

# Yuanzheng Gong

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/11255003/publications.pdf>

Version: 2024-02-01

16  
papers

303  
citations

1306789

7  
h-index

1473754

9  
g-index

16  
all docs

16  
docs citations

16  
times ranked

321  
citing authors

| #  | ARTICLE   | IF  | CITATIONS |
|----|---|-----|-----------|
| 1  | Semi-autonomous image-guided brain tumour resection using an integrated robotic system: A benchmark study. <i>International Journal of Medical Robotics and Computer Assisted Surgery</i> , 2018, 14, e1872.      | 1.2 | 19        |
| 2  | Toward real-time quantification of fluorescence molecular probes using target/background ratio for guiding biopsy and endoscopic therapy of esophageal neoplasia. <i>Journal of Medical Imaging</i> , 2017, 4, 1. | 0.8 | 12        |
| 3  | Three-dimensional measurement of small inner surface profiles using feature-based 3-D panoramic registration. <i>Optical Engineering</i> , 2017, 56, 014108.  | 0.5 | 23        |
| 4  | Toward real-time tumor margin identification in image-guided robotic brain tumor resection. <i>Proceedings of SPIE</i> , 2017, 10135, .   | 0.8 | 3         |
| 5  | Feature-Based Three-Dimensional Registration for Repetitive Geometry in Machine Vision. <i>Journal of Information Technology &amp; Software Engineering</i> , 2016, 6, .  | 0.3 | 5         |
| 6  | Toward real-time endoscopically-guided robotic navigation based on a 3D virtual surgical field model. , 2015, 9415, 94150C.   |     | 4         |
| 7  | Path planning for semi-automated simulated robotic neurosurgery. , 2015, 2015, 2639-2645.   |     | 12        |
| 8  | Semi-autonomous simulated brain tumor ablation with RAVENII Surgical Robot using behavior tree. , 2015, 2015, 3868-3875.  |     | 67        |
| 9  | Axial-Stereo 3-D Optical Metrology for Inner Profile of Pipes Using a Scanning Laser Endoscope. <i>International Journal of Optomechatronics</i> , 2015, 9, 238-247.  | 3.3 | 11        |
| 10 | Bound constrained bundle adjustment for reliable 3D reconstruction. <i>Optics Express</i> , 2015, 23, 10771.  | 1.7 | 17        |
| 11 | Accurate three-dimensional virtual reconstruction of surgical field using calibrated trajectories of an image-guided medical robot. <i>Journal of Medical Imaging</i> , 2014, 1, 035002.                          | 0.8 | 13        |
| 12 | Mapping surgical fields by moving a laser-scanning multimodal scope attached to a robot arm. , 2014, 9036, .  |     | 5         |
| 13 | Improving 4-D shape measurement by using projector defocusing. , 2010, , .  |     | 4         |
| 14 | Ultrafast 3-D shape measurement with an off-the-shelf DLP projector. <i>Optics Express</i> , 2010, 18, 19743.   | 1.7 | 106       |
| 15 | Some recent advance on high-speed, high-resolution 3-D shape measurement using projector defocusing. , 2010, , .  |     | 2         |
| 16 | High-Speed, High-Resolution 3D Imaging Using Projector Defocusing. , 0, , 121-140.  |     | 0         |