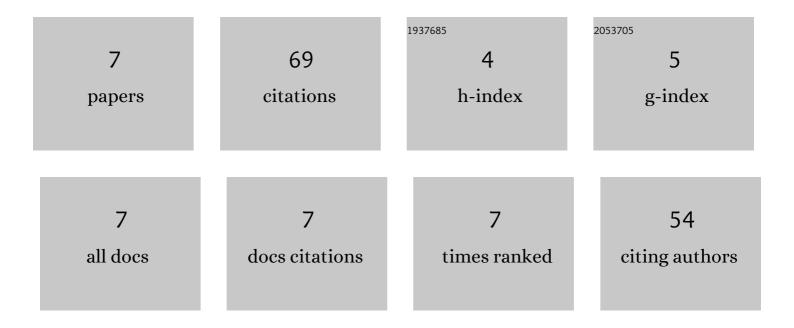
Johan Dahlin

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/11088740/publications.pdf Version: 2024-02-01



#	Article	IF	CITATIONS
1	Sequential Monte Carlo Methods for System Identification**This work was supported by the projects Learning of complex dynamical systems (Contract number: 637-2014-466) and Probabilistic modeling of dynamical systems (Contract number: 621-2013-5524), both funded by the Swedish Research Council IFAC-PapersOnLine, 2015, 48, 775-786.	0.9	28
2	Particle Metropolis–Hastings using gradient and Hessian information. Statistics and Computing, 2015, 25, 81-92.	1.5	22
3	A graph/particle-based method for experiment design in nonlinear systems. IFAC Postprint Volumes IPPV / International Federation of Automatic Control, 2014, 47, 1404-1409.	0.4	6
4	Quasi-Newton particle Metropolis-Hastings**E-mail address to corresponding author: johan.dahlin@liu.se. This work was supported by: Learning of complex dynamical systems (Contract) Tj ETQq0 0 (CADICS, a Linnaeus Center, all funded by the Swedish Research Council IFAC-PapersOnLine, 2015, 48,	0 rgBT /Ov 0.9	erlock 10 Tf
5	981-986. On robust input design for nonlinear dynamical models. Automatica, 2017, 77, 268-278.	5.0	4
6	Backward sequential Monte Carlo for marginal smoothing. , 2014, , .		3
7	Constructing Metropolis-Hastings proposals using damped BFGS updates. IFAC-PapersOnLine, 2018, 51, 664-669.	0.9	Ο