Archit Krishna Kamath

List of Publications by Year in descending order

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Version: 2024-02-01

2258059 2550090 10 88 3 3 citations g-index h-index papers 10 10 10 52 docs citations times ranked citing authors all docs

| # | Article | IF | CITATIONS |
|----|---|-----|-----------|
| 1 | Finiteâ€time super twisting sliding mode controller based on higherâ€order sliding mode observer for realâ€time trajectory tracking of a quadrotor. IET Control Theory and Applications, 2020, 14, 2359-2371. | 2.1 | 26 |
| 2 | Fast Terminal Sliding Mode Super Twisting Controller For Position And Altitude Tracking of the Quadrotor. , $2019, , .$ | | 21 |
| 3 | An Adaptive Fast Terminal Sliding-Mode Controller With Power Rate Proportional Reaching Law for Quadrotor Position and Altitude Tracking. IEEE Transactions on Systems, Man, and Cybernetics: Systems, 2022, 52, 3612-3625. | 9.3 | 18 |
| 4 | A Disturbance Observer-Based Intelligent Finite-Time Sliding Mode Flight Controller Design for an Autonomous Quadrotor. IEEE Systems Journal, 2022, 16, 1649-1660. | 4.6 | 12 |
| 5 | Vision-based Fractional Order Sliding Mode Control for Autonomous Vehicle Tracking by a Quadrotor UAV. , 2019, , . | | 4 |
| 6 | Vision-based Fast-terminal Sliding Mode Super Twisting Controller for Autonomous Landing of a Quadrotor on a Static Platform. , 2019, , . | | 3 |
| 7 | Vision Augmented 3 DoF Quadrotor Control using a Non-singular Fast-terminal Sliding Mode Modified Super-twisting Controller. , 2021, , . | | 3 |
| 8 | Q-learning Based Navigation of a Quadrotor using Non-singular Terminal Sliding Mode Control. , 2019, , . | | 1 |
| 9 | Real-time Trajectory Tracking of a Quadrotor using Adaptive Backstepping Controller and RNN based Uncertainty Observer. , 2020, , . | | O |
| 10 | Vision-Based Autonomous Control Schemes for Quadrotor Unmanned Aerial Vehicle., 0,,. | | 0 |