

Iyad Hashlamon

List of Publications by Year in descending order

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Version: 2024-02-01

10
papers

71
citations

2682572

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2053705

5
g-index

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all docs

10
docs citations

10
times ranked

57
citing authors

#	ARTICLE	IF	CITATIONS
1	Linear adaptive controllers for robust high speed and acceleration motion control for delta robots. International Journal of Dynamics and Control, 2022, 10, 1567-1593.	2.5	2
2	Real Time Distributed Controller For Delta Robots. WSEAS Transactions on Signal Processing, 2020, 16, 99-107.	0.5	1
3	A novel method for slip prediction of walking biped robots. Robotica, 2017, 35, 766-786.	1.9	4
4	An improved real-time adaptive Kalman filter with recursive noise covariance updating rules. Turkish Journal of Electrical Engineering and Computer Sciences, 2016, 24, 524-540.	1.4	34
5	Joint friction estimation for walking bipeds. Robotica, 2016, 34, 1610-1629.	1.9	1
6	An optimal estimation of feet contact distributed normal reaction forces of walking bipeds. , 2014, , .		0
7	Joint sensor fault detection and recovery based on virtual sensor for walking legged robots. , 2014, , .		9
8	Center of mass states and disturbance estimation for a walking biped. , 2013, , .		14
9	Ground reaction force sensor fault detection and recovery method based on virtual force sensor for walking biped robots. , 2013, , .		3
10	Simple Virtual Slip Force Sensor for walking biped robots. , 2013, , .		3