

# Martha E Pollack

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/11367508/publications.pdf>

Version: 2024-02-01

13  
papers

1,501  
citations

1040056

9  
h-index

1372567

10  
g-index

14  
all docs

14  
docs citations

14  
times ranked

860  
citing authors

| #  | ARTICLE   | IF  | CITATIONS |
|----|---|-----|-----------|
| 1  | Plans and resource-bounded practical reasoning. <i>Computational Intelligence</i> , 1988, 4, 349-355.   | 3.2 | 755       |
| 2  | Autominder: an intelligent cognitive orthotic system for people with memory impairment. <i>Robotics and Autonomous Systems</i> , 2003, 44, 273-282.                           | 5.1 | 288       |
| 3  | The uses of plans. <i>Artificial Intelligence</i> , 1992, 57, 43-68.  | 5.8 | 106       |
| 4  | CTP: A New Constraint-Based Formalism for Conditional, Temporal Planning. <i>Constraints</i> , 2003, 8, 365-388.  | 0.7 | 74        |
| 5  | Efficient solution techniques for disjunctive temporal reasoning problems. <i>Artificial Intelligence</i> , 2003, 151, 43-89.   | 5.8 | 73        |
| 6  | Using a goal-driven approach to generate test cases for GUIs. , 1999, , .   |     | 66        |
| 7  | Automated test oracles for GUIs. <i>Software Engineering Notes: an Informal Newsletter of the Special Interest Committee on Software Engineering / ACM</i> , 2000, 25, 30-39. | 0.7 | 36        |
| 8  | Adaptive cognitive orthotics. , 2004, , .   |     | 36        |
| 9  | Evaluating new options in the context of existing plans. <i>Artificial Intelligence</i> , 2001, 127, 199-220.   | 5.8 | 33        |
| 10 | Intelligent Assistive Technology: The Present and the Future. <i>Lecture Notes in Computer Science</i> , 2007, , 5-6.   | 1.3 | 13        |
| 11 | On Solving Soft Temporal Constraints Using SAT Techniques. <i>Lecture Notes in Computer Science</i> , 2005, , 607-621.  | 1.3 | 10        |
| 12 | Evaluating user preferences for adaptive reminding. , 2008, , .   |     | 7         |
| 13 | Towards Focused Plan Monitoring: A Technique and an Application to Mobile Robots. <i>Autonomous Robots</i> , 2000, 9, 71-81.  | 4.8 | 4         |