

Moslem Kazemi

List of Publications by Year in descending order

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Version: 2024-02-01

8
papers

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citations

2258059

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2550090

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g-index

8
all docs

8
docs citations

8
times ranked

315
citing authors

#	ARTICLE	IF	CITATIONS
1	Perceiving, learning, and exploiting object affordances for autonomous pile manipulation. Autonomous Robots, 2014, 37, 369-382.	4.8	51
2	Human-inspired force compliant grasping primitives. Autonomous Robots, 2014, 37, 209-225.	4.8	30
3	Randomized Kinodynamic Planning for Robust Visual Servoing. IEEE Transactions on Robotics, 2013, 29, 1197-1211.	10.3	60
4	Clearing a pile of unknown objects using interactive perception. , 2013, , .		21
5	An integrated system for autonomous robotics manipulation. , 2012, , .		73
6	Path planning for image-based control of wheeled mobile manipulators. , 2012, , .		14
7	Robust Object Grasping using Force Compliant Motion Primitives. , 0, , .		23
8	Perceiving, Learning, and Exploiting Object Affordances for Autonomous Pile Manipulation. , 0, , .		21