Ja LÃ³pez-Orozco

List of Publications by Year
in descending order

8 papers	**123** citations	1937685 **4** h-index	1720034 **7** g-index
8 all docs	**8** docs citations	**8** times ranked	**125** citing authors

#	Article	IF	Citations
1	Centro de Control de Tierra para ColaboraciÃ³n de VehÃculos AutÃ³nomos Marinos. RIAI - Revista Iberoamericana De Automatica E Informatica Industrial, 2017, 15, 1.	1.0	1
2	Symbolic Regression for Marine Vehicles IdentificationˆˆˆˆThe authors wish to thank the â€œMinisterio de EconomÃ¡Ä±a y Com-petitividadâ€•of Spain for support under projects DPI2013-46665-C2- 1-R and DPI2013-46665-C2-2-R. The authors wish to thank also the National University Distance Education (UNED) for support unde project 2014-012-UNED-PROY.. IFAC-PapersOnLine, 2015, 48, 210-216.	0.9	6
3	Remote Web-based Control Laboratory for Mobile Devices based on EJsS, Raspberry Pi and Node.js**This work has been supported by the Spanish National Research Project DPI2013-46665-C2-1-R.. IFAC-PapersOnLine, 2015, 48, 158-163.	0.9	40
4	Virtual and remote practices for learning control topics with a 3DOF quadrotor. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2013, 46, 78-83.	0.4	6
5	EasyJava Simulations meets TwinCAT: Remote Real-Time Control Experiments using Programmable Logic Controllers. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2012, 45, 294-299.	0.4	3
6	MULTIOBJECTIVE OPTIMIZATION OF DYNAMIC PROCESSES BY EVOLUTIONARY METHODS. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2002, 35, 431-436.	0.4	1
7	A kinetic model for beer production under industrial operational conditions. Mathematics and Computers in Simulation, 1998, 48, 65-74.	4.4	59
8	Unified fusion system based on Bayesian networks for autonomous mobile robots. , 0, , .		7