

# Michael Laskey

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/11420829/publications.pdf>

Version: 2024-02-01

3

papers

57

citations

3

all docs

3

docs citations

3

times ranked

34

citing authors

#	ARTICLE	IF	CITATIONS
1	Comparing human-centric and robot-centric sampling for robot deep learning from demonstrations. , 2017, , .		32
2	SHIV: Reducing supervisor burden in DAgger using support vectors for efficient learning from demonstrations in high dimensional state spaces. , 2016, , .		25
3	Dynamic regret convergence analysis and an adaptive regularization algorithm for on-policy robot imitation learning. International Journal of Robotics Research, 2021, 40, 1284-1305.	8.5	0