## Neal Seegmiller

List of Publications by Year in descending order

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1937685 2272923 10 146 4 4 citations g-index h-index papers 10 10 10 126 docs citations times ranked citing authors all docs

#	Article	IF	CITATIONS
1	Vehicle model identification by integrated prediction error minimization. International Journal of Robotics Research, 2013, 32, 912-931.	8.5	40
2	High-Fidelity Yet Fast Dynamic Models of Wheeled Mobile Robots. IEEE Transactions on Robotics, 2016, 32, 614-625.	10.3	34
3	Learning of skid-steered kinematic and dynamic models for motion planning. Robotics and Autonomous Systems, 2017, 95, 207-221.	5.1	23
4	Aiding off-road inertial navigation with high performance models of wheel slip., 2012,,.		16
5	Optical flow odometry with robustness to self-shadowing. , 2011, , .		12
6	Recursive kinematic propagation for wheeled mobile robots. International Journal of Robotics Research, 2015, 34, 288-313.	8.5	9
7	Control of a passively steered rover using 3-D kinematics., 2011,,.		8
8	Online calibration of vehicle powertrain and pose estimation parameters using integrated dynamics. , 2012, , .		4
9	Modeling of wheeled mobile robots as differential-algebraic systems. , 2014, , .		O
10	Control of a passively steered rover using 3-D kinematics. , 2011, , .		O