

# Nikolas Trawny

## List of Publications by Year in descending order

Source: <https://exaly.com/author-pdf/10916184/publications.pdf>

Version: 2024-02-01

13

papers

577

citations

1937685

4

h-index

2272923

4

g-index

13

all docs

13

docs citations

13

times ranked

507

citing authors

#	ARTICLE	IF	CITATIONS
1	Vision-Aided Inertial Navigation for Spacecraft Entry, Descent, and Landing. <i>IEEE Transactions on Robotics</i> , 2009, 25, 264-280.	10.3	278
2	Observability-based consistent EKF estimators for multi-robot cooperative localization. <i>Autonomous Robots</i> , 2011, 30, 99-122.	4.8	78
3	Interrobot Transformations in 3-D. <i>IEEE Transactions on Robotics</i> , 2010, 26, 226-243.	10.3	51
4	Cooperative multi-robot localization under communication constraints., 2009, , .		50
5	Real-Time Terrain Relative Navigation Test Results from a Relevant Environment for Mars Landing. , 2015, , .		33
6	On the global optimum of planar, range-based robot-to-robot relative pose estimation. , 2010, , .		20
7	Flight testing of terrain-relative navigation and large-divert guidance on a VTVL rocket. , 2015, , .		17
8	A Bank of Maximum &lt;italic&gt;A Posteriori&lt;/italic&gt; (MAP) Estimators for Target Tracking. <i>IEEE Transactions on Robotics</i> , 2015, 31, 85-103.	10.3	15
9	3D relative pose estimation from distance-only measurements. , 2007, , .		9
10	A Terrain Relative Navigation sensor enabled by multi-core processing. , 2012, , .		9
11	A bank of maximum a posteriori estimators for single-sensor range-only target tracking. , 2010, , .		8
12	Bearing-only target tracking using a bank of MAP estimators. , 2011, , .		6
13	GN&amp;C Subsystem Concept for Safe Precision Landing of the Proposed Lunar MARE Robotic Science Mission., 2016, , .		3