

Roya Sabbagh Novin

List of Publications by Year in descending order

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2682572
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docs citations

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#	ARTICLE	IF	CITATIONS
1	Optimal motion planning of redundant planar serial robots using a synergy-based approach of convex optimization, disjunctive programming and receding horizon. Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering, 2016, 230, 211-221.	1.0	4
2	Optimal motion planning for parallel robots via convex optimization and receding horizon. Advanced Robotics, 2016, 30, 1145-1163.	1.8	3