## Kenichi Kanatani

## List of Publications by Citations

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26 14 49 745 h-index g-index citations papers 876 4.46 3.3 53 L-index avg, IF ext. citations ext. papers

#	Paper	IF	Citations
49	Hyper least squares fitting of circles and ellipses. <i>Computational Statistics and Data Analysis</i> , <b>2011</b> , 55, 2197-2208	1.6	85
48	Geometric Information Criterion for Model Selection. <i>International Journal of Computer Vision</i> , <b>1998</b> , 26, 171-189	10.6	62
47	Statistical Optimization for Geometric Fitting: Theoretical Accuracy Bound and High Order Error Analysis. <i>International Journal of Computer Vision</i> , <b>2008</b> , 80, 167-188	10.6	62
46	Geometric Structure of Degeneracy for Multi-body Motion Segmentation. <i>Lecture Notes in Computer Science</i> , <b>2004</b> , 13-25	0.9	47
45	Uncertainty modeling and model selection for geometric inference. <i>IEEE Transactions on Pattern Analysis and Machine Intelligence</i> , <b>2004</b> , 26, 1307-19	13.3	45
44	Computational projective geometry. CVGIP Image Understanding, 1991, 54, 333-348		41
43	Cramer <b>R</b> ao Lower Bounds for Curve Fitting. <i>Graphical Models</i> , <b>1998</b> , 60, 93-99		37
42	3-D interpretation of optical flow by renormalization. <i>International Journal of Computer Vision</i> , <b>1993</b> , 11, 267-282	10.6	37
41	MOTION SEGMENTATION BY SUBSPACE SEPARATION: MODEL SELECTION AND RELIABILITY EVALUATION. International Journal of Image and Graphics, <b>2002</b> , 02, 179-197	0.5	33
40	Unified Computation of Strict Maximum Likelihood for Geometric Fitting. <i>Journal of Mathematical Imaging and Vision</i> , <b>2010</b> , 38, 1-13	1.6	28
39	Calibration of ultrawide fisheye lens cameras by eigenvalue minimization. <i>IEEE Transactions on Pattern Analysis and Machine Intelligence</i> , <b>2013</b> , 35, 813-22	13.3	26
38	Performance evaluation of iterative geometric fitting algorithms. <i>Computational Statistics and Data Analysis</i> , <b>2007</b> , 52, 1208-1222	1.6	26
37	Improved algebraic methods for circle fitting. <i>Electronic Journal of Statistics</i> , <b>2009</b> , 3,	1.2	21
36	Uncertainty Modeling for Optimal Structure from Motion. Lecture Notes in Computer Science, 2000, 200	-2:13	16
35	Stabilizing the Focal Length Computation for 3-D Reconstruction from Two Uncalibrated Views. <i>International Journal of Computer Vision</i> , <b>2006</b> , 66, 109-122	10.6	14
34	HyperLS for Parameter Estimation in Geometric Fitting. <i>IPSJ Transactions on Computer Vision and Applications</i> , <b>2011</b> , 3, 80-94	3.3	12
33	Guide to 3D Vision Computation. Advances in Computer Vision and Pattern Recognition, 2016,	1.1	12

Compact algorithm for strictly ML ellipse fitting 2008, 32 11 Ellipse Fitting for Computer Vision: Implementation and Applications. Synthesis Lectures on 11 Computer Vision, **2016**, 6, 1-141 Renormalization Returns: Hyper-renormalization and Its Applications. Lecture Notes in Computer 0.9 30 10 Science, 2012, 384-397 Reconstruction of consistent shape from inconsistent data: Optimization of (2{raise0.5exhbox{\$scriptstyle 1\$}kern-0.1em/kern-0.15emlower0.25exhbox{\$scriptstyle 2\$}})D 10.6 29 9 sketches. International Journal of Computer Vision, 1989, 3, 261-292 Calibration of a Moving Camera Using a Planar Pattern: Optimal Computation, Reliability 28 0.9 9 Evaluation, and Stabilization by Model Selection, Lecture Notes in Computer Science, 2000, 595-609 Statistical optimization and geometric inference in computer vision. Philosophical Transactions 8 27 Series A, Mathematical, Physical, and Engineering Sciences, 1998, 356, 1303-1320 Hyper-renormalization: Non-minimization Approach for Geometric Estimation. IPSJ Transactions on 26 7 3.3 Computer Vision and Applications, 2014, 6, 143-159 Computing internally constrained motion of 3-D sensor data for motion interpretation. Pattern 25 7.7 Recognition, 2013, 46, 1700-1709 Stabilizing Image Mosaicing by Model Selection. Lecture Notes in Computer Science, 2001, 35-51 24 0.9 7 High Accuracy Ellipse-Specific Fitting. Lecture Notes in Computer Science, 2014, 314-324 6 0.9 Hyperaccurate Correction of Maximum Likelihood for Geometric Estimation. IPSJ Transactions on 6 22 3.3 Computer Vision and Applications, 2013, 5, 19-29 Hypothesizing and testing geometric properties of image data. CVGIP Image Understanding, 1991, 6 21 54, 349-357 Road shape reconstruction by local flatness approximation. Advanced Robotics, 1991, 6, 197-213 20 1.7 5 Interpretation of conic motion and its applications. International Journal of Computer Vision, 1993, 10.6 19 10, 67-84 18 Statistical Optimization for Geometric Estimation: Minimization vs. Non-minimization 2014, 4 LATEST ALGORITHMS FOR 3-D RECONSTRUCTION FROM TWO VIEWS 2009, 201-234 17 16 Hyper Least Squares and Its Applications 2010, 3 Uncertainty Modeling and Geometric Inference 2005, 461-491 15

14	Optimal grid pattern for focal length calibration. Advanced Robotics, 1995, 10, 81-103	1.7	2
13	Optimization without Minimization Search: Constraint Satisfaction by Orthogonal Projection with Applications to Multiview Triangulation. <i>IEICE Transactions on Information and Systems</i> , <b>2010</b> , E93-D, 2836-2845	0.6	2
12	Geometric BIC. IEICE Transactions on Information and Systems, 2010, E93-D, 144-151	0.6	1
11	Ellipse Fitting. Advances in Computer Vision and Pattern Recognition, 2016, 11-32	1.1	1
10	Compact Fundamental Matrix Computation. Lecture Notes in Computer Science, 2009, 179-190	0.9	1
9	Calibration of a moving camera using a planar pattern: Optimal computation, reliability evaluation, and stabilization by the geometric AIC. Electronics and Communications in Japan, Part III: Fundamental Electronic Science (English Translation of Denshi Tsushin Gakkai Ronbunshi), 2001, 84, 12-21		
8	Fast display of curves and surfaces with correct topology in all resolutions. <i>Electronics and Communications in Japan, Part III: Fundamental Electronic Science (English Translation of Denshi Tsushin Gakkai Ronbunshi)</i> , <b>2001</b> , 84, 1-11		
7	Statistical Reliability of 3-D Interpretation from Images <b>1993</b> , 149-154		
7 6	Statistical Reliability of 3-D Interpretation from Images <b>1993</b> , 149-154  Accuracy of Geometric Estimation. <i>Advances in Computer Vision and Pattern Recognition</i> , <b>2016</b> , 213-229	1.1	
		1.1	
6	Accuracy of Geometric Estimation. <i>Advances in Computer Vision and Pattern Recognition</i> , <b>2016</b> , 213-229  Maximum Likelihood of Geometric Estimation. <i>Advances in Computer Vision and Pattern Recognition</i> ,		
6	Accuracy of Geometric Estimation. <i>Advances in Computer Vision and Pattern Recognition</i> , <b>2016</b> , 213-229  Maximum Likelihood of Geometric Estimation. <i>Advances in Computer Vision and Pattern Recognition</i> , <b>2016</b> , 231-242	1.1	
6 5 4	Accuracy of Geometric Estimation. <i>Advances in Computer Vision and Pattern Recognition</i> , <b>2016</b> , 213-229  Maximum Likelihood of Geometric Estimation. <i>Advances in Computer Vision and Pattern Recognition</i> , <b>2016</b> , 231-242  Theoretical Accuracy Limit. <i>Advances in Computer Vision and Pattern Recognition</i> , <b>2016</b> , 243-254  Optimization Techniques for Geometric Estimation: Beyond Minimization. <i>Lecture Notes in</i>	1.1	