 63 | Convergence of Pseudospectral Methods for a Class of Discontinuous Optimal Control. , 0, , . | | 7 |
| 64 | Global Practical Output Regulation of a Class of Nonlinear Systems by Output Feedback. , 0, , . | | 2 |
| 65 | A pseudospectral method for the optimal control of constrained feedback linearizable systems. , 0, , . | | 4 |