

Tingshu Hu

List of Publications by Year in Descending Order

Source: <https://exaly.com/author-pdf/11245089/tingshu-hu-publications-by-year.pdf>

Version: 2024-04-26

This document has been generated based on the publications and citations recorded by exaly.com. For the latest version of this publication list, visit the link given above.

The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

54
papers

3,409
citations

24
h-index

58
g-index

85
ext. papers

4,325
ext. citations

4
avg, IF

5.31
L-index

#	Paper	IF	Citations
54	Control design for robust tracking and smooth transition in power systems with battery/supercapacitor hybrid energy storage devices. <i>Journal of Power Sources</i> , 2014 , 267, 566-575	8.9	44
53	A Unified Lyapunov Approach to Analysis of Oscillations and Stability for Systems With Piecewise Linear Elements. <i>IEEE Transactions on Automatic Control</i> , 2010 , 55, 2864-2869	5.9	7
52	Non-conservative matrix inequality conditions for stability/stabilizability of linear differential inclusions. <i>Automatica</i> , 2010 , 46, 190-196	5.7	51
51	Linear discrete-time global and regional anti-windup: an LMI approach. <i>International Journal of Control</i> , 2009 , 82, 2179-2192	1.5	11
50	Analysis of oscillation and stability for systems with piecewise linear components via saturation functions 2009 ,		5
49	Piecewise-quadratic Lyapunov functions for systems with deadzones or saturations. <i>Systems and Control Letters</i> , 2009 , 58, 365-371	2.4	59
48	Set invariance and performance analysis of linear systems via truncated ellipsoids. <i>Automatica</i> , 2009 , 45, 2046-2051	5.7	15
47	Output feedback design for saturated linear plants using deadzone loops. <i>Automatica</i> , 2009 , 45, 2917-2924	5.7	43
46	Stabilization of Switched Systems via Composite Quadratic Functions. <i>IEEE Transactions on Automatic Control</i> , 2008 , 53, 2571-2585	5.9	86
45	Polyhedral functions, composite quadratic functions, and equivalent conditions for stability/stabilization 2008 ,		2
44	Nonlinear feedback laws for practical stabilization of systems with input and state constraints 2008 ,		5
43	Anti-windup synthesis for linear control systems with input saturation: Achieving regional, nonlinear performance. <i>Automatica</i> , 2008 , 44, 512-519	5.7	140
42	Nonlinear control design for linear differential inclusions via convex hull of quadratics. <i>Automatica</i> , 2007 , 43, 685-692	5.7	67
41	Switching Law Construction for Discrete-Time Systems Via Composite Quadratic Functions. <i>Proceedings of the American Control Conference</i> , 2007 ,	1.2	1
40	Analysis of systems with saturation/deadzone via piecewise-quadratic Lyapunov functions. <i>Proceedings of the American Control Conference</i> , 2007 ,	1.2	3
39	On Several Composite Quadratic Lyapunov Functions for Switched Systems 2006 ,		13
38	Conjugate convex Lyapunov functions for dual linear differential inclusions. <i>IEEE Transactions on Automatic Control</i> , 2006 , 51, 661-666	5.9	58

37	Stability and Performance for Saturated Systems via Quadratic and Nonquadratic Lyapunov Functions. <i>IEEE Transactions on Automatic Control</i> , 2006 , 51, 1770-1786	5.9	173
36	Control of saturated linear plants via output feedback containing an internal deadzone loop 2006 ,		7
35	Dual Matrix Inequalities in Stability and Performance Analysis of Linear Differential/Difference Inclusions 2006 , 103-122		22
34	Constrained Control Design for Magnetic Bearing Systems. <i>Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME</i> , 2005 , 127, 601-616	1.6	23
33	Absolute stability analysis of discrete-time systems with composite quadratic Lyapunov functions. <i>IEEE Transactions on Automatic Control</i> , 2005 , 50, 781-797	5.9	40
32	Convex analysis of invariant sets for a class of nonlinear systems. <i>Systems and Control Letters</i> , 2005 , 54, 729-737	2.4	2
31	Conjugate Lyapunov functions for saturated linear systems. <i>Automatica</i> , 2005 , 41, 1949-1956	5.7	36
30	Human gait modeling: dealing with holonomic constraints 2004 ,		1
29	Dissipativity for dual linear differential inclusions through conjugate storage functions 2004 ,		19
28	Reducing power loss in magnetic bearings by optimizing current allocation. <i>IEEE Transactions on Magnetics</i> , 2004 , 40, 1625-1635	2	16
27	Controlled invariance of ellipsoids: linear vs. nonlinear feedback. <i>Systems and Control Letters</i> , 2004 , 53, 203-210	2.4	2
26	Analysis of linear systems in the presence of actuator saturation and L2-disturbances. <i>Automatica</i> , 2004 , 40, 1229-1238	5.7	145
25	Magnetically suspended balance beam with disturbances: A test rig for nonlinear output regulation 2004 ,		1
24	Properties of the composite quadratic Lyapunov functions. <i>IEEE Transactions on Automatic Control</i> , 2004 , 49, 1162-1167	5.9	39
23	Absolute stability with a generalized sector condition. <i>IEEE Transactions on Automatic Control</i> , 2004 , 49, 535-548	5.9	76
22	Output regulation of linear systems with bounded continuous feedback. <i>IEEE Transactions on Automatic Control</i> , 2004 , 49, 1941-1953	5.9	37
21	On the tightness of a recent set invariance condition under actuator saturation. <i>Systems and Control Letters</i> , 2003 , 49, 389-399	2.4	18
20	Composite quadratic Lyapunov functions for constrained control systems. <i>IEEE Transactions on Automatic Control</i> , 2003 , 48, 440-450	5.9	192

19	On maximizing the convergence rate for linear systems with input saturation. <i>IEEE Transactions on Automatic Control</i> , 2003 , 48, 1249-1253	5.9	23
18	Analysis and design for discrete-time linear systems subject to actuator saturation. <i>Systems and Control Letters</i> , 2002 , 45, 97-112	2.4	308
17	An explicit description of null controllable regions of linear systems with saturating actuators. <i>Systems and Control Letters</i> , 2002 , 47, 65-78	2.4	56
16	Output regulation of general discrete-time linear systems with saturation nonlinearities. <i>International Journal of Robust and Nonlinear Control</i> , 2002 , 12, 1129-1143	3.6	3
15	An analysis and design method for linear systems subject to actuator saturation and disturbance. <i>Automatica</i> , 2002 , 38, 351-359	5.7	522
14	Null controllable region of LTI discrete-time systems with input saturation. <i>Automatica</i> , 2002 , 38, 2009-2013	2.4	22
13	On improving the performance with bounded continuous feedback laws. <i>IEEE Transactions on Automatic Control</i> , 2002 , 47, 1570-1575	5.9	17
12	Stability analysis of linear time-delay systems subject to input saturation. <i>IEEE Transactions on Circuits and Systems Part 1: Regular Papers</i> , 2002 , 49, 233-240		148
11	On semiglobal stabilizability of antistable systems by saturated linear feedback. <i>IEEE Transactions on Automatic Control</i> , 2002 , 47, 1193-1198	5.9	18
10	Exact characterization of invariant ellipsoids for single input linear systems subject to actuator saturation. <i>IEEE Transactions on Automatic Control</i> , 2002 , 47, 164-169	5.9	69
9	Semi-global stabilization with guaranteed regional performance of linear systems subject to actuator saturation. <i>Systems and Control Letters</i> , 2001 , 43, 203-210	2.4	33
8	Practical stabilization of exponentially unstable linear systems subject to actuator saturation nonlinearity and disturbance. <i>International Journal of Robust and Nonlinear Control</i> , 2001 , 11, 555-588	3.6	12
7	Control Systems with Actuator Saturation 2001 ,		649
6	Stabilization of exponentially unstable linear systems with saturating actuators. <i>IEEE Transactions on Automatic Control</i> , 2001 , 45, 973-979	5.9	21
5	On enlarging the basin of attraction for linear systems under saturated linear feedback. <i>Systems and Control Letters</i> , 2000 , 40, 59-69	2.4	36
4	Improvement of parametric stability margin under pole assignment. <i>IEEE Transactions on Automatic Control</i> , 1999 , 44, 1938-1942	5.9	3
3	Properties of the composite quadratic Lyapunov functions		1
2	Regional anti-windup compensation for linear systems with input saturation		7

1 Null controllability and stabilization of linear systems subject to asymmetric actuator saturation

2